

National Highway Traffic Safety Administration

DOT HS 807 283 Final Report April 1988

# **Braking Performance of Thirteen Light Trucks**

The United States Government does not endorse products or manufacturers. Trade or manufacturers' names appear only because they are considered essential to the object of this report.

#### Technical Report Documentation Page

1. Report No.  DOT HS 807 283	2. Government Accession	No. 3. R	ecipient's Catalog N	No.
4. Title and Subtitle		5. R	eport Date	
Braking Performance of	Thirteen Light Tru	cks 6. P	April 198. erforming Organizati	
			NRD-22	
	NOTE 15 10 10 10 10 10 10 10 10 10 10 10 10 10	8. P	erforming Organizati	on Report No.
7. Author(s)		ļ		
Mark A. Flick and Richa	rd W Radlinski		VRTC-87-0	000
9. Performing Organization Name and Adda		10 1	Work Unit No. (TRAI	č)
		10.	HOR UNIT NO. (TRAI	3)
National Highway Traffi				
Vehicle Research and Te	st Center	11.	Contract or Grant No	) <b>.</b>
P.O. Box 37				
East Liberty, Ohio 43	310	13.	Type of Report and P	Pariad Cayarad
12. Sponsoring Agency Name and Address	313			
		i	Final Rep	ort
National Highway Traffi	c Safety Administr	ation		
400 7th Street, S.W.				
Washington, D.C. 2059	n	14. 5	Sponsoring Agency C	Code
washington, p.o. 2055				
15. Supplementary Notes				
16. Abstract				
10. Abstract				
A Supplemental Notice	of Proposed Pulama	leine (CNDDM) ha		
A Supplemental Notice	of froposed Rufeman	KING (SNERM) has	s recently be	een issued for
i a braking regularion				
a braking regulation	ror passenger ca	ars (rmv55 15)	Notice 4)	. This report
describes testing of	light trucks (not	currently inclu	ided in the	rulemaking) to
describes testing of	light trucks (not	currently inclu	ided in the	rulemaking) to
describes testing of the proposed FMVSS 135	light trucks (not Notice 4 procedure	currently inclue in order to in	uded in the nonvestigate th	rulemaking) to he feasibility
describes testing of the proposed FMVSS 135 of using the procedu	light trucks (not Notice 4 procedure ce for these vehic	currently incluse in order to in less and to devel	ided in the namestigate the loop a data ba	rulemaking) to he feasibility ase for future
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona	light trucks (not Notice 4 procedure re for these vehic lly, tests were co	currently included in order to in less and to develond to measonducted to meas	ided in the novestigate the loop a data besture the brai	rulemaking) to he feasibility ase for future ke balance and
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity	light trucks (not Notice 4 procedure re for these vehice lly, tests were co heights of the vel	currently inclue in order to in less and to develonducted to measonicles. Thirtee	ided in the novestigate the loop a data baseure the braken vehicles was	rulemaking) to he feasibility ase for future ke balance and were tested to
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity	light trucks (not Notice 4 procedure re for these vehice lly, tests were co heights of the vel	currently inclue in order to in less and to develonducted to measonicles. Thirtee	ided in the novestigate the loop a data baseure the braken vehicles was	rulemaking) to he feasibility ase for future ke balance and were tested to
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity cover the range of size	light trucks (not Notice 4 procedure re for these vehice lly, tests were co heights of the vel and configuration	currently inclue in order to in less and to develonducted to measonicles. Thirtee . The report in	ided in the reception to the second details and the braken vehicles which discuss the second discussion and the second dis	rulemaking) to he feasibility ase for future ke balance and were tested to
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity	light trucks (not Notice 4 procedure re for these vehice lly, tests were co heights of the vel and configuration	currently inclue in order to in less and to develonducted to measonicles. Thirtee . The report in	ided in the reception to the second details and the braken vehicles which discuss the second discussion and the second dis	rulemaking) to he feasibility ase for future ke balance and were tested to
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity cover the range of size	light trucks (not Notice 4 procedure re for these vehice lly, tests were co heights of the vel and configuration	currently inclue in order to in less and to develonducted to measonicles. Thirtee . The report in	ided in the reception to the second details and the braken vehicles which discuss the second discussion and the second dis	rulemaking) to he feasibility ase for future ke balance and were tested to
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity cover the range of size	light trucks (not Notice 4 procedure re for these vehice lly, tests were co heights of the vel and configuration	currently inclue in order to in less and to develonducted to measonicles. Thirtee . The report in	ided in the reception to the second details and the braken vehicles which discuss the second discussion and the second dis	rulemaking) to he feasibility ase for future ke balance and were tested to
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity cover the range of size	light trucks (not Notice 4 procedure re for these vehice lly, tests were co heights of the vel and configuration	currently inclue in order to in less and to develonducted to measonicles. Thirtee . The report in	ided in the reception to the second details and the braken vehicles which discuss the second discussion and the second dis	rulemaking) to he feasibility ase for future ke balance and were tested to
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity cover the range of size	light trucks (not Notice 4 procedure re for these vehice lly, tests were co heights of the vel and configuration	currently inclue in order to in less and to develonducted to measonicles. Thirtee . The report in	ided in the reception to the second details and the braken vehicles which discuss the second discussion and the second dis	rulemaking) to he feasibility ase for future ke balance and were tested to
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity cover the range of size	light trucks (not Notice 4 procedure re for these vehice lly, tests were co heights of the vel and configuration	currently inclue in order to in less and to develonducted to measonicles. Thirtee . The report in	ided in the reception to the second details and the braken vehicles which discuss the second discussion and the second dis	rulemaking) to he feasibility ase for future ke balance and were tested to
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity cover the range of size	light trucks (not Notice 4 procedure re for these vehice lly, tests were co heights of the vel and configuration	currently inclue in order to in less and to develonducted to measonicles. Thirtee . The report in	ided in the reception to the second details and the braken vehicles which discuss the second discussion and the second dis	rulemaking) to he feasibility ase for future ke balance and were tested to
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity cover the range of size	light trucks (not Notice 4 procedure re for these vehice lly, tests were co heights of the vel and configuration	currently inclue in order to in less and to develonducted to measonicles. Thirtee . The report in	ided in the reception to the second details and the braken vehicles which discuss the second discussion and the second dis	rulemaking) to he feasibility ase for future ke balance and were tested to
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity cover the range of size	light trucks (not Notice 4 procedure re for these vehice lly, tests were co heights of the vel and configuration	currently inclue in order to in less and to develonducted to measonicles. Thirtee . The report in	ided in the reception to the second details and the braken vehicles which discuss the second discussion and the second dis	rulemaking) to he feasibility ase for future ke balance and were tested to
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity cover the range of size	light trucks (not Notice 4 procedure re for these vehice lly, tests were co heights of the vel and configuration	currently inclue in order to in less and to develonducted to measonicles. Thirtee . The report in	ided in the reception to the second details and the braken vehicles which discuss the second discussion and the second dis	rulemaking) to he feasibility ase for future ke balance and were tested to
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity cover the range of size	light trucks (not Notice 4 procedure re for these vehice lly, tests were co heights of the vel and configuration	currently inclue in order to in less and to develonducted to measonicles. Thirtee . The report in	ided in the reception to the second details and the braken vehicles which discuss the second discussion and the second dis	rulemaking) to he feasibility ase for future ke balance and were tested to
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity cover the range of size	light trucks (not Notice 4 procedure re for these vehice lly, tests were co heights of the vel and configuration	currently inclue in order to in less and to develonducted to measonicles. Thirtee . The report in	ided in the renvestigate the lop a data basure the braken vehicles was cludes discu	rulemaking) to he feasibility ase for future ke balance and were tested to
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity cover the range of size	light trucks (not Notice 4 procedure re for these vehice lly, tests were co heights of the vel and configuration	currently inclue in order to in less and to develonducted to measonicles. Thirtee . The report in	ided in the renvestigate the lop a data basure the braken vehicles was cludes discu	rulemaking) to he feasibility ase for future ke balance and were tested to
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity cover the range of size	light trucks (not Notice 4 procedure re for these vehice lly, tests were co heights of the vel and configuration	currently inclue in order to in less and to develonducted to measonicles. Thirtee . The report in	ided in the renvestigate the lop a data basure the braken vehicles was cludes discu	rulemaking) to he feasibility ase for future ke balance and were tested to
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity cover the range of size	light trucks (not Notice 4 procedure re for these vehice lly, tests were co heights of the vel and configuration	currently inclue in order to in less and to develonducted to measonicles. Thirtee . The report in	ided in the renvestigate the lop a data basure the braken vehicles was cludes discu	rulemaking) to he feasibility ase for future ke balance and were tested to
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity cover the range of size tests vehicles, test si	light trucks (not Notice 4 procedure for these vehically, tests were content to the end configuration te, test procedures	currently inclue in order to in less and to develonducted to measonicles. Thirtee . The report in	ided in the renvestigate the lop a data basure the braken vehicles was cludes discu	rulemaking) to he feasibility ase for future ke balance and were tested to
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity cover the range of size tests vehicles, test si	light trucks (not Notice 4 procedure for these vehically, tests were content to the end configuration te, test procedures	currently inclue in order to in les and to develonducted to measticles. Thirtee. The report in s and test resul	ided in the movestigate the hop a data basure the braken vehicles which discults.	rulemaking) to he feasibility ase for future ke balance and were tested to ussions of the
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity cover the range of size tests vehicles, test si	light trucks (not Notice 4 procedure for these vehically, tests were content to the end configuration te, test procedures	currently include in order to include and to develonducted to measure the conducted. Thirtee. The report includes and test results and test results.  Distribution Statement includes the conducted to measure the conducted to measure the conducted the cond	ided in the investigate the lop a data basure the braken vehicles which discults.	rulemaking) to he feasibility ase for future ke balance and were tested to ussions of the
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity cover the range of size tests vehicles, test si  17. Key Words Light Trucks Brakes	light trucks (not Notice 4 procedure for these vehically, tests were content to the end configuration te, test procedures	currently include in order to include and to develonducted to measure the conducted. Thirtee. The report includes and test results and test results.  Distribution Statement includes the conducted to measure the conducted to measure the conducted the cond	ided in the movestigate the hop a data basure the braken vehicles which discults.	rulemaking) to he feasibility ase for future ke balance and were tested to ussions of the
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity cover the range of size tests vehicles, test si	light trucks (not Notice 4 procedure for these vehically, tests were content to the end configuration te, test procedures	currently inclue in order to in les and to develonducted to meast hicles. Thirtee. The report in and test results and test result.  Distribution Statement public from the public from the product of the public from the product of the public from the publi	ided in the movestigate the lop a data basure the brailen vehicles which discults.	rulemaking) to he feasibility ase for future ke balance and were tested to ussions of the  to the hal
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity cover the range of size tests vehicles, test si  17. Key Words Light Trucks Brakes	light trucks (not Notice 4 procedure for these vehically, tests were content to the end configuration te, test procedures	currently include in order to include and to develonducted to measure thicles. Thirtee. The report in sand test results and test results and test results and test results are the comment in public from Technical	aded in the representation and the brail and	rulemaking) to he feasibility ase for future ke balance and were tested to ussions of the to the hal Service,
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity cover the range of size tests vehicles, test si  17. Key Words Light Trucks Brakes	light trucks (not Notice 4 procedure for these vehically, tests were content to the end configuration te, test procedures	currently inclue in order to in les and to develonducted to meast hicles. Thirtee. The report in and test results and test result.  Distribution Statement public from the public from the product of the public from the product of the public from the publi	aded in the representation and the brail and	rulemaking) to he feasibility ase for future ke balance and were tested to ussions of the to the hal Service,
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity cover the range of size tests vehicles, test si  17. Key Words Light Trucks Brakes FMVSS 135	light trucks (not Notice 4 procedure for these vehically, tests were conheights of the vehicand configuration te, test procedures	currently include in order to include and to develonducted to measure thicles. Thirteens and test results are test results and test results and test results are test results and test results and test results are test results and test results and test results are test results are test results and test results are test results are test results are test results and test results are test results ar	aded in the representation and the brail and	to the nal Service,
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity cover the range of size tests vehicles, test si  17. Key Words Light Trucks Brakes FMVSS 135	light trucks (not Notice 4 procedure for these vehically, tests were conheights of the vehicand configuration te, test procedures  20. Security Classif. (controlled)	currently inclue in order to in les and to develonducted to meast hicles. Thirtee. The report in s and test results and test results and test results because the comment of this page.	aded in the representation and the brail and	rulemaking) to he feasibility ase for future ke balance and were tested to ussions of the to the hal Service,
describes testing of the proposed FMVSS 135 of using the procedu rulemaking. Additiona the center of gravity cover the range of size tests vehicles, test si  17. Key Words Light Trucks Brakes FMVSS 135	light trucks (not Notice 4 procedure for these vehically, tests were conheights of the vehicand configuration te, test procedures	currently inclue in order to in les and to develonducted to meast hicles. Thirtee. The report in s and test results and test results and test results because the comment of this page.	aded in the representation and the brail and	to the nal Service,

#### TABLE OF CONTENTS

Section		Page
Technical	Documentation Page	i
List of F	igures	iv
List of Ta	ables	v
Technical	Summary	ix
	and the second of the second o	٠
1.0	INTRODUCTION	1
2.0	TEST CONDITIONS	2
	2.1 Test Site	2
	2.2 Test Vehicles	4
	2.3 Instrumentation	7
3.0	TESTS TO THE FMVSS 135 NOTICE 4	11
	3.1 Test Procedure - FMVSS 135 Notice 4 Tests	11
	3.2 Test Results - FMVSS 135 Notice 4 Tests	13
4.0	CENTER OF GRAVITY HEIGHT MEASUREMENT	31
	4.1 Test Procedure - Center of Gravity Heights	37
	4.2 Test Results - Center of Gravity Heights	37
5.0	BRAKE BALANCE MEASUREMENTS	45
	5.1 Test Procedure - Brake Balance Tests	46
	5.2 Test Results - Brake Balance Tests	47
6.0	SUMMARY AND CONCLUSIONS	83
7.0	ACKNOWLEDGMENTS	84
8.0	REFERENCES	84
APPENDIX A	A - Detailed Test Procedure	87
APPENDIX 1	B - Vehicle Information and Summary Data Sheets	113
APPENDIX (	C - Tabular Results FMVSS 135 Notice 4 Tests	158
APPENDIX I	D - RTP Axle Lock Sequence Tests	166
APPENDIX	E - RTP Load Height Tests	185
APPENDIX	F - RTP Tests Composites	192

#### LIST OF FIGURES

Figur	<u>e</u>	Page
1	Aerial View of TRC Facilities	3
2	Close Up View of Road Transducer Plate	5
3	FMVSS 135 Notice 4 Low Coefficient - 50 km/h	14
4	FMVSS 135 Notice 4 Full System - 100 km/h	17
5	FMVSS 135 Notice 4 80% Vmax Tests	19
6	FMVSS 135 Notice 4 Full System - 80% Vmax	19
7	FMVSS 135 Notice 4 Full System - Engine Off	20
8	FMVSS 135 Notice 4 Hydraulic Circuit Failure - Laden	21
9	FMVSS 135 Notice 4 Hydraulic Circuit Failure - Unladen	21
10	FMVSS 135 Notice 4 Failed System - Power Assist Failed	23
11	FMVSS 135 Notice 4 Static Parking Brake	26
12	FMVSS 135 Notice 4 Dynamic Parking Brake - Distance	27
13	FMVSS 135 Notice 4 Dynamic Parking Brake - Deceleration	27
14	FMVSS 135 Notice 4 Hot & Recovery Stops - 100 km/h	29
15	FMVSS 135 Notice 4 Hot/Cold & Recovery/Cold - Ratio	29
16	FMVSS 135 Notice 4 Full System - 100 km/h Post Fade	30
17	FMVSS 135 Notice 4 Tests Light Truck and Passenger Car Comparison Full System Tests	32
18	FMVSS 135 Notice 4 Tests Light Truck and Passenger Car Comparison Full Service Braking - 80% Vmax Tests	33
19	FMVSS 135 Notice 4 Tests Light Truck and Passenger Car Comparison Failed System Tests	34
20	FMVSS 135 Notice 4 Tests Light Truck and Passenger Car Comparison Fade and Recovery Performance Stopping Distance	35
21	FMVSS 135 Notice 4 Tests Light Truck and Passenger Car Comparison Fade and Recovery Performance Ratios	36
22	Vehicle on TPMD	38

# LIST OF FIGURES (Continued)

F:	igur	<u>e</u>	Page
	23		40
	24	Chevrolet S-10 Load Height Comparison	42
	25	S-10 Braking Efficiency	43
	26	Ford Ranger Load Height Comparison	44
	27	Dodge Caravan - Laden Adhesion Utilization and Braking Efficiency	48
	28	Dodge Caravan - Unladen Adhesion Utilization and Braking Efficiency	49
	29	Toyota Van - Laden Adhesion Utilization and Braking Efficiency	51
	30	Toyota Van - Unladen Adhesion Utilization and Braking Efficiency	52
	31	Chevrolet Astro - Laden Adhesion Utilization and Braking Efficiency	53
	32	Chevrolet Astro - Unladen Adhesion Utilization and Braking Efficiency	54
	33	Ford E-250 - Laden Adhesion Utilization and Braking Efficiency	55
	34	Ford E-250 - Unladen Adhesion Utilization and Braking Efficiency	56
	35	Nissan Laden - Single Axle and RTP	58
	36	Nissan Unladen - Single Axle and RTP	59
	37	Chevrolet S-10 - Laden Adhesion Utilization and Braking Efficiency	60
	38	Chevrolet S-10 - Unladen Adhesion Utilization and Braking Efficiency	61
	39	Ford Ranger - Laden Adhesion Utilization and Braking Efficiency	62
	40	Ford Ranger - Unladen Adhesion Utilization and Braking Efficiency	63

# LIST OF FIGURES (Continued)

Figur	<u>e</u>	Page
41	Ford F-150 - Laden Adhesion Utilization and Braking Efficiency	65
42	Ford F-150 - Unladen Adhesion Utilization and Braking Efficiency	66
43	Chevrolet C-1500 - Laden Adhesion Utilization and Braking Efficiency	67
44	Chevrolet C-1500 - Unladen Adhesion Utilization and Brakin Efficiency	g 68
45	Ford F-150 4x4 - Laden Adhesion Utilization and Braking Efficiency	69
46	Ford F-150 4x4 - Unladen Adhesion Utilization and Braking Efficiency	70
47	Dodge Dakota - Laden Adhesion Utilization and Braking Efficiency	72
48	Dodge Dakota - Unladen Adhesion Utilization and Braking Efficiency	73
49	Toyota 4-Runner - Laden Adhesion Utilization and Braking Efficiency	74
50	Toyota 4-Runner - Unladen Adhesion Utilization and Braking Efficiency	75
51	Jeep Cherokee - Laden Adhesion Utilization and Braking Efficiency	76
52	Jeep Cherokee - Unladen Adhesion Utilization and Braking Efficiency	77
53	Light Truck - Laden Single Axle Braking Efficiency	78
54	Cars - Laden Single Axle Braking Efficiency	78
55	Light Trucks - Laden RTP Braking Efficiency	79
56	Light Trucks - Unladen Single Axle Braking Efficiency	80
57	Cars - Unladen Single Axle Braking Efficiency	80
58	Light Trucks - Unladen RTP Braking Efficiency	82

#### LIST OF TABLES

<u>Table</u>		Page
1	Test Vehicles	6
2	FMVSS 135 Notice 4 Test Schedule	12
3	Axle Lock Sequence Results	15
4	Failed Variable Prop and Failed Antilock Results	24
5	Center of Gravity Heights	39

ſ

# Department of Transportation National Highway Traffic Safety Administration

#### TECHNICAL SUMMARY

Report Title

Braking Performance of Thirteen Light Trucks

April 1988

Report Author(s)

Mark A. Flick and Richard W. Radlinski

A Supplemental Notice of Proposed Rulemaking (SNPRM) has recently been issued for a braking regulation for passenger cars (FMVSS 135 Notice 4). This report describes testing of light trucks (not currently included in the rulemaking) to the proposed FMVSS 135 Notice 4 procedure in order to investigate the feasibility of using the procedure for these vehicles and to develop a data base for future rulemaking. Additionally, tests were conducted to measure the brake balance and the center of gravity heights of the vehicles. Thirteen vehicles were tested to cover the range of size and configuration.

In testing the vehicles to the proposed FMVSS 135 Notice 4 test procedure, no problems were found which would suggest the need for a change in the procedure to accommodate light trucks. A comparison of the light trucks and a set of 19 passenger cars tested to the same procedure showed that the difference in average performance was less than 11 percent in all of the test sections.

The brake balance of the light trucks indicate that most would lock their front wheels first when fully loaded. In the unladen condition, a number of the vehcles would be rear brake biased on many surfaces. In both cases, the braking efficiencies were greater than 70 percent.

#### Braking Performance of Thirteen Light Trucks

#### 1.0 INTRODUCTION

The National Highway Traffic and Safety Administration (NHTSA) has recently issued a Supplemental Notice of Proposed Rulemaking (SNPRM) for a braking regulation for passenger cars (FMVSS 135, Notice 4). The purpose of this rulemaking action is to develop an internationally harmonized standard. A more detailed description of the harmonization effort and results of five test programs on versions of proposed harmonized procedures are given in References 1 through 5. While efforts to date have centered on only passenger cars, the next area of interest will probably be light trucks. Additionally, front/rear brake balance, adhesion utilization characteristics, and center of gravity height information are also of interest for light trucks.

In order to investigate the feasibility of using the proposed FMVSS 135 Notice 4 test procedure for light trucks and also to develop a data base for any future rulemaking, 13 light trucks were tested to the Notice 4 procedure. Brake balance and center of gravity heights were also measured on the same set of vehicles. The report which follows describes the tests on these 13 vehicles and the results of these tests. Comparisons of these results to the results for 19 passenger cars tested to the same procedure (discussed in Reference 5) will also be made.

All of the testing was performed at the NHTSA's Vehicle Research and Test Center (VRTC) which is located at the Transportation Research Center (TRC) of Ohio.

Section 2 of the report describes the test conditions. Section 3 gives the results of the tests to the FMVSS 135 Notice 4 procedure. Section 4 of the report describes the center of gravity measurements and Section 5 gives the results of the brake balance tests. A summary and conclusions is given in Section 6.

#### 2.0 TEST CONDITIONS

This section of the report describes the test site, the test vehicles and the instrumentation used for the tests.

#### 2.1 Test Site

All of the tests were conducted at the Transportation Research Center (TRC) of Ohio. Figure 1 is an aerial veiw of the TRC track facilities. The Skid Pad was utilized for most of the testing. Skid Pad is 9,000 feet long overall with a 0.5% slope (from North to South) and has a 309 foot radius loop at each end for vehicle turn around. Length of the 6-lane wide test area is 2,500 feet. different surfaces are available on the Skid Pad. Two of the skid pad surfaces were used for these tests. The surface on which most of the testing was conducted is a concrete surface having a dry ASTM skid number of 80 nominal. The other surface is a polished concrete surface having a wet ASTM skid number of 50 nominal. Both skid numbers were determined with a 15 inch ASTM tire at 40 mph. The dry surface was used for the straight line stopping distance tests and the 50 SN surface was used for axle lockup sequence tests

The 50 acre Vehcile Dynamics Area has a portion of the area coated with Jennite, a driveway sealer. The Jennite was used for low mu stopping distance tests and axle lockup sequence tests. The Jennite area has a wet ASTM skid number of 20 nominal as determined with a 15 inch ASTM tire at 40 mph.

The skid numbers listed represent 100 times the sliding coefficient of friction between the surface and the standard ASTM tire. A peak coefficient of friction or mu value will generally be higher than the skid number and will have a different value for different tires. Past testing has shown that with passenger car tires the peak mu for the 50 SN surface is in the 0.8 to 0.9 range and for the 20 SN surface it is in the 0.4 to 0.6 range.

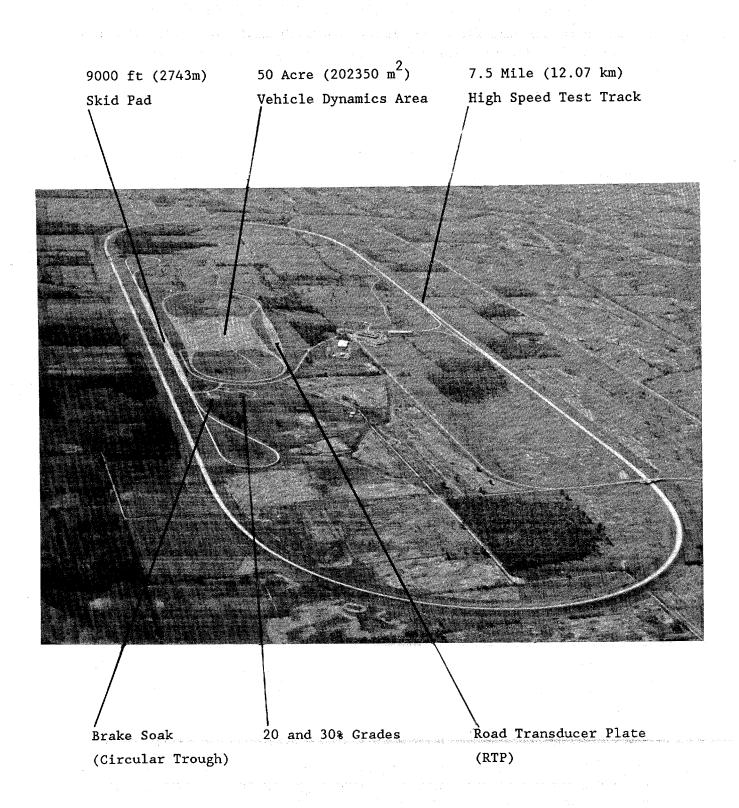


FIGURE 1 -- Aerial View of TRC Facilities

The road transducer plate (RTP) facility was used to measure front/rear brake balance during the axle lockup sequence of the FMVSS 135 Notice 4 procedure and also before and after the brake distribution procedure described in Section 5. A close up view of the facility is shown in Figure 2. The RTP consists of four plates flush with the surface leading up to it. Force transducers attached to the structure of the plates below the surface measure the braking forces as the vehicle passes over the plates. This information is collected and analysed by a computer inside the building. A number of snubs are made at various deceleration levels and at the conclusion of the test, plots showing the percent rear braking versus deceleration and braking efficiency versus peak mu are produced.

The basic design of the RTP facility was supplied by the General Motors Corporation. A complete description of the GM facility can be found in Reference 6. The TRC facility is essentially the same as the GM facility with two notable exceptions of a building over the pads (included at GM and not at TRC) and different computer systems.

The 7-1/2 mile High Speed Track was used for maximum speed determinations, burnishes, and the fade and recovery tests. The static parking brake tests were conducted on the 20% slope of the parking brake hill.

#### 2.2 Test Vehicles

A list of the test vehicles used is given in Table 1. These vehicles were selected to cover the range of loads up to 8500 lb GVWR with different types of brake systems and drive configurations. The Dodge Caravan, the Chevrolet Astro and the 1988 Chevrolet C-1500 were rented from local rental companies or dealerships. The two Toyota vehicles, the Ford E-250, the Nissan Truck, the Chevrolet S-10 and the Jeep Cherokee were borrowed from the manufacturers. The Ford F-150 and the Dodge Dakota were borrowed from other NHTSA programs. Finally, the Ford F-150 4X4 and the Ford Ranger were rented from individuals. In all cases, new brake parts were installed on the

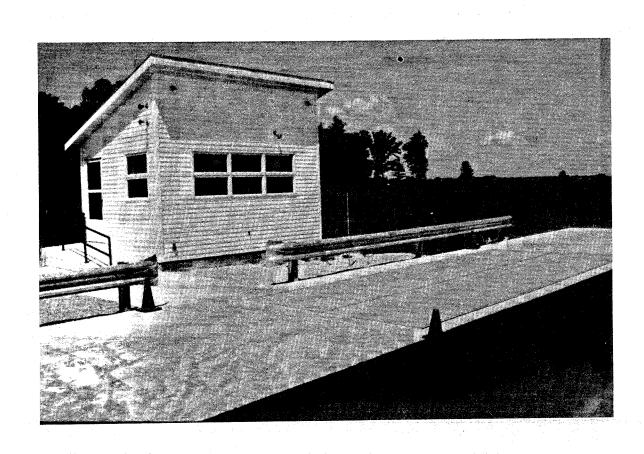


FIGURE 2 -- Close Up View of Road Transducer Plate

TABLE 1 -- Test Vehicles

	Vehicle	Wheelbas	е	Brake	GVWR	
<u>No.</u>	<u>Type</u>	(mm)	<u>Drive</u>	System	<u>(kg)</u>	<u>Vehicle</u>
1	Van	2845	FWD	V.P.	2200	Dodge Caravan
2	Van	2243	RWD	V.P.	2243	Toyota Van
3	Van	3340	RWD	С	2378	Chevrolet Astro
4	Van	3505	RWD	V.P.	3265	Ford E-250
,5	Small Pickup	2949	RWD	V.P.	1996	Nissan Truck
6	Large Pickup	3124	4WD	С	2314	Chevrolet S-10
7	Small Pickup	2743	RWD	С	1763	Ford Ranger
8	Large Pickup	2967	RWD	AL	2177	Ford F-150
9	Large Pickup	3353	RWD	AL	2540	Chevrolet C-1500
10	Large Pickup	3391	4WD	С	2741	Ford F-150 4X4
11	Small Pickup	2845	RWD	V.P.	1865	Dodge Dakota
12	Multipurpose	2624	4WD	V.P.	2304	Toyota 4-Runner
13	Multipurpose	2576	4WD	С	1960	Jeep Cherokee

V.P. = Variable Proportioning, C = Conventional, AL = Antilock

vehicles prior to the FMVSS 135 Notice 4 tests and new parts were again installed prior to the brake balance tests. (The 1988 Chevrolet C-1500 pickup was a new vehicle and was trailered from the dealers lot to VRTC and so new parts were not installed on this vehicle prior to In many cases, the brake parts were supplied or the FMVSS test.) purchased directly from the manufacturer. For the remainder of the vehicles, the parts were purchased from local dealerships. For those vehicles which had tires with more than 5000 miles on the tires, new tires were also installed prior to the testing. Each of the vehicles was checked and, where necessary, reset to factory timing and idle rpm On those vehicles equipped with variable proportioning valves, the valves were checked to be sure that they were set according to the manufacturers specifications. The valve on one of the vehicles was incorrectly set and was reset according to the service manual.

The two vehicles equipped with antilock (Ford F-150 and Chevrolet C-1500) use a system which senses the drive shaft speed and only controls the rear wheels. Both vehicles use a system supplied by the same manufacturer, however, the plumbing arrangements of the two vehicles are slightly different.

#### 2.3 Instrumentation

The test vehicles were equipped with instrumentation to measure the following variables:

- a) vehicles speed
- b) stopping distance
- c) deceleration
- d) service brake pedal force
- e) parking brake pedal or lever force
- f) brake lining temperature
- g) wheel lockup
- h) time between two selected speeds
- i) brake line pressure

Speed and stopping distance were measured using a commercially available fifth wheel system. The fifth wheel drives a magnetic pick-up and pulses from this pick-up are fed into two digital meters. Electronics in the meters sum the pulses from the wheel to indicate distance traveled and differentiate this distance traveled continuously with respect to time to indicate speed. The system has a 12 volt trigger circuit to initiate distance measuring and "memorize" speed at the instant of trigger. The trigger circuit is connected to the 12 volt stoplight circuit on the vehicle and the brake pedal is adjusted so that a slight movement (1/8 inch or less) of the pedal provides the trigger signal. During stopping distance tests, the driver simply brings the vehicle up to the desired test speed by watching the speed meter and then applies the brake. When the vehicle reaches a stop, the distance meter indicates the stopping distance (to the nearest 0.1 ft.) and the velocity meter indicates the speed (to the nearest 0.1 mph) at which the brakes were initially applied. system does not measure suspension rock-back at the end of a stop (it stops counting the first time the wheel reaches zero speed) and it does not stop counting distance if the brake pedal is fully released by the driver during modulation of pedal force while the vehicle is moving.

Calibration of the stopping distance system was accomplished by running the vehicle over a 1000 foot measured course. Fifth wheel tire pressure was adjusted so that distance indicated agreed with the measured course. Calibration of speed was performed on a motor driven calibration stand. Overall accuracy of the system was determined to be better than  $\pm 0.2$  percent of indicated reading for distance and  $\pm 0.2$  mph for speed.

In addition to the triggered or "memorizing" velocity meter, a second untriggered meter (in parallel with the triggered meter) was used with its output driving a digital to analog converter to provide a reference signal for the lockup detector system.

Vehicle deceleration measurements were made using a servo accelerometer. The output signal of the accelerometer was sent to a meter on the dash for the driver to utilize during constant deceleration tests and to a strip chart recorder. The deceleration readings are slightly higher than the actual deceleration due to the pitch of the vehicle. This error is equal to the sine of the pitch angle (which is generally small) times the acceleration due to gravity. This error is typically in the order of 5 percent.

The service brake pedal force was measured by a strain gage load cell mounted to the brake pedal. The output signal was sent to a meter on the dash and to a strip chart recorder. The same type of load cell was used on pedal actuated parking brakes for the parking brake tests. For lever type parking brakes, a strain gaged load cell was fasteded to the hand lever at the center of the hand grip area with a hose clamp. Pedal and lever load cells were dead weight calibrated and measurements were accurate to within ±2 lbs.

Thermocouples, fabricated from 20 gauge iron-constantan wire, were utilized to measure brake lining temperatures. "Quick tip" crimp-on connectors were used to form the thermocouple junction. These thermocouple tips, which, when crimped, form a hexagon shape, were installed by drilling an undersized hole in the lining and then driving the tip to a depth of 0.040 inches. Thermocouples (one per brake) were installed in the most heavily loaded shoe or pad in the brake as per the proposed procedure.

Each vehicle was equipped with a single channel high impedance digital thermocouple readout and a multi-position thermocouple selector switch to which all of the thermocouples were connected. By rotating the switch, the driver could observe the lining temperature of each brake. During the fade and recovery portion of the test, a temperature recorder was also used to provide a continuous reading of the brake temperatures. Overall system accuracy was determined to be better than ±5 degrees Fahrenheit.

The system used for determining wheel lockup consisted of dc tachometer generators installed at each wheel and a "lockup box" with electronic circuitry to which the signal from the wheel tachometers were connected. Also connected to the circuit was an analog signal from a digital to analog converter "reading" the vehicle velocity An analog comparator circuit in the box compares "wheel velocity", which is equal to the wheel's rotation rate multiplied by the rolling radius of the wheel, to the vehicle's velocity as measured by the fifth wheel. Whenever the "wheel velocity" falls below five percent of the vehicle velocity (i.e., whenever the wheel slip exceeps 95 percent), the wheel is considered to have locked up and the comparator triggers additional circuits. A bulb is illuminated on the front panel of the box indicating that the wheel has locked during the The "lockup box" can also be set up to output to a recorder a discrete voltage for each wheel to show when it is locked. The system is designed to disregard lockup at vehicle speeds below 15 km/h.

Although the exact definition of wheel lockup requires that the wheel be at 100 percent slip, the lockup detectors use the 95 percent slip criteria because it greatly simplifies the electronics by eliminating the need to know when wheel velocity is exactly at zero. The error introduced by using this criteria is very small because any wheel that reached 95 percent slip will continue to 100 percent slip almost instantaneously since it is operating in an unstable region of the tire-road coefficient of friction curve.

The method for determining the time between two speeds used the "lockup box" which also has circuitry to compare the vehicle speed to preset values. These values are set by the driver prior to the test, then the driver exceeds the higher of the two speeds and as the vehicle decelerates through the higher speed the timer starts counting. When the speed goes below the lower set speed, the timer stops and an audible alarm alerts the driver that he is below that speed. The "lockup box" also incorporates an external timer to alert the driver at set intervals which is used during the fade where stops are made every 40 seconds.

The brake line pressures were measured by installing T's in the brake line with a strain gage type pressure transducer in one leg of the T. The pressure transducers were dead weight calibrated for accuracy and a shunt resistor was installed for periodic checks on the system calibration.

For the FMVSS tests, a two channel strip chart recorder was used in each vehicle to record deceleration and pedal force (or lever force in parking brake tests) during the stopping distance tests and the fade tests. During the axle lock sequence tests, vehicle speed was recorded on one channel and a signal showing wheel lockup (from the "lockup box") was recorded on the other channel. For the brake balance tests, a four channel recorder was used to record pedal force, vehicle speed, and front and rear brake line pressure. Electrical power for the recorders and other 115 vac powered instruments was provided by a dc to ac static inverter powered by the vehicle's electrical system.

#### 3.0 TESTS TO THE FMVSS 135 NOTICE 4

This section of the report describes the testing to the FMVSS 135 Notice 4 procedure. A discussion of the test procedure and the results will be given and also comparisons made to a 19 passenger car sample tested to the same procedure.

#### 3.1 Test Procedure - FMVSS 135 Notice 4 Tests

These tests were conducted in accordance with the FMVSS 135 Notice 4 procedure. A summary of this procedure is given in Table 2 with a more detailed description of the procedure given in Appendix A. In addition to the FMVSS 135 tests, an RTP test was run after each of the axle lock sequences for eight of the vehicles and for two more, the RTP was run after one of the axle lock sequences to compare the results. (The RTP was not fully operational when this program was begun and thus was not used on all vehicles.) In order to have additional data on the vehicles and the test procedure, a post fade

#### TABLE 2 -- FMVSS 135 Notice 4 Test Schedule

- 1. Load Vehicle to GVWR
- 2. Burnish 80 km/h, 3 m/s $^2$  in gear - 200 stops
- Service Brake Effectiveness at Full Load
  - Low Coefficient, 50 km/h in neutral 6 stops
  - Axle lockup sequence, 20 SN, 65 km/h in neutral
  - c. Axle lockup sequence, 50 SN, 65 km/h in neutral
  - 100 km/h in neutral 6 stops

  - 80 % V in gear 6 stops 100 km/h engine off in neutral 6 stops
- 4. Unload Vehicle
- 5. Service Brake Effectiveness at Light Load
  - Low Coefficient, 50 km/h in neutral 6 stops
  - Axle lockup sequence, 20 SN, 65 km/h in neutral
  - Axle lockup sequence, 50 SN, 65 km/h in neutral
  - 100 km/h in neutral 6 stops
  - 80 %  $V_{max}$  in gear 6 stops
- Partial System Tests at Light Load
  - Anti-lock failed, 100 km/h in neutral 6 stops
  - ъ. Variable prop failed, 100 km/h in neutral - 6 stops
  - Circuit 1 failed, 100 km/h in neutral 4 stops
  - Circuit 2 failed, 100 km/h in neutral 4 stops
- 7. Load Vehicle to GVWR
- 8. Partial System Tests at Full Load
  - Circuit 2 failed, 100 km/h in neutral 4 stops
  - Circuit 1 failed, 100 km/h in neutral 4 stops b.
  - Anti-lock failed, 100 km/h in neutral 6 stops
  - Variable prop failed, 100 km/h in neutral 6 stops
  - Power assist failed, 100 km/h in neutral 6 stops
- .9. Parking Brake Tests Loaded
  - Static 20 % grade, uphill/downhill in neutral
  - Dynamic, 60 km/h in neutral 2 stops
- Fade and Recovery Loaded
  - Heating, slower of 120 km/h or 80 % V to 1/2 initial speed, 3 m/s  $^2$  , 40 second interval 15 snubs
  - Hot performance, 100 km/h in neutral 2 stops Ъ.
  - Recovery, 50 km/h in gear 3 m/s<sup>2</sup> 4 stops
  - d. Recovery performance, 100 km/h in neutral - 2 stops

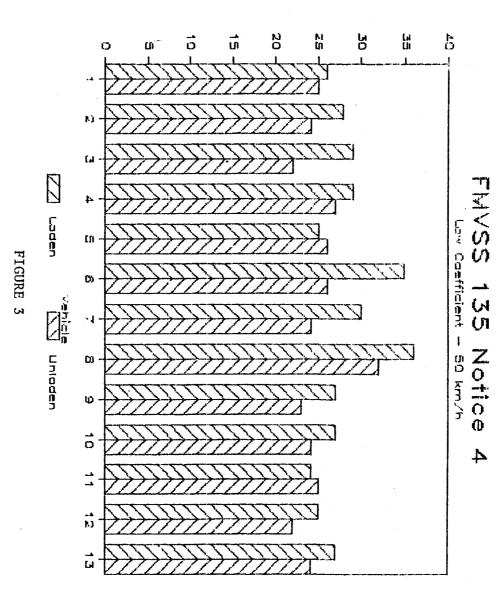
effectiveness test consisting of 6 best effort stops from 100 km/h was run. All of the vehicles were tested by the same driver and this driver also tested the 19 passenger cars discussed in Reference 5.

#### 3.2 Test Results - FMVSS 135 Notice 4 Tests

The test results for the FMVSS 135 Notice 4 tests will be shown graphically. A summary data sheet for each of the vehicles is given in Appendix B along with a vehicle information sheet, pictures of the vehicles and of any special equipment on the vehicle. Numbers on the graphs shown in this section of the report correspond to the vehicle numbers shown in Table 1. The results are also given in tabular form in Appendix C. At the end of this section, comparisons of the results of these tests will be made to the results of the 19 passenger car sample discussed in Reference 5.

The low coefficient stopping distance test is run on a 20 SN surface from  $50 \, \text{km/h}$ . The results from the laden and unladen tests are shown in Figure 3. The average for the 13 vehicles in the laden condition is  $28.3 \, \text{m}$  with a range from 24 m to 36 m. In the unladen condition the average is  $24.9 \, \text{m}$  and a range from 22 m to 32 m.

The axle lock sequence tests are run on a 20 SN surface and a 50 SN surface in both the laden and unladen conditions. The tests are run by making stops from 65 km/h with constant pedal force. The pedal force is incremented until only one axle locks. For eight of the vehicles (Dodge Caravan, Chevrolet Astro, Nissan Truck, Ford Ranger, Ford F-150 4X4, Dodge Dakota, Toyota 4-Runner and Jeep Cherokee), an RTP test was run immediately after each of the axle lock sequences. Toyota Van was run on the RTP only after the unladen axle lock sequence and the Chevrolet C-1500 was run on the RTP only after the laden sequence. Plots showing the results of these RTP tests are given in Appendix D. Table 3 shows the results of the axle lock sequence tests and the predictions made from the RTP tests (where available) which were run immediately after the axle lock sequence. The RTP graphs in Appendix D show the results in terms of peak tire to



\_

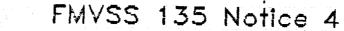
TABLE 3 -- Axle Lock Sequence Results

	Axle	Lock	Seque	ence	R	r Pre	edicti	Lon
	Laden		Unla	Unladen		Laden		aden
	<u> 20sn</u>	<u>50sn</u>	<u>20sn</u>	<u>50SN</u>	<u>20SN</u>	<u>50sn</u>	<u>20sn</u>	<u>50sn</u>
Dodge Caravan	F	F	F	F	F	F	F	F
Toyota Van	F	F	F	F	NA	NA	F	?
Chevrolet Astro	F	F	F	F	F	F	F	F
Ford E-250	F	R	F	F	NA	NA	NA.	NA
Nissan Truck	F	F	F	F	F	F	F	F
Chevrolet S-10	F	F	F	F	NA	NA	NA	NA
Ford Ranger	F	R	F	R	F	R	?	R
Ford F-150	F	F	F	F	NA	NA	NA	NA
Chevrolet C-1500	F	F	F	F	F	F	NA	NA
Ford F-150 4X4	F	F	F	<b>F</b>	F	F	F	?
Dodge Dakota	F	F	F	F	F	F	F	F
Toyota 4-Runner	F	F	F	F	F	F	F	F
Jeep Cherokee	F	F	F	F	F	F	F	F

road coefficient of friction and not skid number. In making these predictions, a peak mu value in the range of 0.4 to 0.6 was used for the  $^{\prime}$  20 SN surface and a peak mu value in the range of 0.8 to 0.9 was used for the 50 SN surface. Note that the table has a question mark for the Ford Ranger unladen on the 20 SN surface, and the Toyota Van and Ford F-150 4X4 in the unladen condition on the 50 SN surface. This means that a precise prediction of lockup sequence could not be made due to lack of sufficient tire data and/or RTP data. For the Ford Ranger, the plots from the RTP tests indicate a change from rear bias to front bias at a peak mu of approximately 0.25 and then back to front biased at a peak mu of approximately 0.45. Without further data on the tires, it is unknown what peak mu value would be appropriate for the 20 SN surface. Additional RTP data would also be necessary to more accurately define the mu values where the vehicle changes from front to rear or rear to front brake bias. In the case of the Toyota, the test was only run at decelerations high enough to make predictions on a surface with a peak mu of 0.45. For the Ford F-150 4X4, the predicted brake balance changes from front to rear biased on a surface having a peak mu value of approximately 0.7. As in the case with the Ranger, additional data on the vehicle tires would be necessary to know if the 50 SN surface would have a peak mu value greater or less than 0.7 and more RTP data to know the exact crossover point, so no prediction could be made. For the remainder of the cases where RTP data was available, the predictions and the test results agree. All of the 13 vehicles locked the front axle first on the 20 SN surface and only two of the vehicles (Ford E-250 laden and the Ford Ranger laden and unladen) had the rear axle lock first on the 50 SN surface.

The full system 100 km/h test results both laden and unladen are shown in Figure 4. The average, minimum and maximum distances for the laden tests were 59.5 m, 50 m and 66 m respectively. For the unladen tests, the average was 54.8 m with a range of 51 m to 60 m.

Full system tests are also run at 80 percent of the maximum speed of the vehicle. For these vehicles, the maximum speed was determined by accelerating the vehicle to its maximum speed twice in



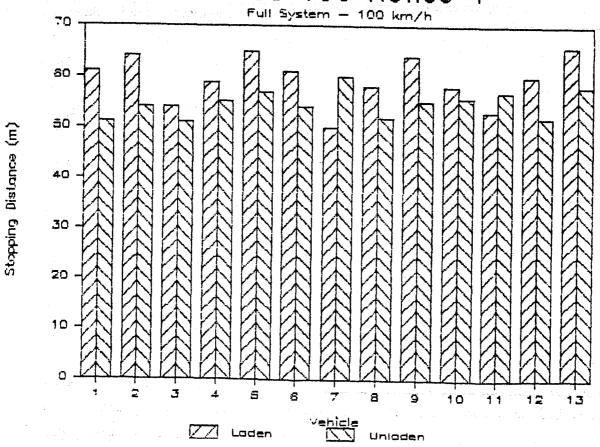


FIGURE 4

each direction on the high speed track. The average of the four speeds was used for the vehicle maximum speed. The results of the tests at 80 percent of  $V_{\rm max}$  are shown in Figure 5, showing the best stop distance as a function of the test speed. To establish requirements for passenger cars on this test, FMVSS 135 Notice 4 sets a minimum deceleration level the vehicle must meet. The vehicle deceleration is calculated using the stopping distance, the initial speed and an assumed system reaction time of 0.25 seconds. Using this same system reaction time, vehicle decelerations were calculated and are shown in bargraph form in Figure 6. The average laden deceleration level was 7.44 m/s $^2$  with a range from 6.27 m/s $^2$  to 8.67 m/s $^2$ . For the unladen tests, the average deceleration was 8.22 m/s $^2$  and ranged from 7.45 m/s $^2$  to 8.94 m/s $^2$ .

The full system 100 km/h tests with the engine off results are shown in Figure 7. This test is only run in the laden condition. Average, minimum and maximum values were 58.3 m, 46 m and 69 m respectively.

The failed system tests are all run at 100 km/h. The results for the laden circuit failure tests are shown in Figure 8. All but one of the vehicles (Dodge Caravan) have front/rear plumbing splits. letters above the bars in this and the next graph indicate the axle on which the brakes were failed. For this set of tests, the overall average (i.e. the average for all of the vehicles with both failures together) was 109.8 m and the range was 70 m to 198 m. For the unladen condition, the results are shown in Figure 9. Again overall values were used giving an average of 107.5 m and a range of 59 m to 201 m. In both of these tests, vehicle number 8 (Ford F-150) with the front brakes failed had the longest stopping distance. This vehicle had a rear wheel antilock system which allowed full pedal effort to be applied without wheel lockup during the test with the front brakes failed. Vheicle 9 (Chevrolet C-1500) had the same rear wheel antilock system using a different plumbing arrangement and had shorter stopping distances during the failed front brakes tests. It is unclear why the performance of these two vehicles are different.

# FMVSS 135 Notice 4

STATE OF THE PROPERTY OF STATE OF STATE

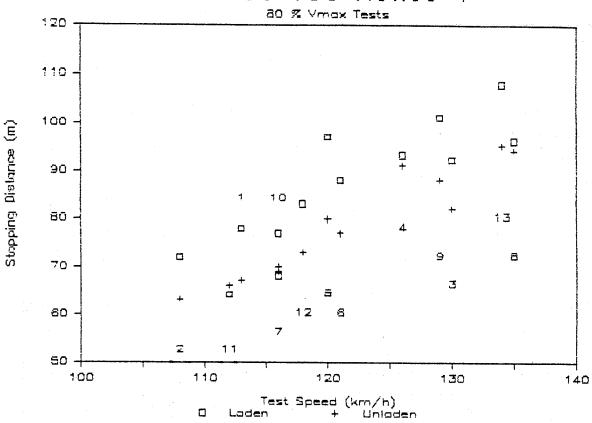


FIGURE 5

## FMVSS 135 Notice 4

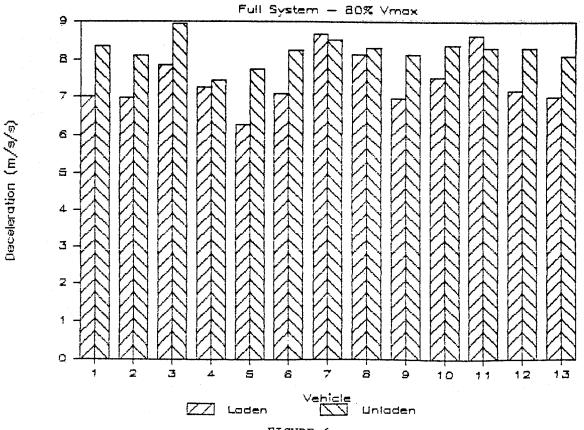


FIGURE 6

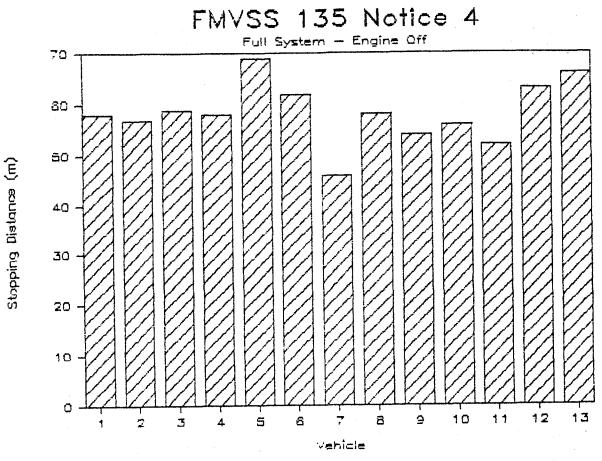


FIGURE 7

# FMVSS 135 Notice 4

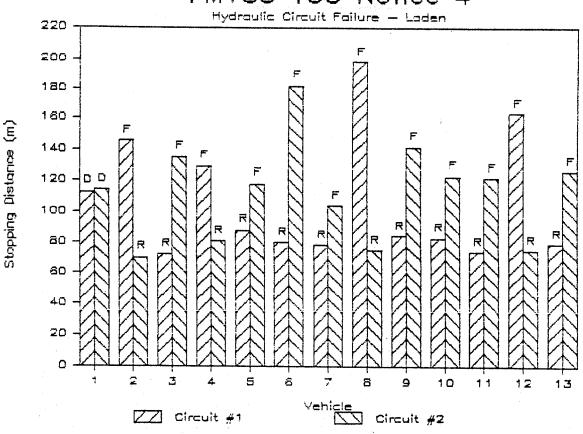


FIGURE 8

## FMVSS 135 Notice 4

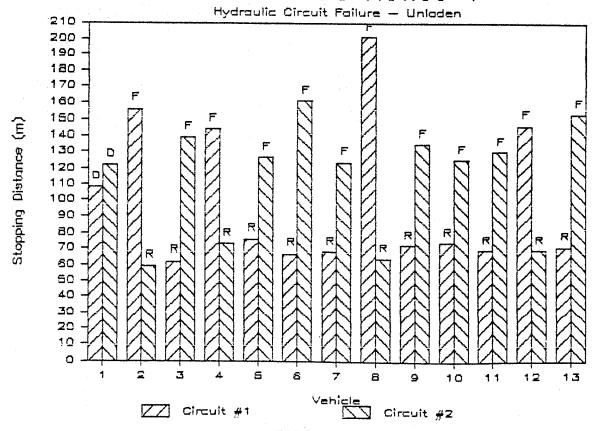


FIGURE 9

The failed power assist test results are shown in Figure 10. This test is only run in the laden condition. The average for the 13 vehicles was 125.1 m with a range of 62 m to 180 m.

For the vehicles which have variable proportioning systems or antilock systems, the stopping distance performance with these systems failed was measured. The results of these tests are shown in Table 4. The antilock systems were failed by disconnecting the power to the unit. On the Ford F-150, however, the incorrect wire was disconnected and due to the smooth operation of this antilock system, the driver was unaware that the antilock was still operational during the "failed This problem was not detected until all of the antilock" tests. testing on this vehicle had been completed. Stopping distance tests were repeated in both load conditions with the antilock system operational and with it failed. The percent increase in stopping distance with the system failed was calculated for both load conditions. From these percentages and the FMVSS 135 Notice 4 full system stopping distances, the failed system stopping distances shown in Table 4 were Table 4 shows an improvement in stopping distance calculated. (negative increase) for the C-1500 with the antilock failed in the laden condition. In the laden condition, this vehicle is front brake biased and so failing the antilock system should not effect the stop-The six percent change in stopping distance is ping performance. probably due to a change in the brake effectiveness from the time the full system tests were run to the time the failed system tests were run and test to test variability.

Of the vehicles equipped with variable proportioning, all except the Nissan truck had height sensing valves. These valves use a linkage which senses the distance between the bed and the rear axle. As the vehicle is loaded, this distance decreases and the proportioning valve decreases the amount of rear brake proportioning. The Ford E-250 had a two stage valve which set the proportioning to one of two levels. The other height sensing valves were continuously variable. Where possible, the valves were failed to simulate the worst case condition. This means that when the vehicle was fully loaded, the

### FMVSS 135 Notice 4

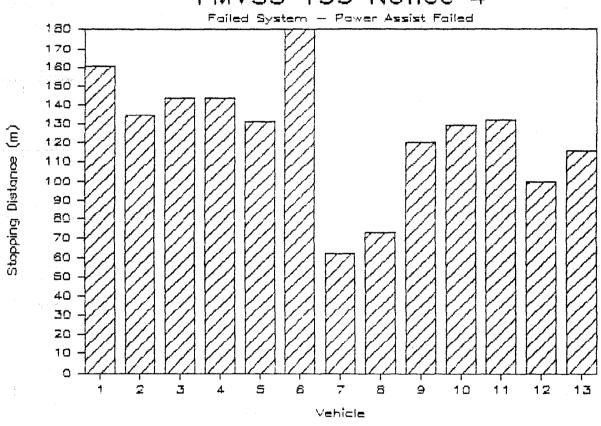


FIGURE 10

TABLE 4 -- Failed Variable Prop and Failed Antilock Results

			Laden		Unladen			
		Sy	ystem	In-	Sys	stem	In-	
		Full	Failed	crease	Ful1	Failed	crease	
<u>Vehicle</u>	<u>Sys</u> *	<u>(m)</u>	<u>(m)</u>	<u>(%)</u>	<u>(m)</u>	<u>(m)</u>	<u>(%)</u>	
Dodge Caravan	VP	61	63	4	51	61	20	
Toyota Van	VP	64	57	-11	54	58	7	
Ford E-250	VP	59	63	7	55	55	0 -	
Nissan Truck	VP	65	52	-20	57	67	18	
Ford F-150	AL	58	59**	1	52	64**	22	
Chevrolet C-1500	AL	64	60	-6	55,	55	O	
Dodge Dakota	VP	53	63	19	57	58	2	
Toyota 4-Runner	VP	60	63	5	52	55	, <b>7</b> .	

\*System failed: VP = Variable Prop, AL = Antilock

\*\*Stopping distance calculated from later tests

valve was failed such that it was in a lightly loaded position and the rear brake pressure was fully proportioned. Conversely, when the vehicle was lightly loaded, the valve was failed to a fully loaded position and the rear brake pressure had little or no proportioning. It was not possible to do this on the Dodge Dakota, however, so the linkage to the valve was simply disconnected, simulating a lightly loaded condition. The Nissan truck had a deceleration sensing valve which changes the proportioning characteristics based on the vehicle On this vehicle, the valve was failed by installing deceleration. plumbing bypass the valve (i.e. no rear brake pressure Table 4 shows that for two of the vehicles with proportioning). variable proportioning valves, the stopping distance improved when the valve was failed. This is because the valves on these vehicles proportioned the rear brake pressure more than necessary for that load condition, reducing the rear brake output which resulted in longer stopping distances.

and the control of the

The FMVSS 135 Notice 4 specifies two tests for the parking brake system. The first is a static test where the vehicle is parked on a 20 percent grade both facing uphill and downhill and must hold with only 400 or 500 N force on the parking brake control depending on whether the brake is hand or foot applied respectively. For these tests, the vehicles were parked on the hill and the minimum force to hold the vehicle stationary was determined. This minimum force to hold is shown in Figure 11. The letters above the bars in this graph indicate whether the parking brake is hand or foot acctuated. The Ford F-150 4X4 would not hold with only 500 N force, however, this was an older vehicle and while the parking mechanism appeared to work freely, there may have been friction which would not have been present with a new vehicle.

The second parking brake test is the dynamic test where two stops are made from 60 km/h using only the parking brake. The stopping distance for the best of these two stops is shown in Figure 12 and the deceleration at the very end of that stop is shown in Figure 13. The average stopping distance was 66.6 m, ranging from 43 m to

### FMVSS 135 Notice 4

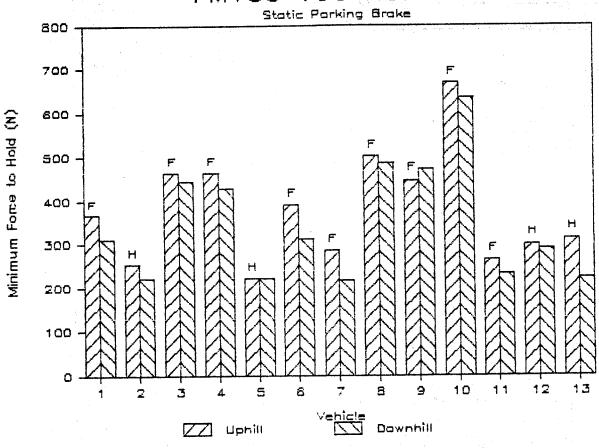
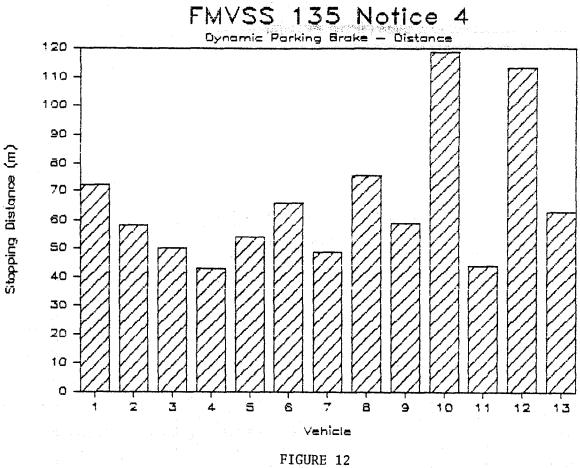
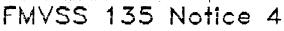
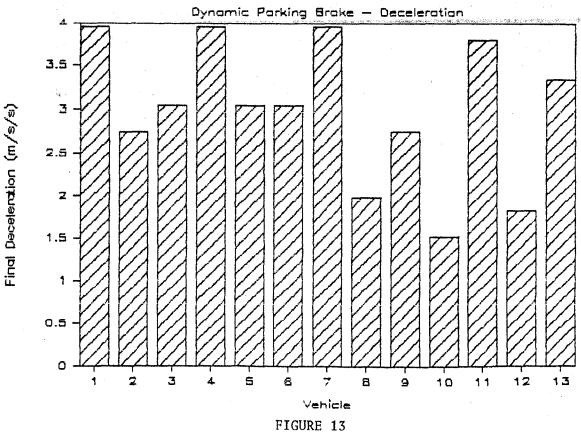


FIGURE 11

The figure  $\mathbb{A}_{i}^{(n)}$  is a decolerate for  $(1,1,2,\ldots,n)$  , . .







119 m. For the final deceleration (deceleration immediately before the vehicle stopped), the average was 3.0 m/s $^2$  ranging from 1.52 m/s $^2$  to 3.96 m/s $^2$ .

The fade and recovery sequence consists of heating snubs at 40 second intervals, two 100 km/h hot performance stops, 4 recovery snubs and two 100 km/h recovery performance stops. The best of the two hot performance and recovery performance stops are shown in Figure 14. The average, minimum and maximum distances were 77.3 m, 61 m and 104 m respectively for the hot performance and 67.0 m, 56 m and 77 m respectively for the recovery performance. The ratio of the best cold 100 km/h stopping distance to the hot performance distance and the best cold stop to the recovery performance distance are shown in Figure 15. The average ratio was 0.78 with a range of 0.57 to 0.90 for the hot performance and for the recovery performance the average was 0.89 ranging from 0.78 to 0.97.

The FMVSS 135 Notice 4 test procedure does not include a post fade effectiveness test, however, six 100 km/h best effort stops with the vehicle fully laden were made to have additional data on the vehicles. The results from this test are shown in Figure 16. In general, the post fade distances are about the same as the 100 km/h full system effectiveness with no obvious trends of shorter or longer distances after the fade. The average stopping distance for these stops was 59.7 m ranging from 47 m to 66 m.

In running the thirteen light trucks to the FMVSS 135 Notice 4 test procedure, there were no difficulties associated with testing this type of vehicle to the procedure which would suggest the need to change the procedure.

Nineteen passenger cars were tested to this same procedure and the results are discussed in Reference 5. These 19 cars covered a range of weights and brake configurations so that it was representative of vehicles in the fleet. Comparisons of the results for

### FMVSS 135 Notice 4

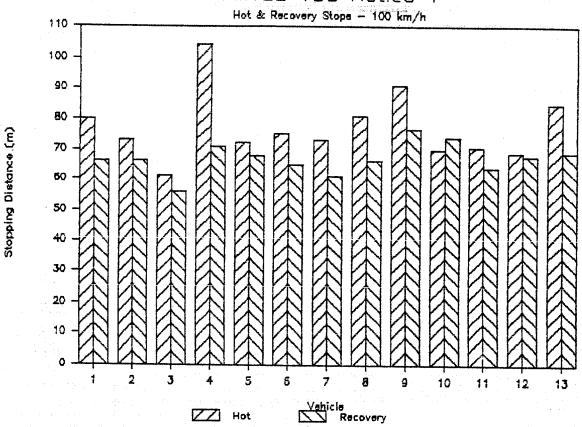
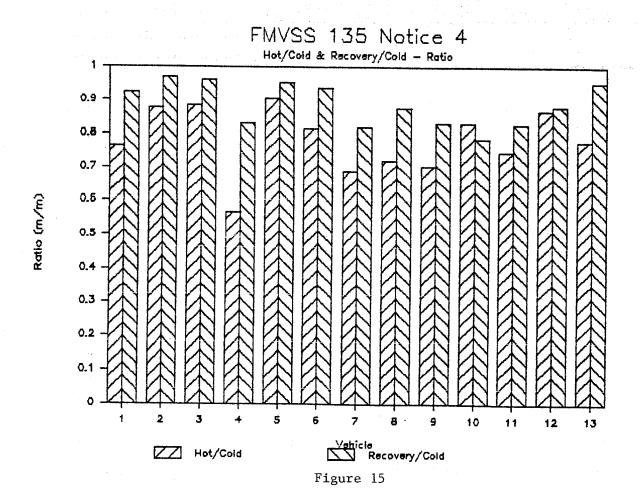
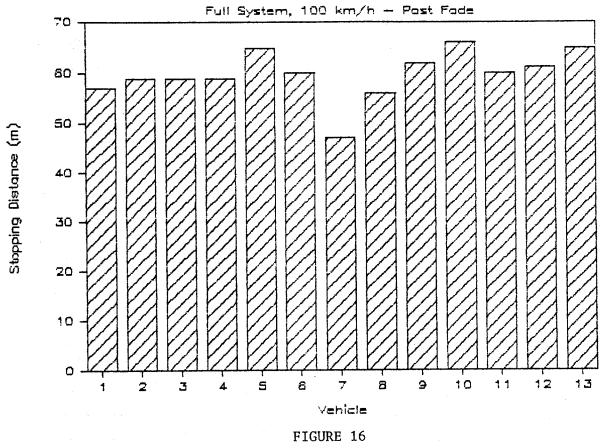


Figure 14





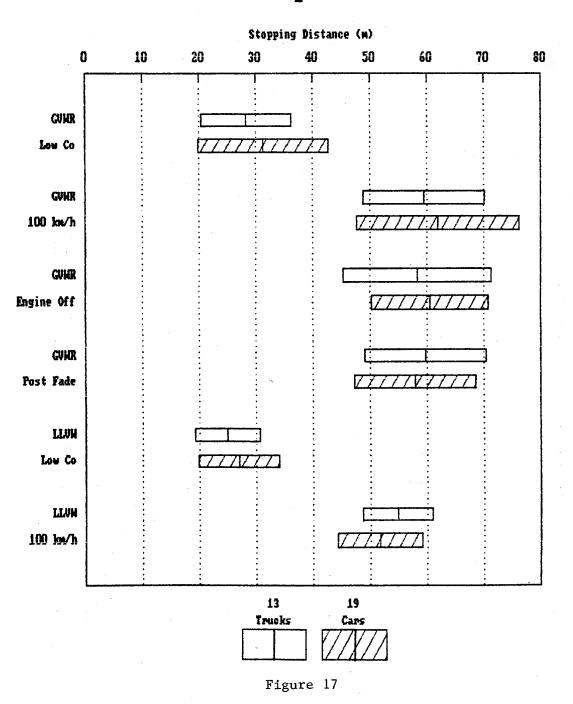
the 13 light trucks to the 19 passenger cars are shown in Figures 17 - 21 for each of the major test segments. The ends of the bars in these figures indicate the 95 percent confidence limits in vehicle performance and the line inside the bar shows the average for all of the vehicles. The 95 percent confidence limit was used for this comparison to eliminate differences due to sample size.

Figure 17 shows the comparison of the results of the full system This figure shows that the difference in the average performance is less than 3 m (10 ft). The comparison of the calculated deceleration for the 80 percent of  $V_{max}$  test is shown in Figure 18. The average performance of the two sets of vehicles are within 0.4  ${\rm m/s}^2$  (1.3 ft/s<sup>2</sup>). The comparison of the failed system tests are shown in Figure 19. The circuit failure results are for both circuits taken Comparing the two sets of vehicles, the light trucks stopped an average of 12 m (39 ft) shorter in the laden failed system test, 4 m (13 ft) longer in the inoperative power tests and 2 m (7 ft) longer in the unladen failed system tests. The light trucks had some vehicles with sigfnificantly longer stopping distances on the circuit failure tests resulting in wider confidence limits. This may be due the fact that more of the light trucks had front/rear plumbing splits than did the cars. Comparisons of the fade and recovery performance are shown in Figure 20 for the stopping distances and Figure 21 for the ratios of the hot performance to the best cold stop and the recovery performance to the best cold stop. The averages on these tests show the light trucks averaged 4 m (13 ft) shorter on the hot stop and 1 m (3 ft) longer on the recovery stop making the average ratios the same for the hot stop and 6 percent smaller on the light trucks for the recovery stop. The confidence limits for these tests are larger for the cars than the light trucks.

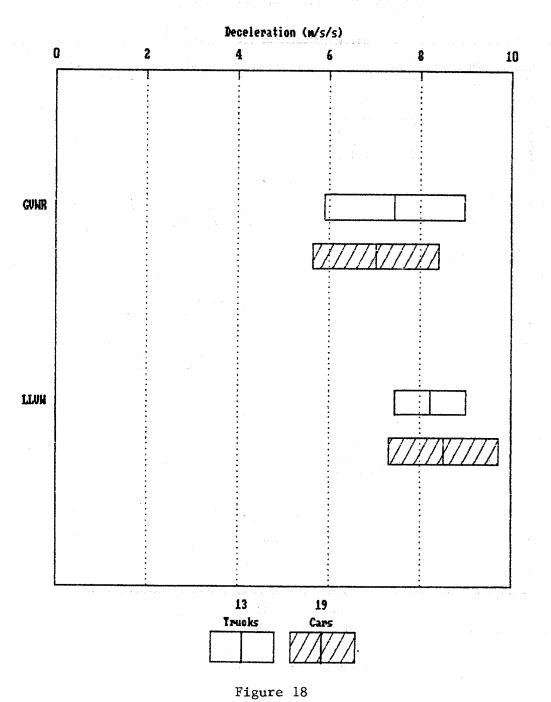
### 4.0 CENTER OF GRAVITY HEIGHT MEASUREMENT

This section of the report describes the method of measuring the center of gravity heights and moments of inertia of the vehicles.

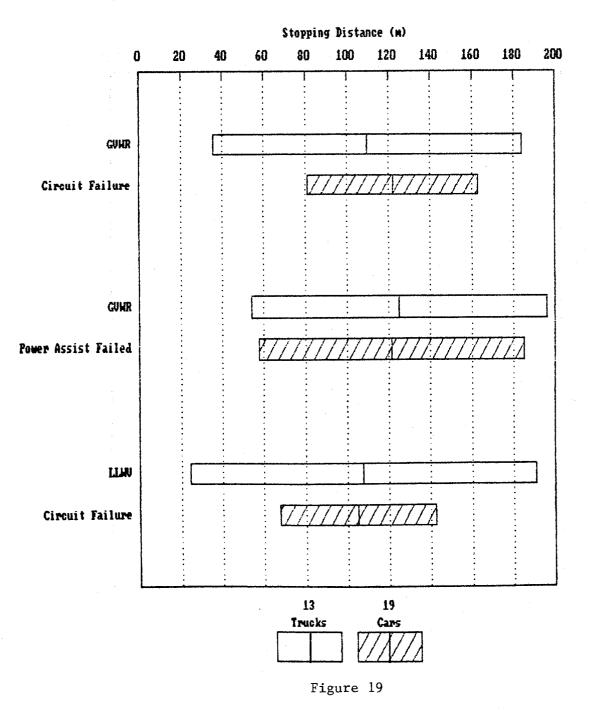
### FMVSS 135 Notice 4 Tests Light Truck and Passenger Car Comparison Full System Tests



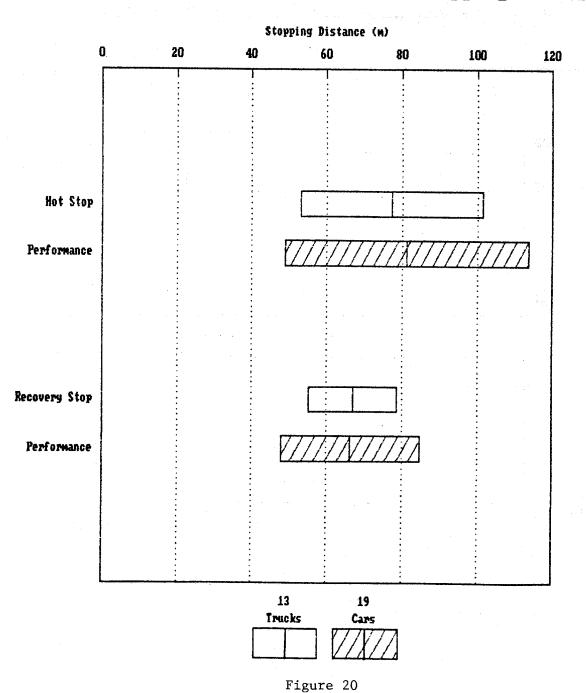
## FMUSS 135 Notice 4 Tests Light Truck and Passenger Car Comparison Full Service Braking - 80 % Vmax Tests



### FMUSS 135 Notice 4 Tests Light Truck and Passenger Car Comparison Failed System Tests



# FMVSS 135 Notice 4 Tests Light Truck and Passenger Car Comparison Fade and Recovery Performance Stopping Distance



## FMUSS 135 Notice 4 Tests Light Truck and Passenger Car Comparison Fade and Recovery Performance Ratios

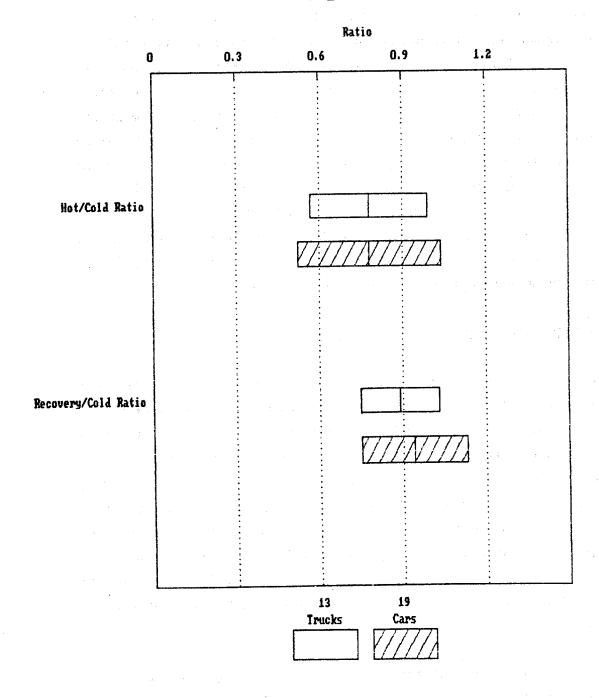


Figure 21

Additional tests were run on the Chevrolet S-10 and the Ford Ranger to evaluate the effect of load height on stopping distance. The results of these tests will be discussed in this section.

### 4.1 Test Procedure - Center of Gravity Heights

The center of gravity heights were measured using the device shown in Figure 22. This device and its use is described in detail in Reference 7. The vehicle is driven onto ramps so that the center of gravity is centered over the pivot point of the platform. The platform is raised and known torques are applied to the platform pivot. By measuring the angular displacement of the device for each torque input, the center of gravity can be determined. By allowing the device to swing freely and measuring the period of oscillation, the pitch moment of inertia can be determined. The vehicle can be repositioned so that the roll moment of inertia can be determined in the same way. Springs are attached to a free turning table on the device to allow the measurement of the yaw moment of inertia.

### 4.2 Test Results - Center of Gravity Heights

The center of gravity heights were measured in three load configurations; curb weight configuration, lightly loaded test configuration and the fully loaded test configuration. The center of gravity heights for each of these load conditions are shown in Table 5. For the Ford E-250 and the Chevrolet C-1500, the center of gravity heights could not be measured in the fully loaded configuration due to constraints on the test device. These values were estimated based on the unladen CG height, the load, and the change in the height of the vehicle above the ground with the change in load. The center of gravity height of the E-250 van in the curb weight condition was not measured.

To investigate the effect of load height on stopping distance, a load rack was built to be used on the Chevrolet S-10. With this load rack, shown in Figure 23, the load could be moved to various heights.

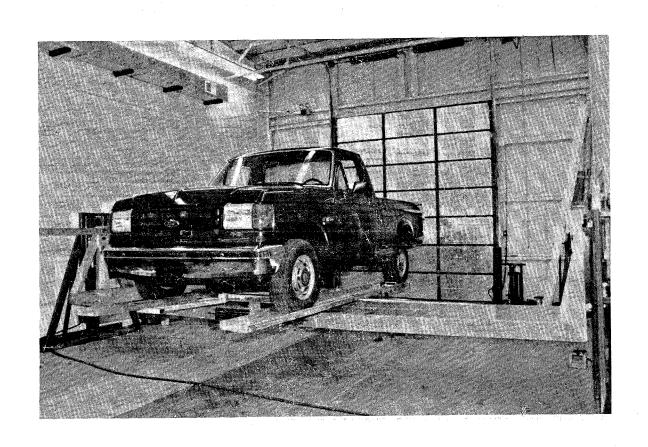


FIGURE 22 -- Vehicle on IPMD

TABLE 5 -- Center of Gravity Heights

	Curb	Unladen	Laden
<u>Vehicle</u>	<u>(mm)</u>	<u>(mm)</u>	<u>(mm)</u>
Dodge Caravan	683	692	667
Toyota Van	684	685	712
Chevrolet Astro	749	749	805
Ford E-250	NA	771	734*
Nissan Truck	608	606	635
Chevrolet S-10	618	639	697
Ford Ranger	619	658	659
Ford F-150	704	706	734
Chevrolet C-1500	734	763	745*
Ford F-150 4X4	706	737	794
Dodge Dakota	600	617	625
Toyota 4-Runner	737	766	805
Jeep Cherokee	693	710	700

\*CG height estimated

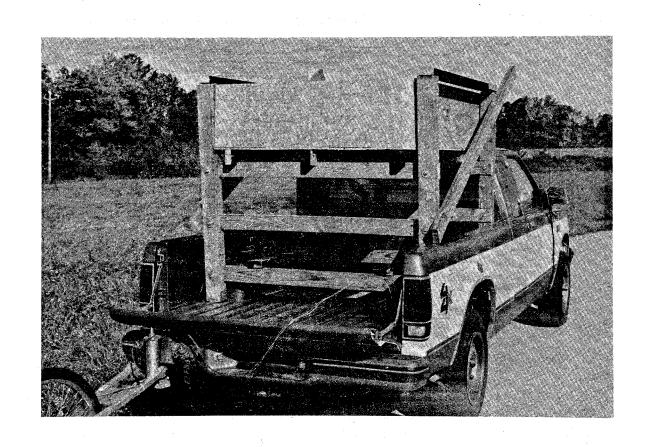
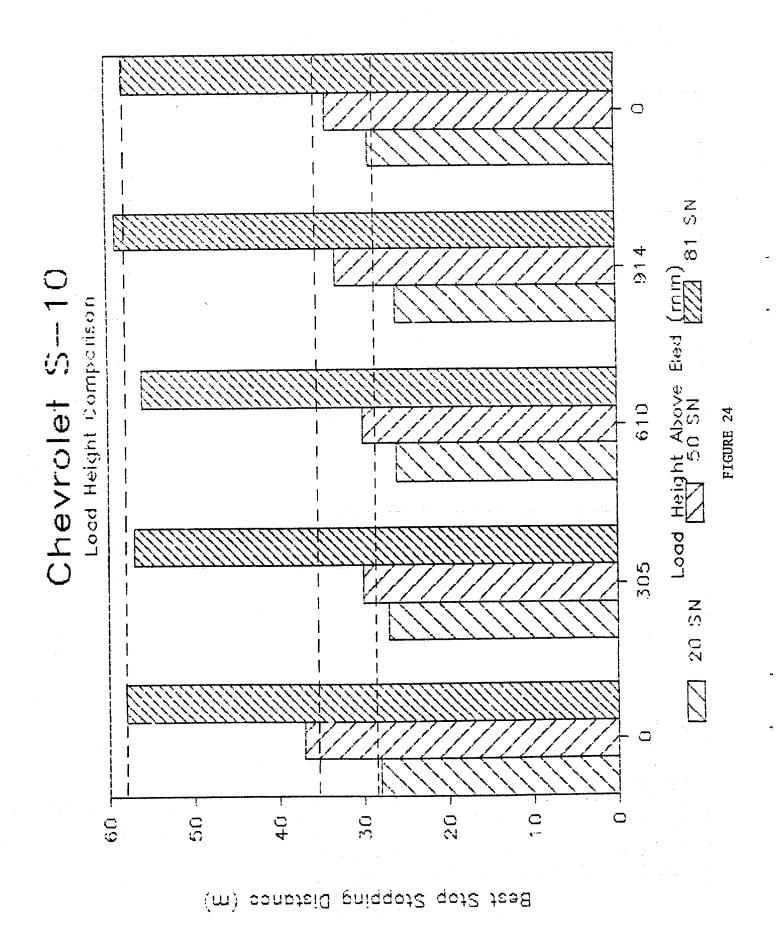
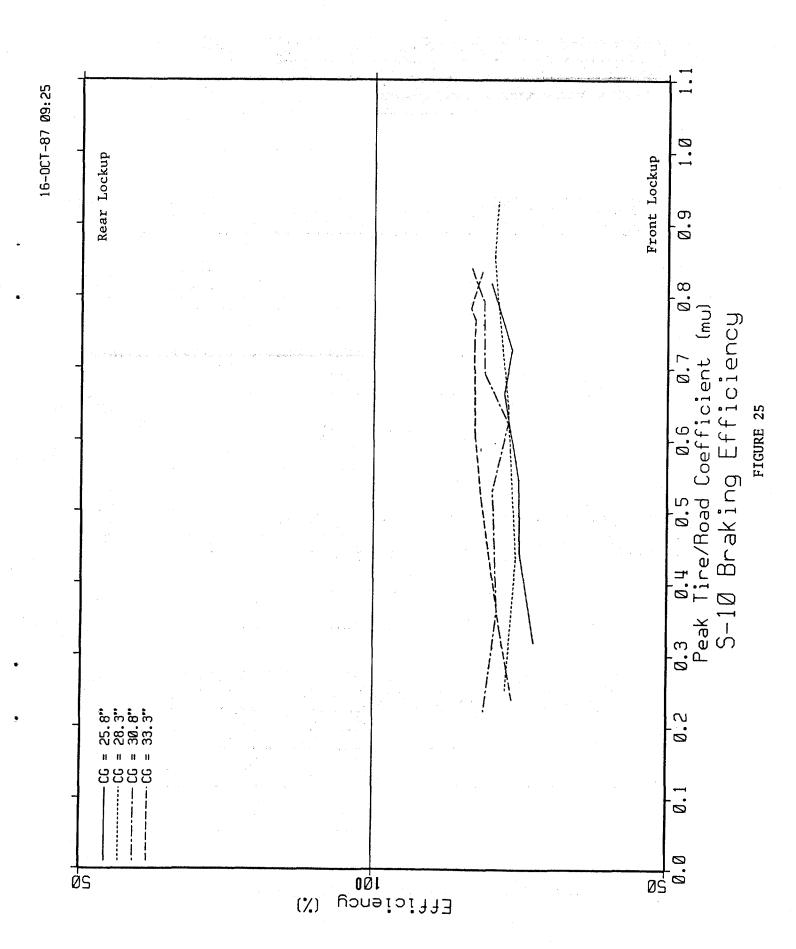


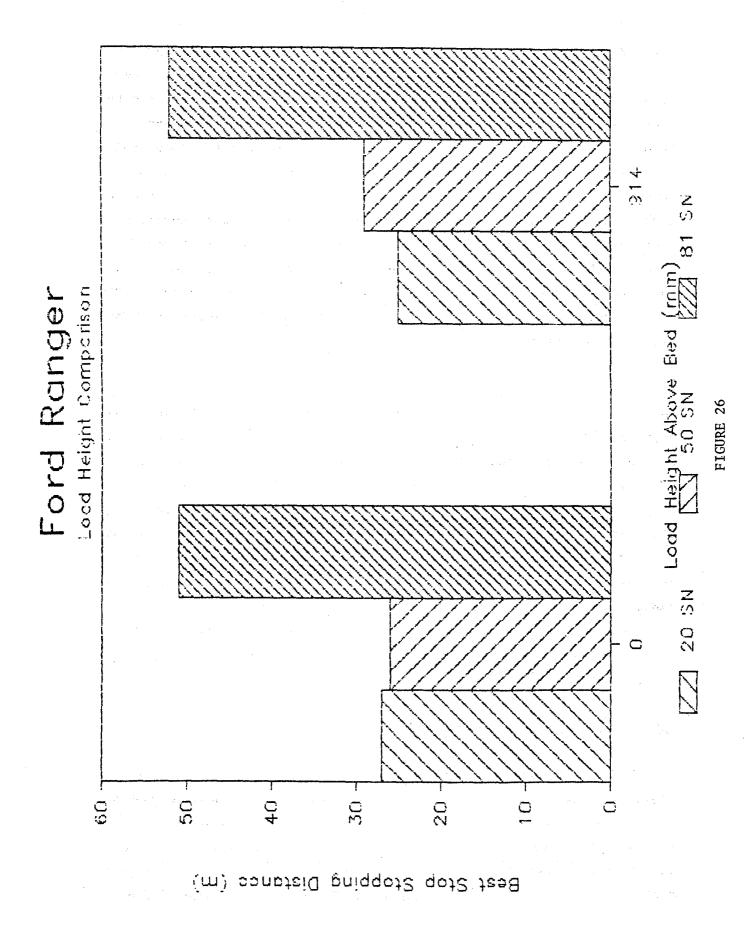
FIGURE 23 -- Chevrolet S-10 With Load Rack

The load heights used included having the load in the bed, at 305 mm (12 in) above the bed, 610 mm (24 in) above the bed and 914 mm (36 in) above the bed. These load configurations resulted in center of gravity heights of 697 mm, 760 mm, 823 mm and 886 mm respectively. At each load height, six best effort stops were made on each of three surfaces and an RTP test was run. The stops were made on a 20 SN surface from 50 km/h, a 50 SN surface from 65 km/h and a 80 SN surface from 100 km/h. At the conclusion of these tests, the stops with the load in the bed were repeated to determine if any conditioning of the brake system had occured which would confuse the test results. Figure 24 shows the stopping distance results for each of the configurations. The dashed lines on the figure represent the average stopping distance for the two tests with the load in the bed. The tests on the 20 SN and 81 SN surfaces show essentially no change in stopping distance for the two sets of tests with the load in the bed while the 50 SN surface results show a slight change. The stops on the 20 SN surface show a slight improvement in stopping distance for the higher load heights, however, these differences are small. On the other surfaces, the results do not show any significant trend with the differences being within normal data scatter. The results for the RTP tests at the various load heights are shown in Appendix E. While the braking forces did not change significantly between the configurations, the braking efficiency changed due to the change in CG height. Figure 25 shows a composite of the braking efficiencies for the four load As can be seen in the figure, the braking efficiency imheights. proved slightly for the higher load heights, however, the change is small which agrees with the results of the stopping distance tests.

The same load rack was used in the Ford Ranger and six best effort stops were made on the same three surfaces with the load in the bed and elevated 914 mm. The center of gravity heights for the two load configurations were 659 mm (25.9 in) and 830 mm (32.7 in). Figure 26 shows the results of these stopping distance tests. The differences in the distances for the two load heights are relatively small. The 81 SN surface results are the same while on the 20 SN surface the elevated load gave slightly shorter stops and on the 50 SN







surface the stops were slightly longer with the elevated load. An axle lock sequence was run on the 20 and 50 SN surfaces with both loads. On the 20 SN surface, the front axle locked first in both configurations. With the load in the bed on the 50 SN surface, the front axle locked first but showed nearly ideal balance (the front axle locked first on two stops and the rear axle locked first on the other stop). With the load elevated on this surface, the rear axle locked first. RTP tests were run in both of the load configurations, however, some conditioning of the brakes occurred during the time between the two tests which changed the performance of the brakes. The two RTP tests (results included in Appendix E) showed significant differences in the braking forces which made the results of these tests inconclusive.

The results of the tests with elevated loads indicate that the height of the load did not have a significant affect the stopping distance performance. For these two vehicles, the load height was changed an extreme amount (914 mm) which changed the vehicle center of gravity height 189 mm (7.4 in) on the S-10 and 171 mm (6.7 in) on the Ranger. Even with this change in load and CG height, the stopping distance performance change was small. The lockup sequence results changed on the Ranger with the change in load height, but only on a surface where the brake balance was near ideal. The results on this vehicle were also effected by a change in the brake system balance due to conditioning. Further investigation is needed to better quantify the importance of load height on tests such as a lockup sequence for vehicles with near ideal brake balance.

### 5.0 BRAKE BALANCE MEASUREMENTS

This section of the report describes the methods used to determine the vehicle braking balance and shows the results of these tests. At the time this program was started, the RTP was not in operation, so it was decided that the brake balance would be established by rebuilding the brake system, burnishing the brakes according to the FMVSS 135 Notice 4 procedure, and running a test to measure the brake balance

rather than conditioning the brakes during the FMVSS 135 Notice 4 tests. Since an RTP test does little conditioning of the brakes, the brake balance of some of the vehicles was measured on the RTP during the axle sequence tests described above in addition to the tests discussed here. A comparison of the brake balance of the light trucks will be made to the brake balance of the 19 passenger car sample.

### 5.1 Test Procedure - Brake Balance Tests

The brake balance for ten of the vehicles was measured in two For all 13 of the vehicles, new brakes were installed and burnished per FMVSS 135 Notice 4 and the brake balance was measured using a method similar to that described in Reference 8 hereafter referred to as the single axle procedure. This method consists of making snubs with only the front axle brakes operational and then only the rear axle brakes operational. By measuring the time between two speeds, the deceleration and, therefore, the braking force can be The brake line pressure was measured during these snubs. calculated. The braking force as a function of brake pressure is then determined by the straight line defined by the measured braking force and brake pressure and the brake pushout pressure at zero braking force. proportioning valve characteristics were also determined so for any front brake pressure, the front axle braking force, rear brake pressure and rear axle braking force could be calculated. Given this information and vehicle static weights, wheelbase and center of gravity height, the deceleration and adhesion utilization could be calculated. For vehicles with fixed proportioning valves, the proportioning valve characteristics were determined by making static brake applications to various levels while recording the front and rear To determine the proportioning valve characbrake line pressures. teristics for vehicles with variable proportioning valves, snubs were made, in addition to the static brake applications, at various deceleration levels in both the laden and unladen conditions. Variable proportioning valves use a set front to rear pressure ratio and vary the break point depending on load or deceleration. From the static test, the slope of the curve beyond the break point was

determined. From the dynamic tests, the relationship between the break point and rear axle load or deceleration was determined. In this fashion, the adhesion utilization characteristics were determined.

The second method used to determine the front to rear brake balance was with the RTP. The RTP was used for 10 of the 13 vehicles. For 8 of the vehicles, an RTP test was run in both load conditions both before and after the single axle distribution test and the remainder of the vehicles were run in only some of the conditions. Some of the scatter in the RTP data for those vehicles where the RTP was run both before and after the single axle test is due to conditioning changes of the brakes during the single axle test. The results from both methods will be shown below where available.

All of the plots shown in this section of the report show performance with the vehicle in gear. For the vehicles with standard transmissions, the gear used for the test was the appropriate gear for normal driving at the test speed.

### 5.2 Test Results - Brake Balance Tests

The adhesion utilization and braking efficiency plots for the laden Dodge Caravan are shown in Figure 27 and in Figure 28 for the unladen configuration. The adhesion utilization curve is interpreted by finding the peak tire/road coefficient of friction (mu) of interest along the verticle axis. The first line crossed when following horizontally across from this point (the line for the front axle in this case) is the axle which will lock first on the given surface. The smooth lines on these plots indicate the projection from the single axle test with the solid square indicating the point where the data was actually taken. The symbols on the plots show the results from the RTP tests. The braking efficiency plots also show which axle locks first by showing the line either above (rear biased) or below (front biased) the 100 percent efficiency line. The braking efficiency is read from this plot by finding the point on the curve

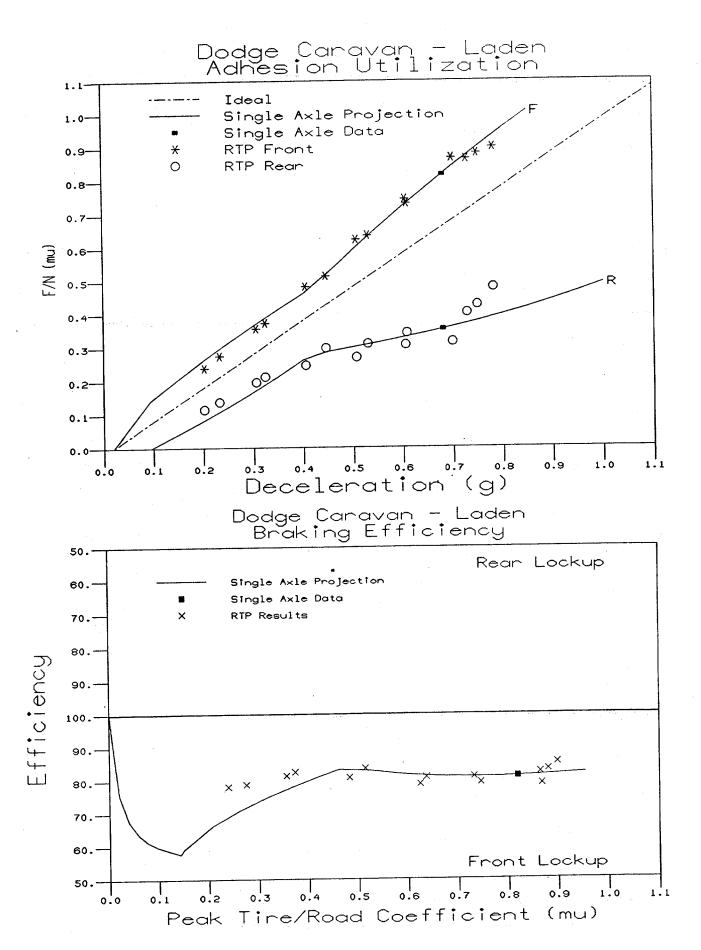
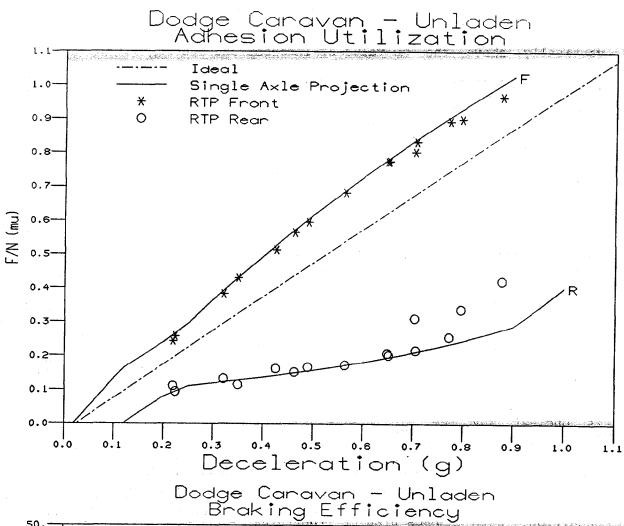
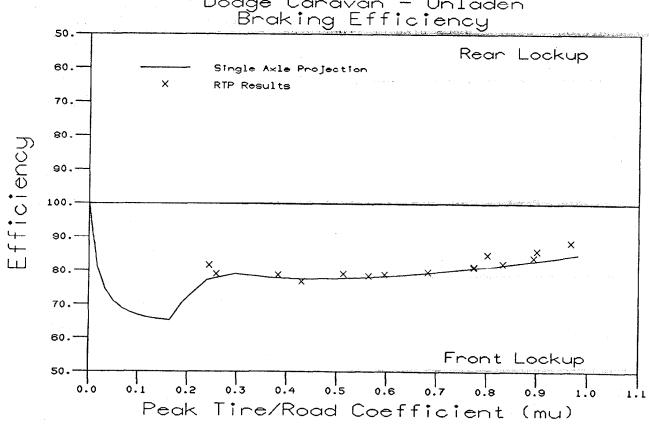


FIGURE 27



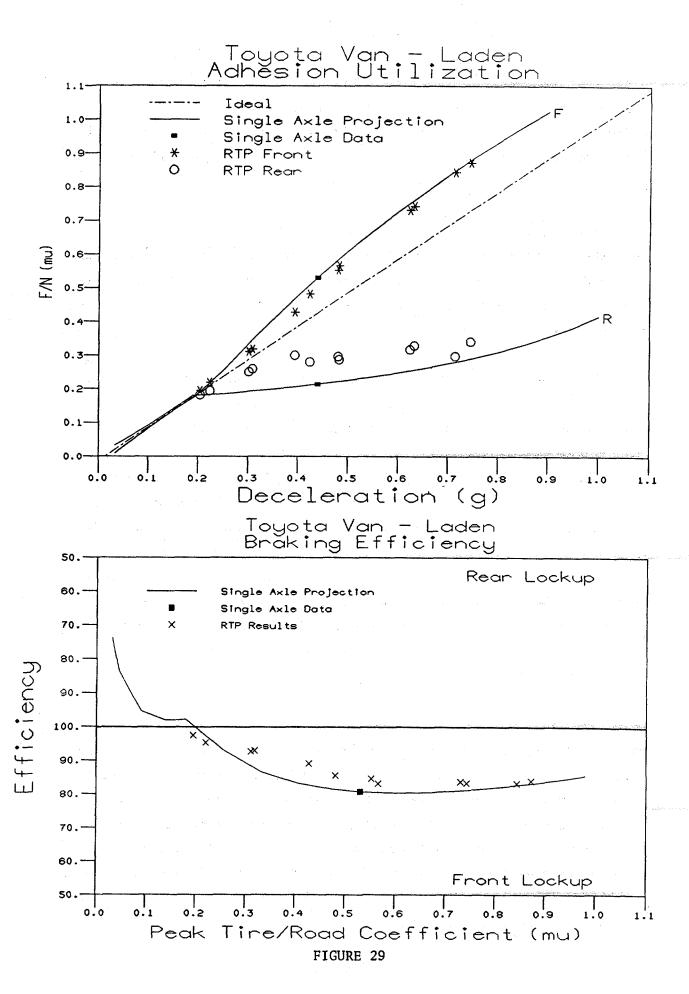


vertically above the mu value of interest and reading across to the braking efficiency. For the Dodge Caravan, which was equiped with a height sensing proportioning valve, the plots show that the vehicle is front brake biased in both load conditions and that the single axle projection and the RTP test agree quite well.

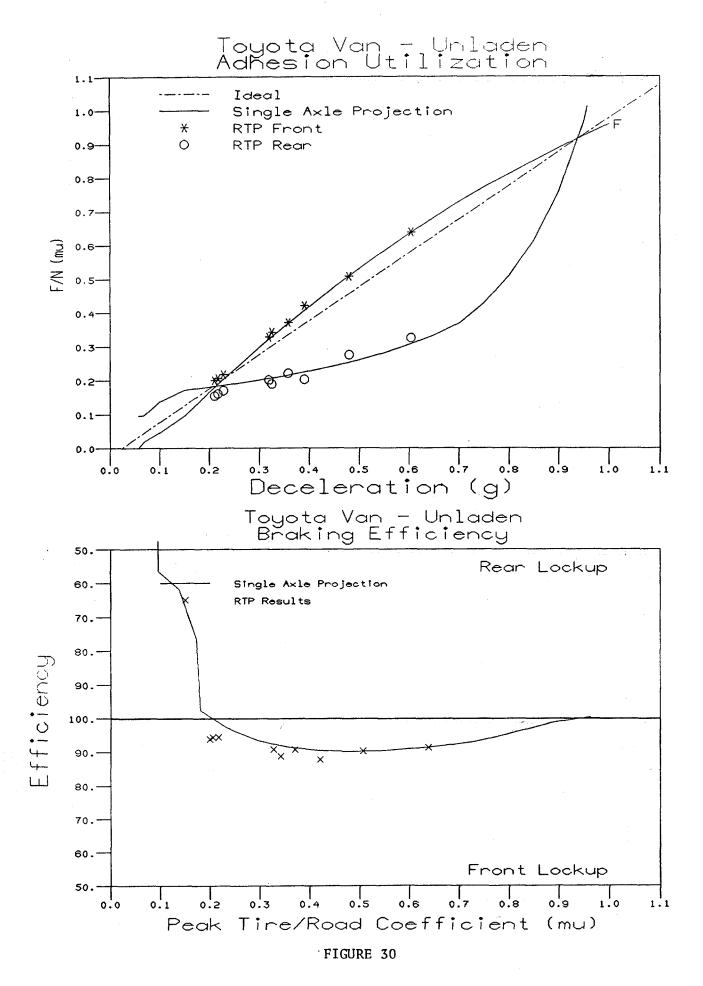
The results for the Toyota Van are shown in Figures 29 and 30 for the laden and unladen conditions respectively. This vehicle was equipped with a height sensing proportioning valve. The plot shows that the vehicle is basically front brake biased and that the two test methods agree quite well.

The Chevrolet Astro brake balance plots are shown in Figure 31 for the laden tests and Figure 32 for the unladen tests. The Astro had a conventional brake system with a fixed proportioning valve. It is unclear why the single axle procedure predicted more rear brake bias than did the RTP tests, however, the RTP tests on this vehicle during the axle lock sequence portion of the FMVSS 135 Notice 4 procedure agree quite well with the RTP tests shown here. In the laden condition, both methods predict front brake bias with the single axle projection indicating a higher braking efficiency. In the unladen condition, however, the single axle procedure predicts rear brake lockup above a peak mu of 0.3 while the RTP predicts front bias until a peak mu of around 0.9 to 0.95. Both methods predict a high braking efficiency.

The Ford E-250 van was not tested on the RTP. The results of the single axle test are shown in Figures 33 and 34 for the laden and unladen conditions respectively. This vehicle had a two stage height sensing proportioning valve which set the brake proportioning to one of two levels depending upon the distance between the bed and the rear axle. In the laden configuration, the single axle test predicted front brake bias up to a peak mu of 0.52 with nearly ideal balance for most of the values of mu. In the unladen condition, the vehicle is



To the respectful design breaking the first in



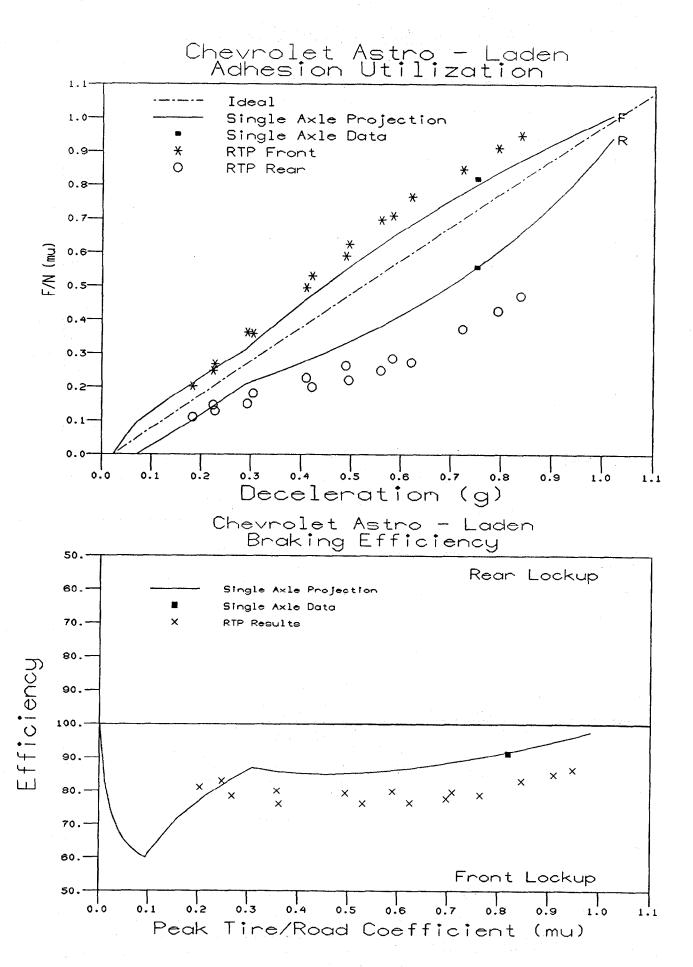
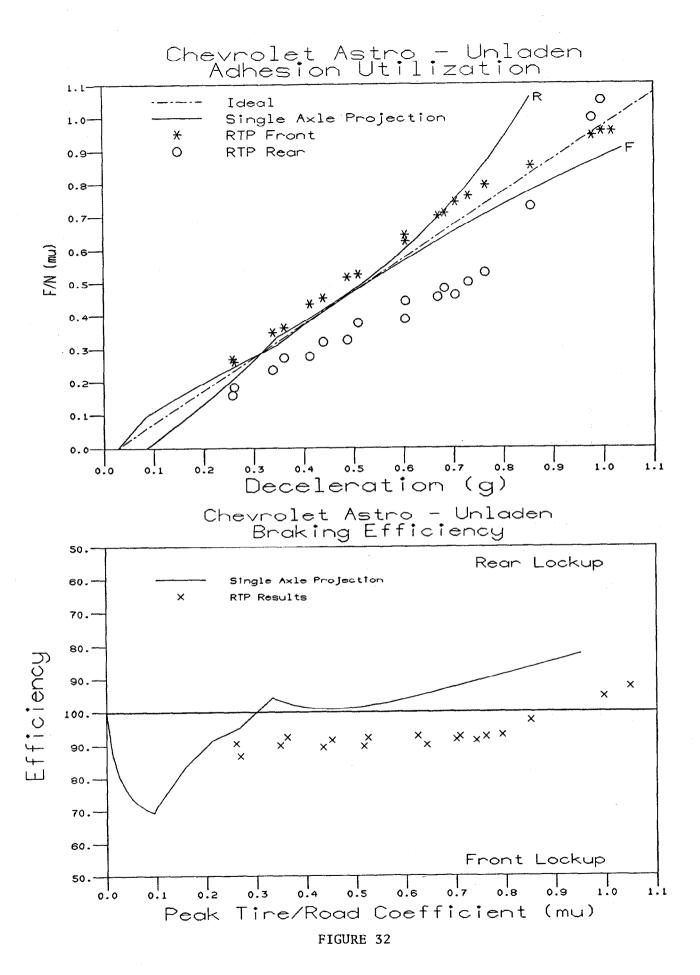


FIGURE 31



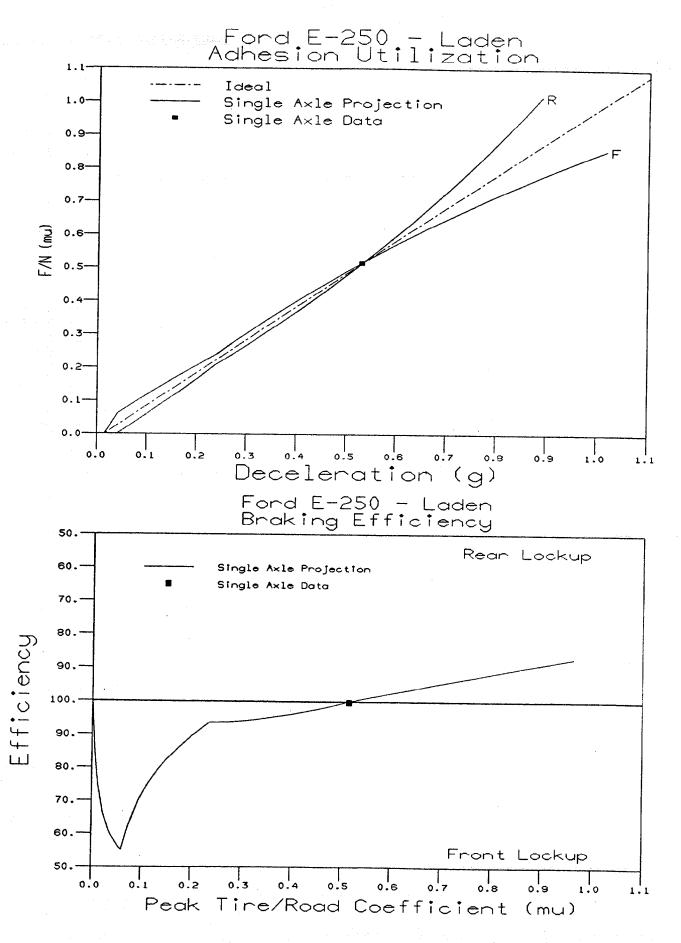
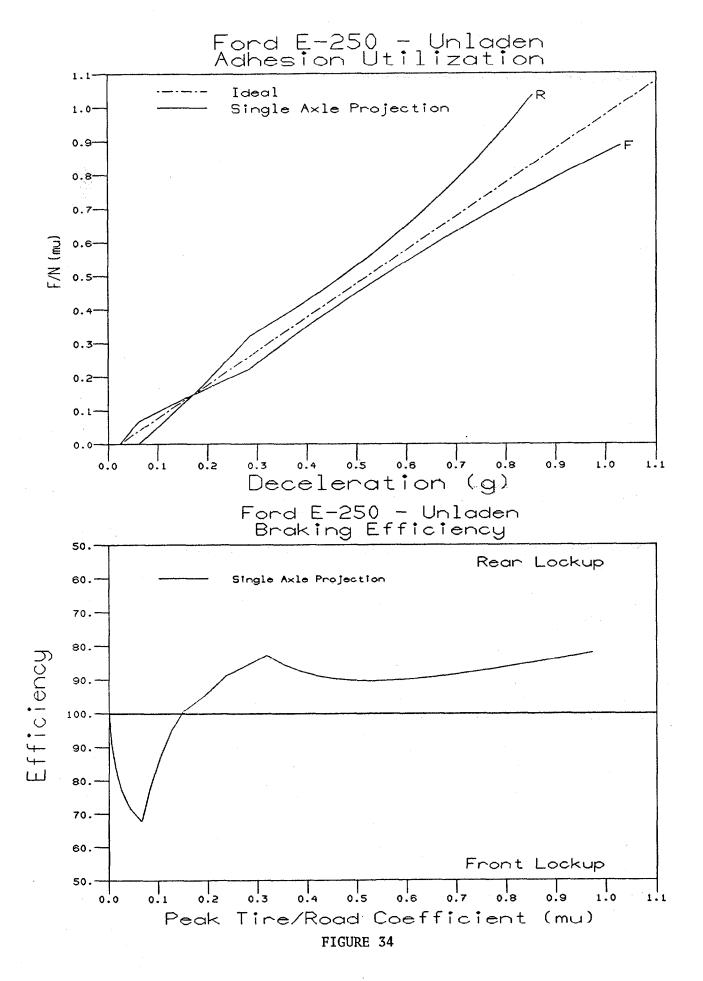


FIGURE 33

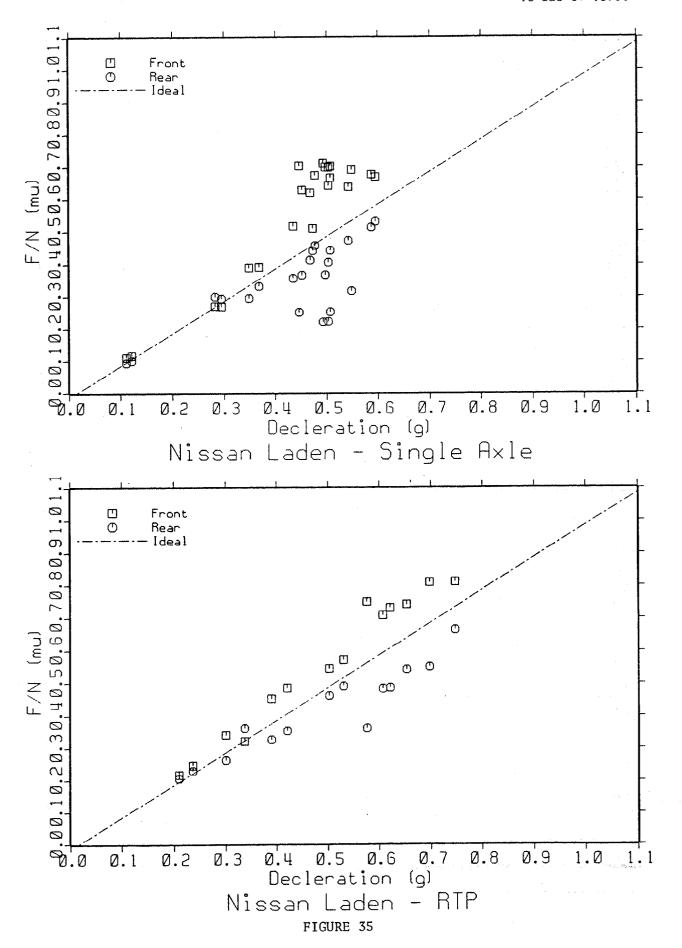


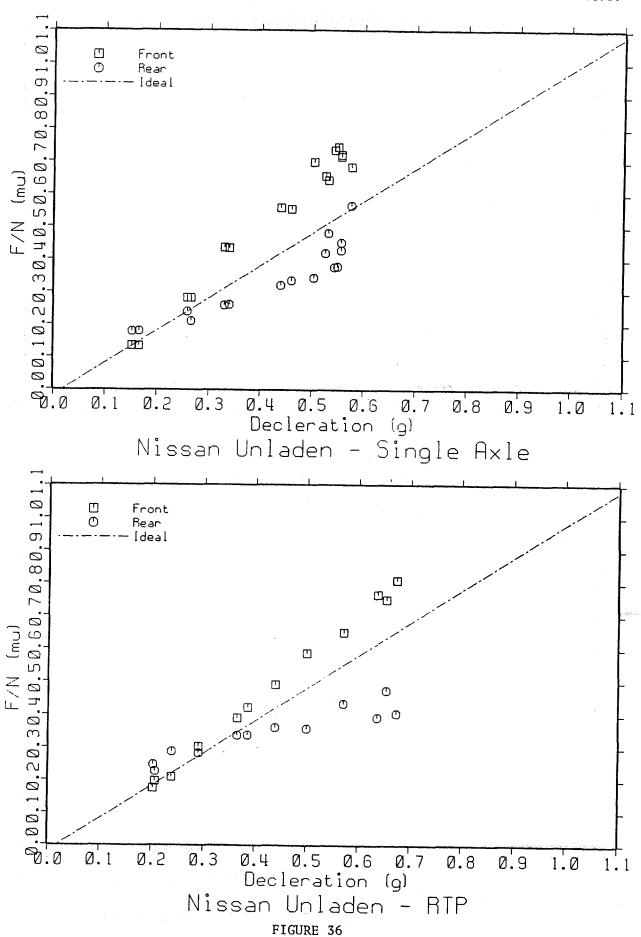
predicted to be rear brake biased for most values of mu with fairly high braking efficiency.

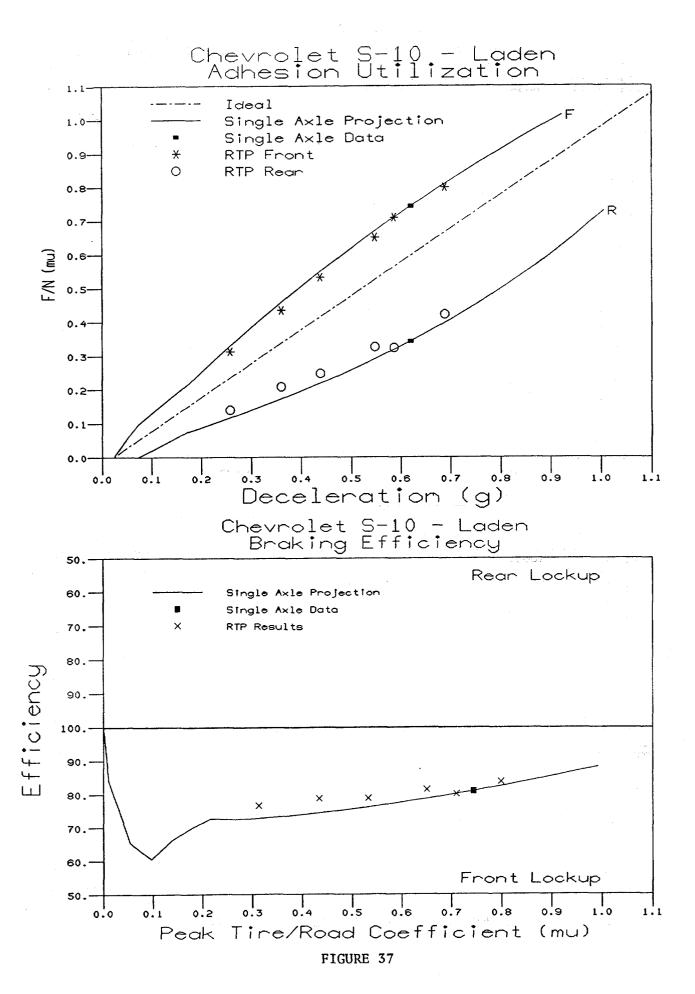
The Nissan truck was equipped with a deceleration sensing proportioning valve. In order to make a smooth projection of the brake balance for this vehicle, a number of snubs were made at various deceleration levels in both the laden and unladen condition while measuring the front and rear brake pressures. These measurements showed a great deal of scatter of the proportioning characteristics as a function of deceleration, hence, no smooth projection of brake balance could be made. Figure 35 shows the brake balance for each of the snubs made in the laden condition and also the results of the RTP tests. The unladen results are shown in Figure 36. For both loads, both methods agree that the vehicle is front brake biased and the trends of the relative amount of front bias are similar.

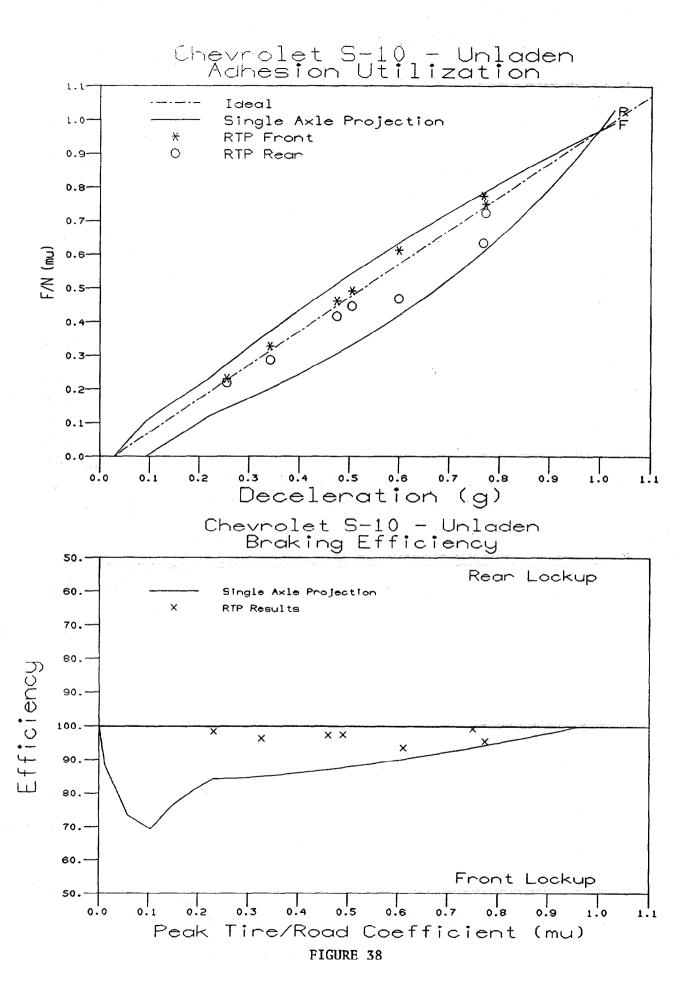
The Chevrolet S-10 brake balance results are shown in Figure 37 for the laden condition and Figure 38 for the unladen condition. The RTP test on this vehicle was only run immediately after the single axle test. For both loads, the vehicle is predicted to be front brake biased. The RTP and single axle methods agree reasonably well with the RTP predicting balance slightly closer to ideal in the unladen condition than the single axle test.

The results of the Ford Ranger tests are shown in Figure 39 for the laden condition and Figure 40 for the unladen condition. This vehicle had a conventional brake system with no proportioning valve. In the laden condition, the two methods agree reasonably well, predicting front brake bias up to a peak mu value of approximately 0.65. In the unladen condition, the single axle test predicted that the vehicle would switch from front biased to rear biased at approximately 0.32. The RTP tests for this vehicle showed some scatter, probably due to conditioning of the brakes, and so it is difficult to make precise predictions, however, it would appear that the RTP prediction of the crossover point would be slightly higher.









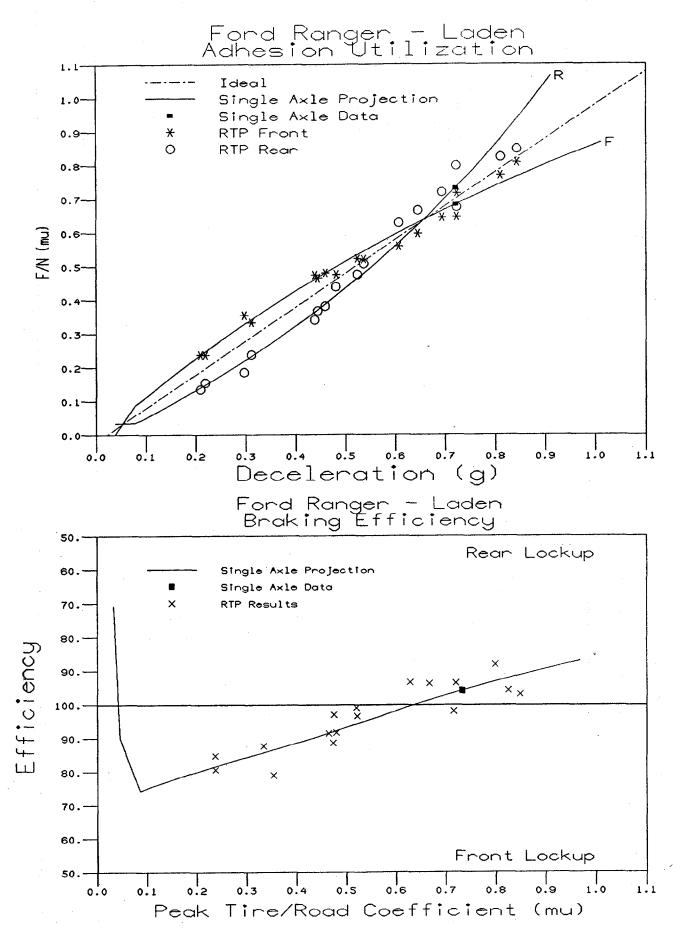
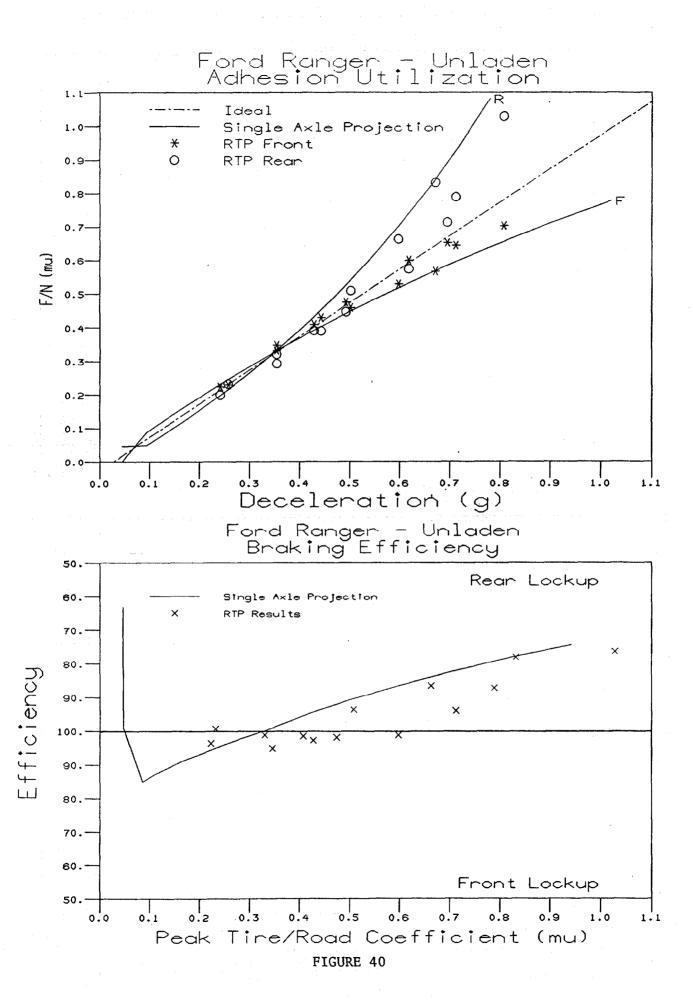


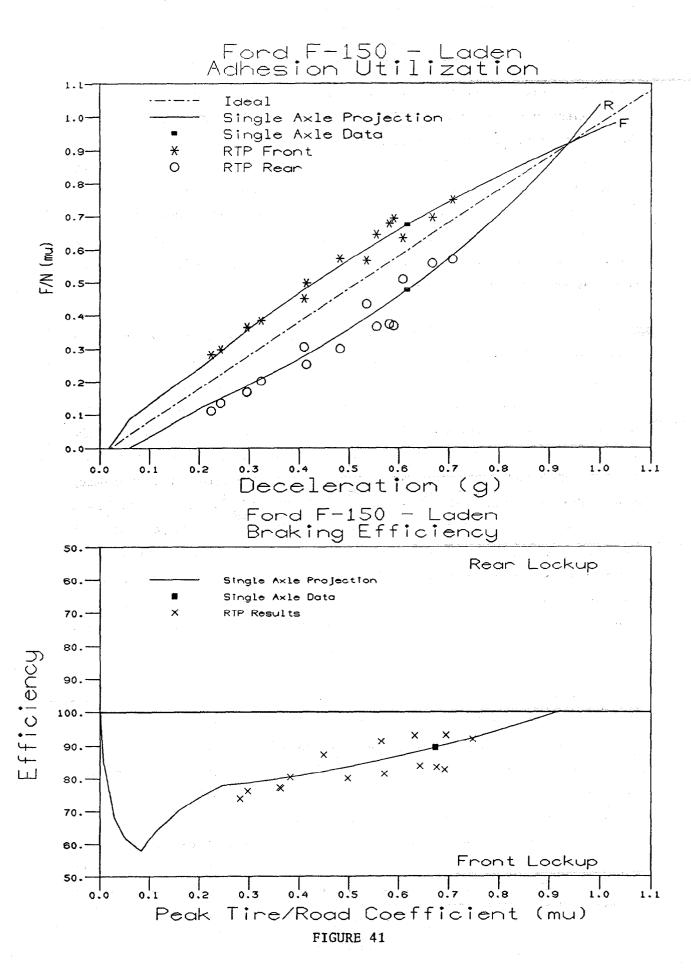
FIGURE 39

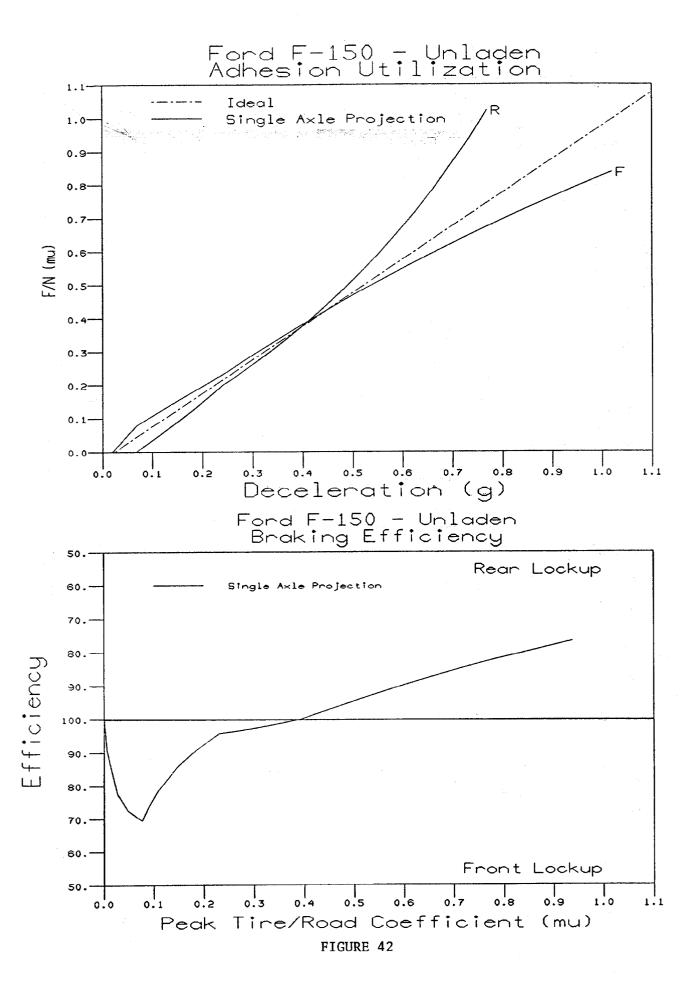


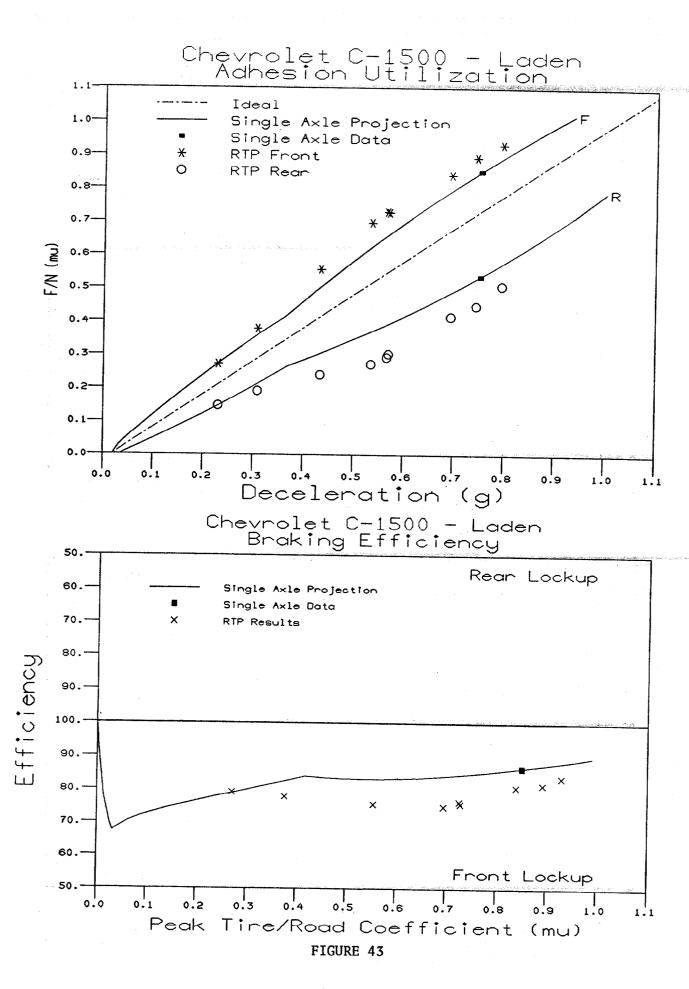
The Ford F-150 was equipped with an antilock system on the rear axle which was disconnected for these tests. The laden brake balance for this vehicle is shown in Figure 41. The vehicle is predicted to be front brake biased up to a high value of mu, hence, the rear antilock would not be used. In this load configuration, the RTP and the single axle methods agree quite well. In the unladen condition, shown in Figure 42, the single axle test predicts that the vehicle will become rear biased above a peak mu value of approximately 0.4. An RTP test was not run on this vehicle in the unladen configuration.

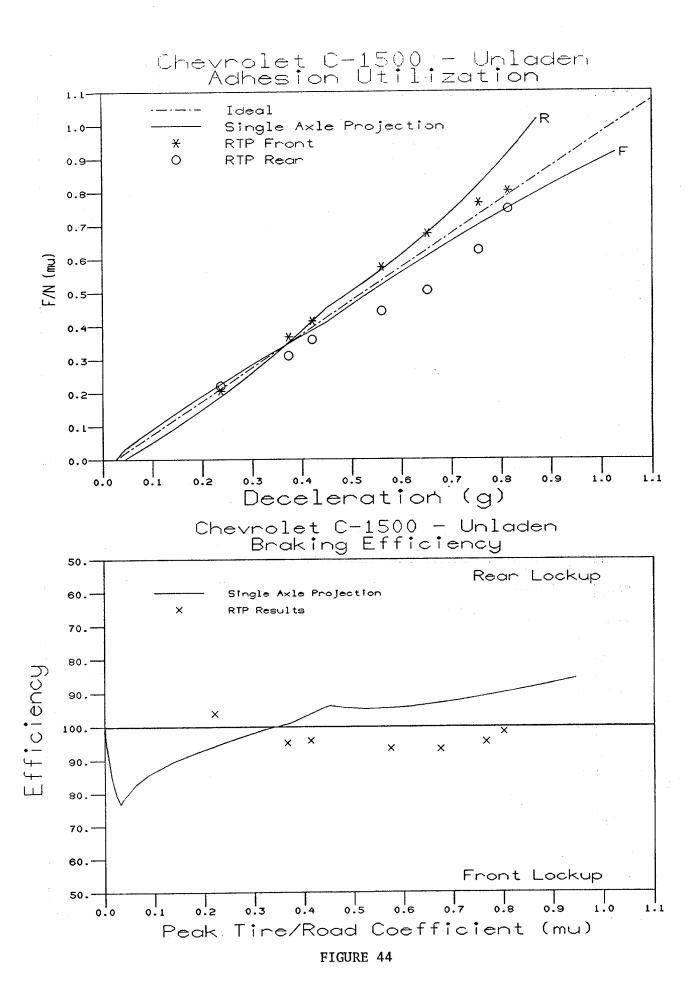
The Chevrolet C-1500 was also equipped with a rear antilock system which was disconnected for these tests. The brake balance test results are shown in Figure 43 for the laden condition and Figure 44 for the unladen condition. With the vehicle fully loaded, both test methods indicate that the vehicle would be front biased, however, the RTP shows more front brake force than does the single axle projection. In the unladen condition, the RTP again predicts more front braking than does the single axle procedure, with the RTP showing front brake bias while the single axle procedure predicts rear brake bias for peak mu values greater than approximately 0.35. It is unknown why the two methods do not agree for this vehicle, however, the RTP test run after the laden axle lock sequence agrees quite well with the laden RTP test shown here. (No RTP test was run after the unladen axle lock sequence.)

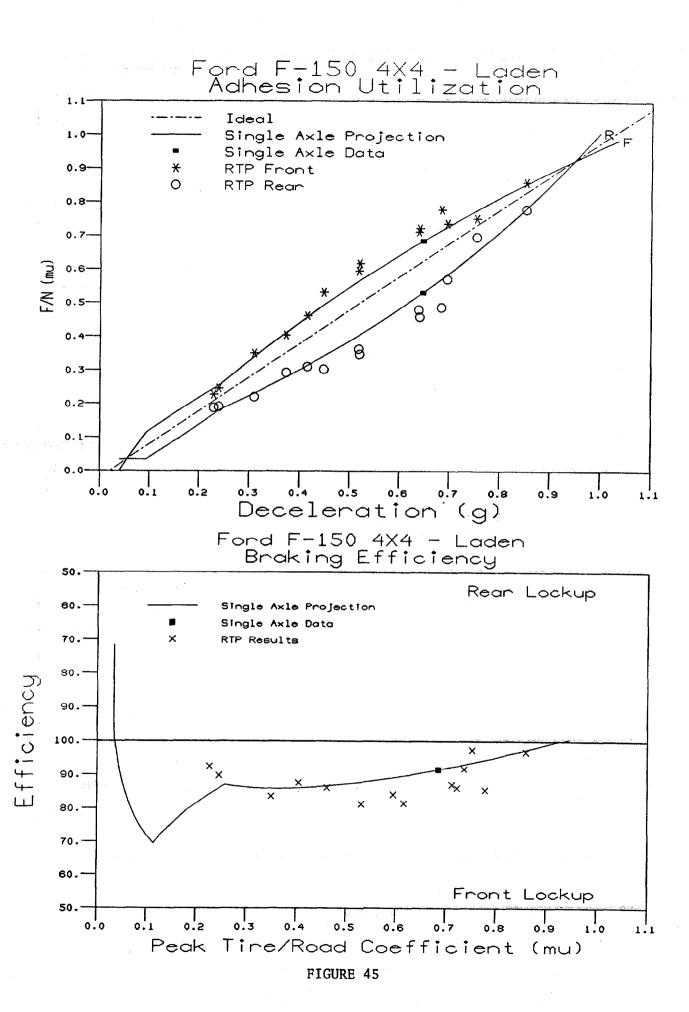
The results of the Ford F-150 4X4 brake balance tests are shown in Figures 45 and 46. In the laden condition, the vehicle is front brake biased up to a peak mu value of around 1.0. The single axle and RTP tests agree reasonably well. In the unladen condition, the vehicle is nearly ideally balanced in the range of peak mu's from 0.25 to 0.5. At higher peak mu values, the single axle predictions show the vehicle to be rear brake biased. The RTP tests indicate that the vehicle is front biased to slightly higher values of mu, although it is very near ideal and the agreement between the two procedures is still reasonable good.

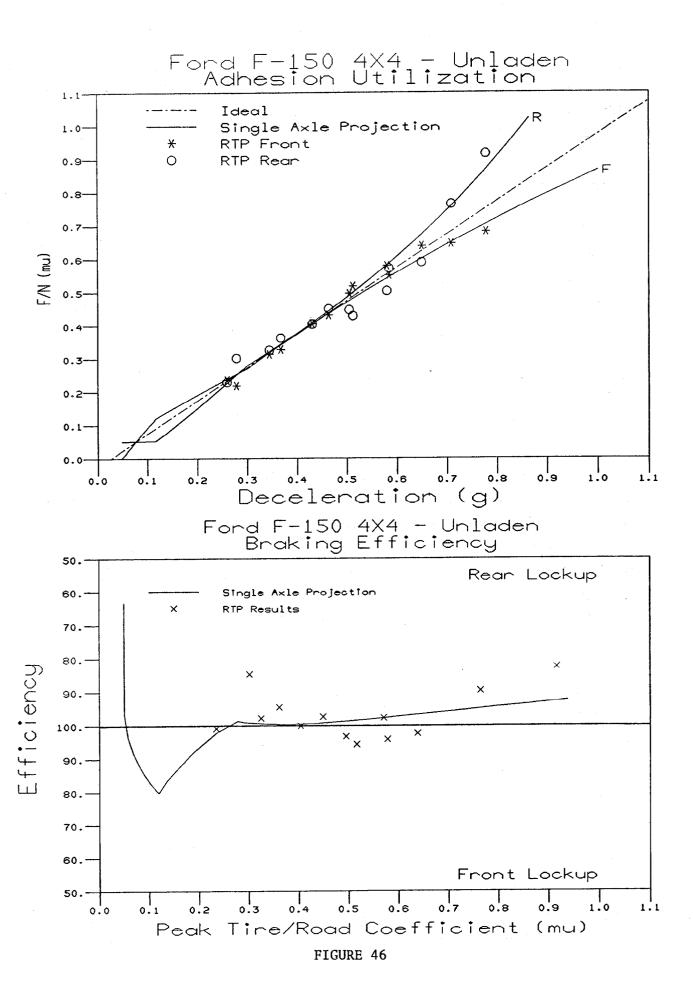










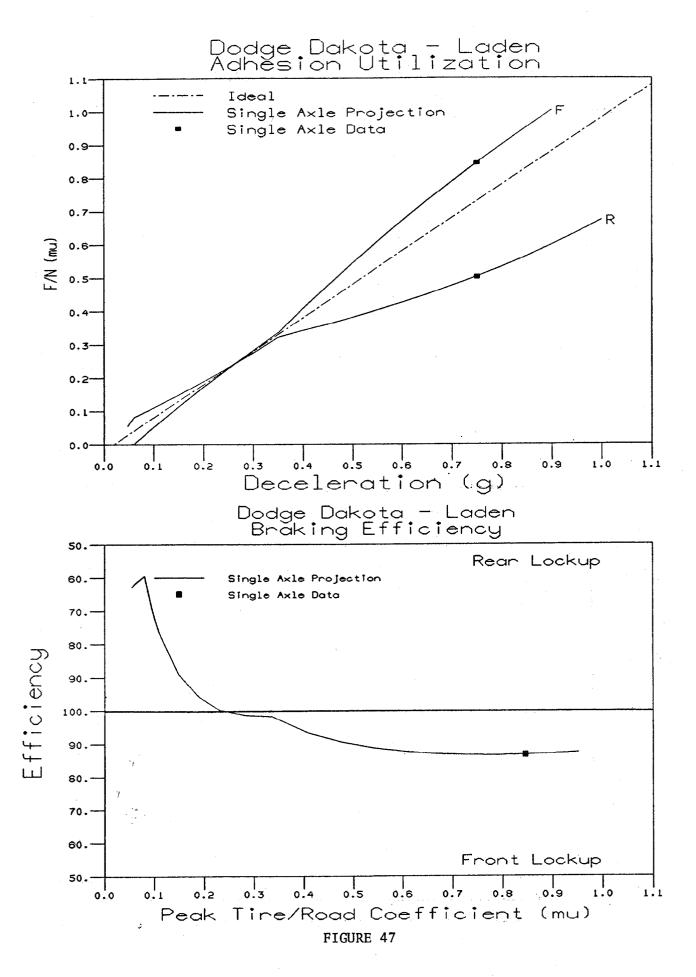


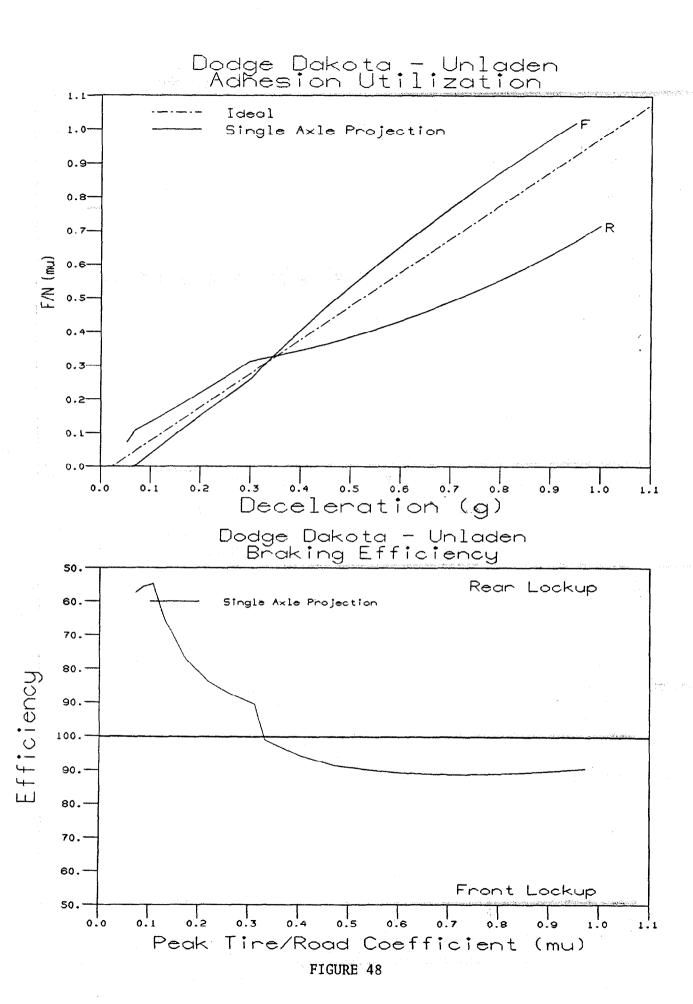
The brake balance results for the Dodge Dakota are shown in Figure 47 in the laden condition and in Figure 48 in the unladen condition. No RTP tests were run on this vehicle. The Dakota, which had a height sensing proportioning valve, was predicted to be front brake biased in both load configurations.

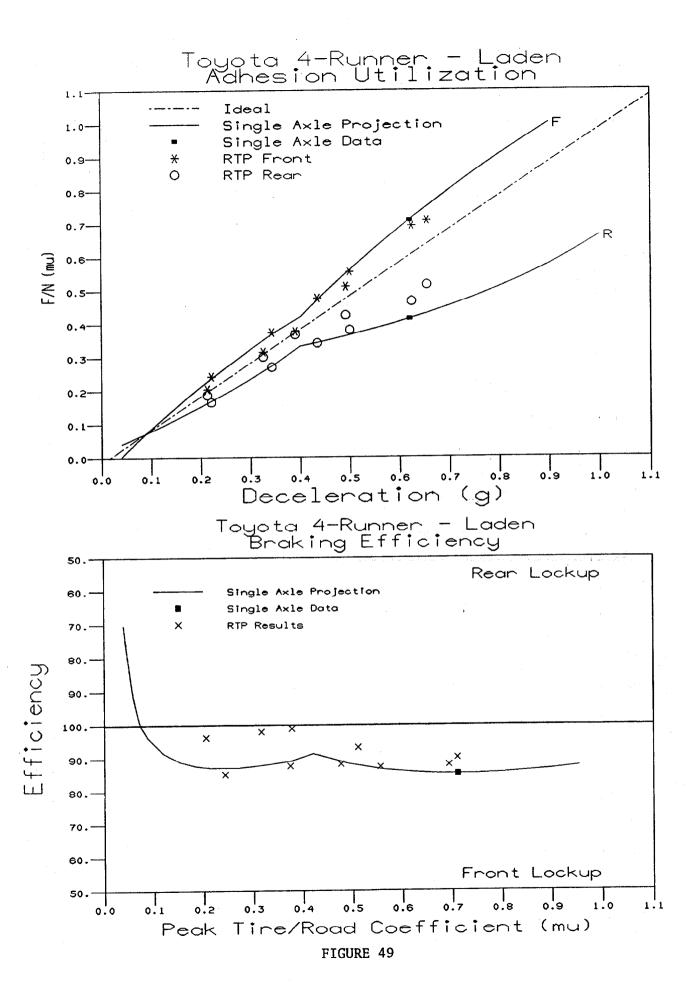
The Toyota 4-Runner had a height sensing proportioning valve. The brake balance results are shown in Figures 49 and 50 for the laden and unladen cases respectively. In the laden condition, the vehicle is basically front brake bised with efficiencies above 80 percent. The single axle and the RTP show good agreement. For the unladen case, the vehicle is front biased except at mu values below approximately 0.35. The rear brake bias at the low mu's is due to the drag of the transmission acting on the rear wheels. Again, the single axle and the RTP show good agreement.

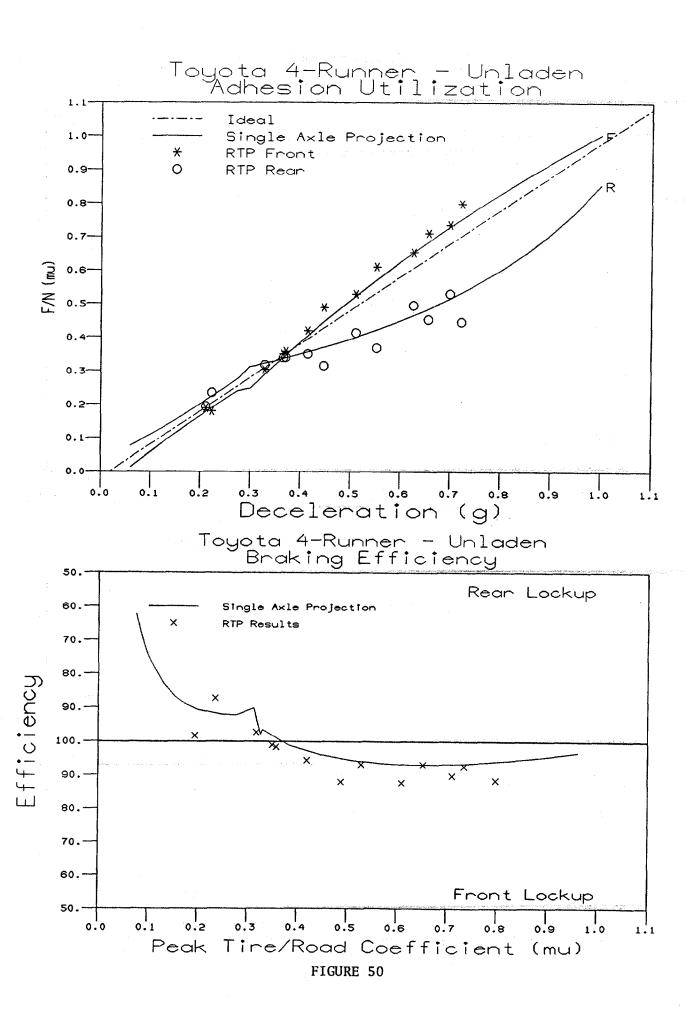
For the Jeep Cherokee, the brake balance results are shown in Figures 51 and 52 for the laden and unladen conditions respectively. In the laden condition, the vehicle is predicted to be front brake biased for the entire range of mu. The RTP tests and the single axle method give good agreement. In the unladen configuration, the tests indicate the vehicle will switch from front brake biased to rear brake biased at approximately 0.75 mu. Again, the RTP and the single axle methods agree quite well.

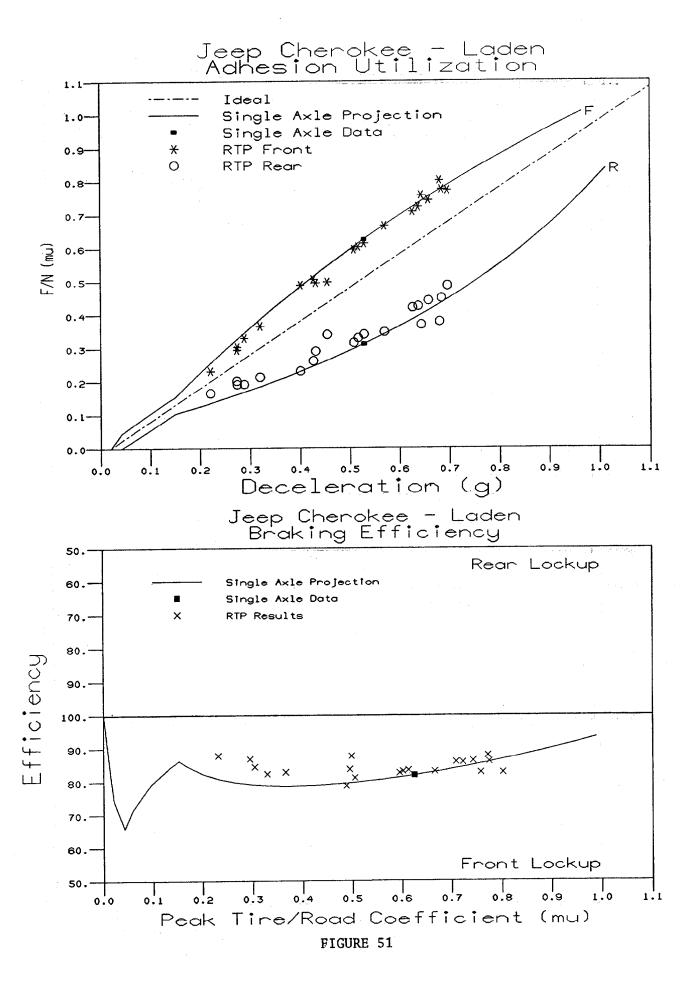
As a means to compare the overall brake balance of the light trucks described in this report to the passenger cars discussed in Reference 5, plots were made showing the braking efficiency of all of the vehicles of each sample on one plot. The plot showing the braking efficiency from the single axle test for 12 of the 13 vehicles in the laden configuration (the Nissan truck is not shown due to the scatter in the results discussed earlier) is shown in Figure 53. The laden brake balance for the passenger cars is shown in Figure 54. All 13 vehicles on the RTP in the laden condition are shown in Figure 55. For the unladen configuration, the single axle results for the light trucks is shown in Figure 56, the passenger car balance is shown in

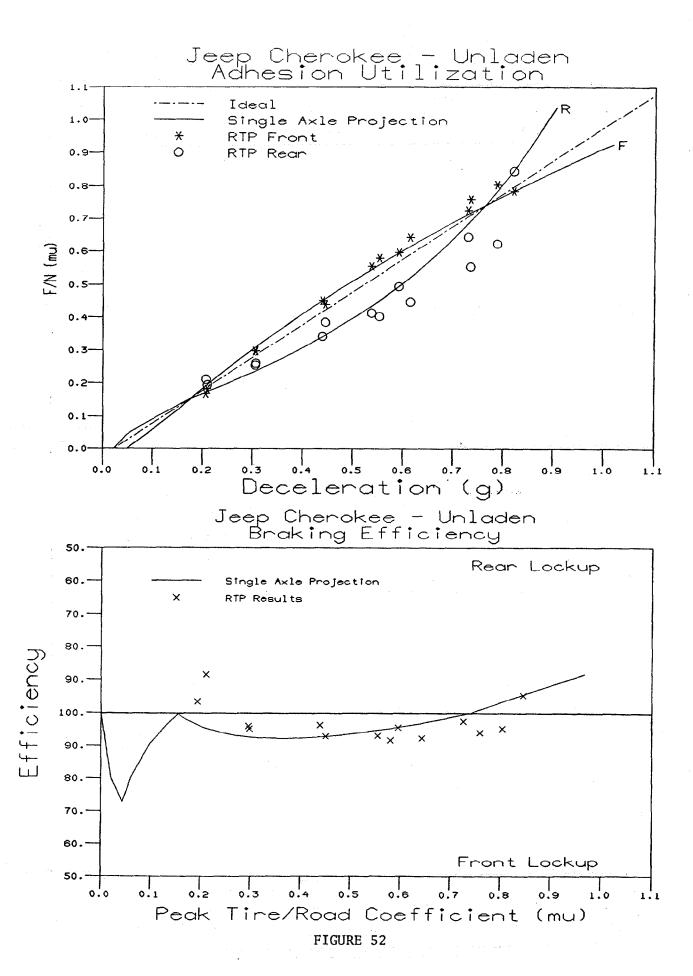


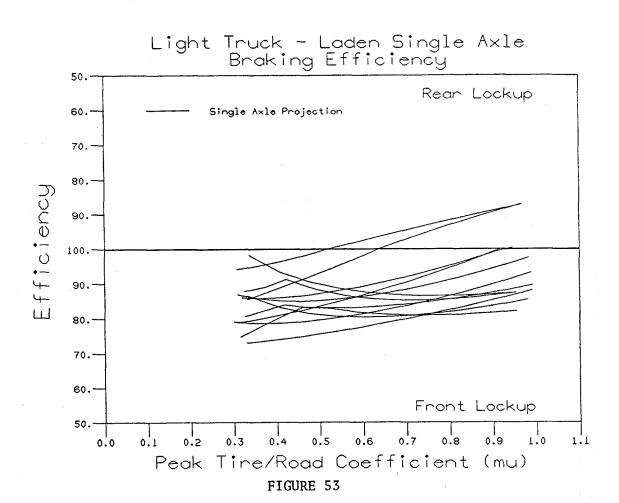


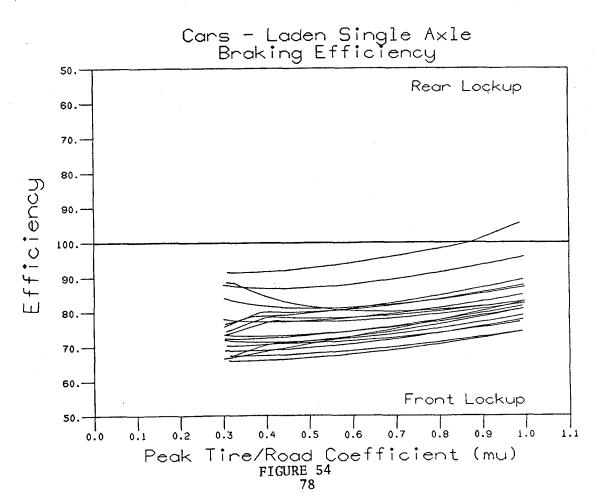


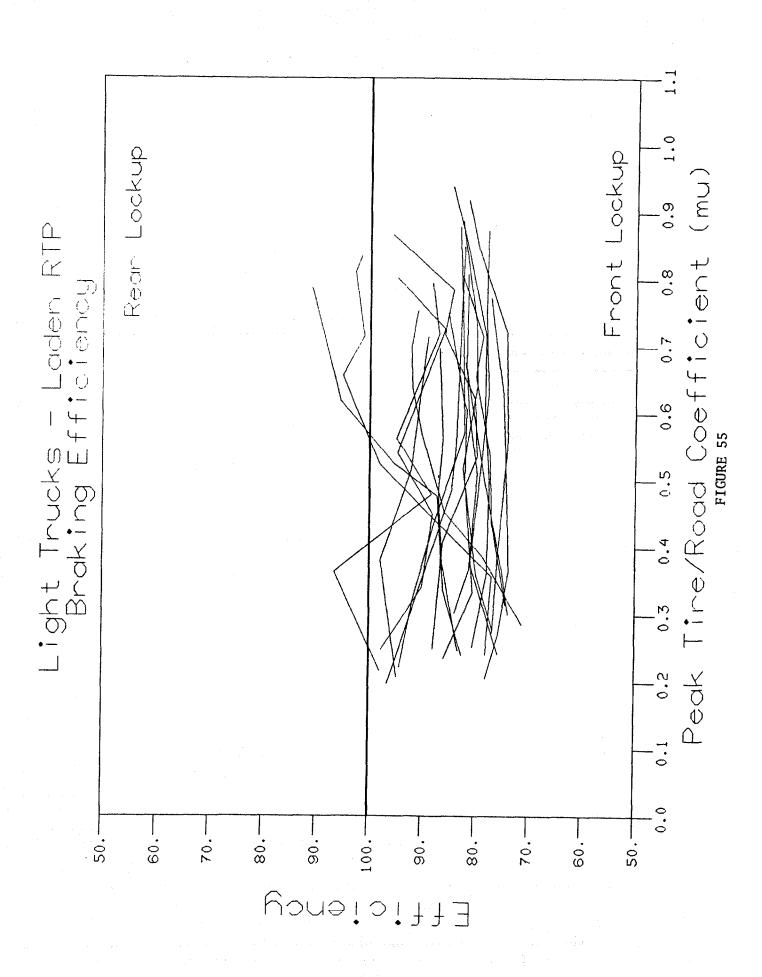




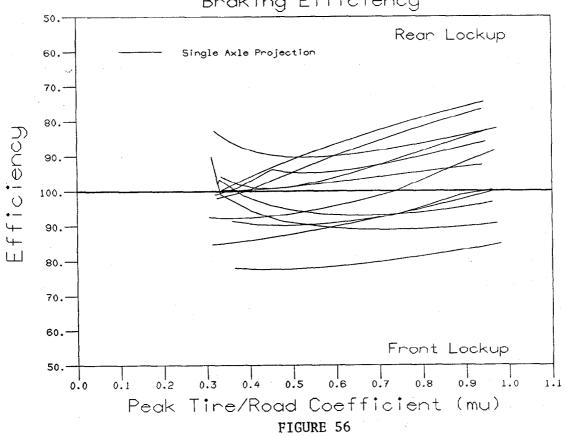








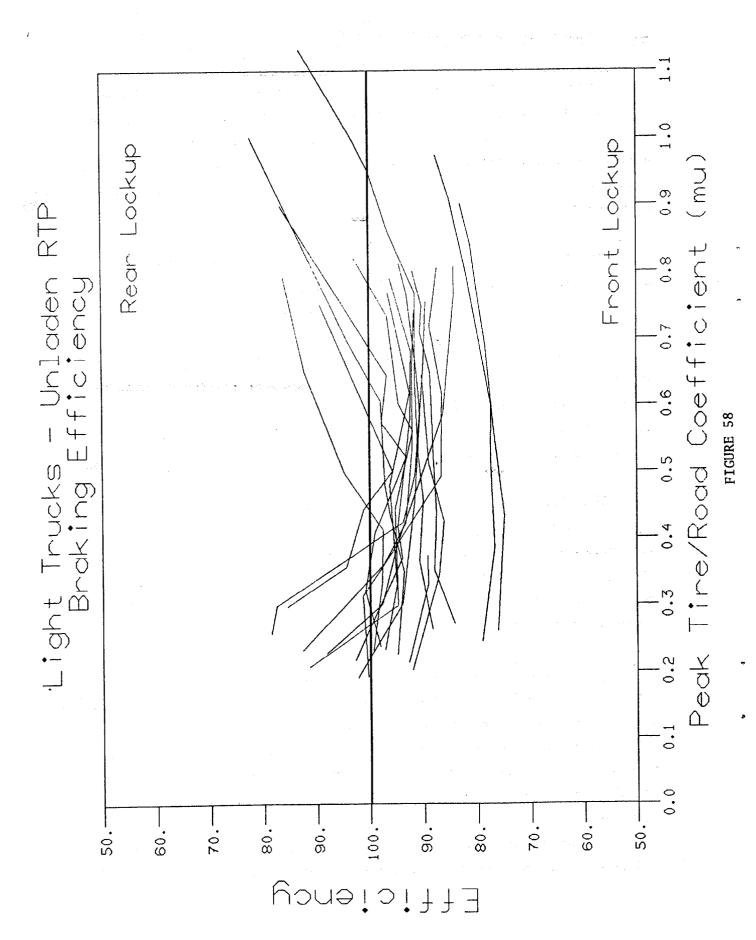




Cars - Unladen Single Axle Braking Efficiency 50.-Rear Lockup 60.-70. 80. Efficiency 90. 100. 90.-80.-70. 60.-Front Lockup 50.-0.1 0.5 1.0 0.6 0.7 0.0 Peak Tire/Road Coefficient (mu) FIGURE 57

Figure 57 and the RTP results are shown in Figure 58. In the laden configuration, the two sets of vehicles have similar braking efficiencies with most of the vehicles being front biased and having efficiencies between 70 percent and 90 percent for mu values above For mu values below 0.3, the pushout pressures of the brakes have the greatest effect on the braking efficiency and tends to show a great deal of scatter in this range. For this reason, the braking efficiency is not shown on these plots for mu values below 0.3. With the vehicles in the unladen condition, the light trucks show a wider range in braking efficiency than do the cars. All of the cars showed front brake bias up to higher values of peak tire/road coefficient of friction, while several of the trucks were rear biased at lower values This difference in performance may be due in part to the of mu. greater differences in laden and unladen weights for trucks than cars and, therefore, greater difficulty in compromising the braking efficiency and brake balance for all load conditions.

On nine of the 13 vehicles, the brake balance was measured on two sets of linings. RTP tests were run on these vehicles after one or both of the axle lock sequences and also during the brake distribution tests. A comparison of the results of these two sets of RTP data shows a combination of test variability and an indication of the variability of brake linings. For each of the nine vehicles, composite plots of all of the RTP tests run on that vehicle showing percent rear braking as a function of deceleration are given in Appendix F. For those vehicles equipped with variable proportioning valves, the percent rear braking versus deceleration will change with the load, Generally, these plots show good agreement between the tests with differences in percent rear brake less than 10 percent. Notable exceptions to this are the Nissan, which showed a great deal of run to run scatter during the testing discussed above, and the Ford Ranger which showed brake conditioning during the tests.



#### 6.0 SUMMARY AND CONCLUSIONS

pier en en en de la compaña en E

Thirteen light trucks were tested to the FMVSS 135 Notice 4 test procedure to investigate the feasibility of using this proposed procedure for these vehicles. The brake balance and center of gravity height of the vehicles was also measured. The vehicles were selected to cover a range of weights up to 8500 lb GVWR with various brake and drive configurations.

In testing the vehicles to the proposed FMVSS 135 test procedure, no problems were found which would suggest the need for a change in the procedure to accommodate this type of vehicle.

Comparing the performance of the light trucks to that of a group of 19 passenger cars tested to the same procedure, the average performance for the two sets of vehicles differed by less than 11 percent on all of the test sections with the light truck performance being better on some sections and the cars better on other sections.

The brake balance of all of the light trucks was measured using a single axle brake distribution procedure and 11 of the vehicles were also measured using a Road Transducer Plate (RTP) facility. For those 11 cases where both methods were used, the agreement between the methods was good for nine of the vehicles with the other two showing unexplained discrepancies.

Brake distribution tests (as well as axle lock sequence tests run in the FMVSS 135 Notice 4 procedure) indicate that most of the light trucks would lock their front wheels first on all surfaces when fully loaded. The braking efficiency ranged from 70 percent front biased to 88 percent rear biased. In the unladen condition, a number of the vehicles would be rear biased on many surfaces. The braking efficiency ranged from 77 percent front biased to 75 percent rear biased. Brake distribution tests on the group of 19 passenger cars indicated that most of these vehicles would be front biased under all

conditions of surface and load with braking efficiencies of 65 percent front biased to 90 percent rear biased.

#### 7.0 ACKNOWLEDGEMENTS

The discussion and views expressed in this report are those of the authors and not necessariloy those of the NHTSA.

The authors wish to thank the following persons at VRTC and TRC for their significant contributions to this report: Dave Hand (TRC) for vehicle preparation and conducting vehicle tests, Doyle McPherson and Dan DeLisle (TRC) for instrumentation support, and Susan Weiser (VRTC) for preparation of the report.

### 8.0 REFERENCES

- Radlinski, R.W. and Flick, M., "Harmonization of Braking Regulations -- Report Number 1, Evaluation of First Proposed Test Procedure for Passenger Cars," National Highway Traffic Safety Administration, Final Report, DOT HS 806 452, May 1983.
- 2. Flick, M. and Radlinski, R.W., "Harmonization of Braking Regulations -- Report Number 2, Evaluation of Second Proposed Test Procedure for Passenger Cars," National Highway Traffic Safety Administration, Final Report, DOT HS 806 751, May 1985.
- 3. Flick, M. and Radlinski, R.W., "Harmonization of Braking Regulations -- Report Number 3, Evaluation of Third Proposed Test Procedure for Passenger Cars," National Highway Traffic Safety Administration, Final Report, DOT HS 806 752, May 1985.

- 4. Flick, M. and Radlinski, R.W., "Harmonization of Braking Regulations -- Report Number 4, Testing to Address Issues Raised During Development of the NPRM," National Highway Traffic Safety Administration, Final Report, DOT HS 806 820, July 1985.
- 5. Flick, M. and Radlinski, R.W., "Harmonization of Braking Regulations -- Report Number 5, Testing for Development and Evaluation of the Supplemental Notice of Proposed Rulemaking on Harmonization of Passenger Car Brake Standards," National Highway Traffic Safety Administration, Final Report, DOT HS 807 127, May 1987.
- 6. Wolanin, W.J. and Baptist, T.A., Road Transducer- Objective Brake Balance Measurement Without Vehicle Instrumentation, SAE 870266 (1987)
- 7. Garrott, W.R., Chrstos, J.P., and Monk, M.W., "Vehicle Inertial Parameters Measured Values and Approximations,"
  Draft SAE Paper, 1988.
- 8. Radlinski, R.W. and Flick, M., "A Vehicle Test Procedure for Determining Adhesion Utilization Properties," SAE Paper #840334.

# APPENDIX A

## Detailed Test Procedure

	*
·	
	• • • • • • • • • • • • • • • • • • •
	8

## S7.1. Burnish.

## S7.1.1. General Information.

Any pretest instrumentation checks are conducted as part of the burnish procedure, including any necessary rechecks after instrumentation repair, replacement or adjustment. Instrumentation check test conditions must be in accordance with the burnish test procedure specified in S7.1.2 and S7.1.3.

### S7.1.2. Vehicle Conditions.

- (a) Vehicle load: GVWR only.
- (b) Transmission position: In gear.

### S7.1.3 Test Conditions and Procedures.

- (a) IBT:  $\leq 100$ °C (212°F).
- (b) Test speed: 80 km/h (49.7 mph).
- (c) Pedal force:  $\leq 500 \text{ N } (112.4 \text{ lb}).$
- (d) Decel rate:  $3 \text{ m/s}^2 (9.9 \text{ fps}^2)$ .
- (e) Wheel lockup: No lockup of any wheel allowed at speeds greater than 15 km/h (9.3 mph).
- (f) Number of runs: 200 stops.

- (g) Interval between runs: The interval from the start of one service brake application to the start of the next is either the time necessary to reduce the IBT to 100°C (212°F) or less, or the distance of 2 km (1.24 miles), whichever occurs first.
- (h) Accelerate to 80 km/h (49.7 mph) after each stop and maintain that speed until making the next stop.
- (i) After burnishing, adjust the brakes as specified in S6.3.4.

### S7.2. Low Coefficient Effectiveness.

#### S7.2.1. General Information.

This test is for vehicles with or without antilock brake systems. This test and that specified in S7.3 for wheel lockup sequence are meant to be a check of the adhesion utilization characteristics of the vehicle.

#### \$7.2.2. Vehicle Conditions.

- (a) Vehicle load: GVWR and LLVW.
- (b) Transmission position: In neutral.

#### S7.2.3. Test Conditions and Procedures.

- (a) IBT:  $\geq 50$ °C (122°F)  $\leq 100$ °C (212°F)  $\leq$  .
- (b) Test speed: 50 km/h (31.1 mph) for each stop.

- (c) Pedal force:  $\leq 500 \text{ N } (112.4 \text{ lbs})$ .
- (d) Wheel lockup: No lockup of any wheel allowed at speeds greater than 15 km/h (9.3 mph).
- (e) Number of runs: 6 stops.
- (f) Test surface: Skid number 20 (wet).
- (g) For each stop, bring the vehicle to test speed and then stop the vehicle in the shortest possible distance under the specified conditions.

## S7.3. Wheel Lockup Sequence.

### S7.3.1. General Information.

- (a) The purpose of this test is to ensure that lockup of both front wheels occurs simultaneously or at a lower deceleration rate than the lockup of both rear wheels when tested on road surfaces with skid numbers of 20 and 50.
- (b) A simultaneous lockup of the front and rear wheels refers to the condition when the time interval between the lockup of the last (second) wheel on the rear axle and the last (second) wheel on the front axle is ≤ 0.1 seconds for vehicle speeds ≥ 15 km/h (9.3 mph).

#### S7.3.2. Vehicle Conditions.

- (a) Vehicle load: GVWR and LLVW.
- (b) Transmission position: In neutral.

#### S7.3.3 Test Conditions and Procedures.

- (a) IBT:  $\geq 50^{\circ}\text{C} (122^{\circ}\text{F}) \leq 100^{\circ}\text{C} (212^{\circ}\text{F}) \leq .$
- (b) Test speed: 65 km/h (40.4 mph).
- (c) Initial pedal force: 45 N (10.1 lb)
- (d) Pedal force:
  - (1) Pedal force is applied and controlled by a mechanical brake pedal actuator.
  - (2) Pedal force must reach its full application level within 1/2 second and be held within  $\pm$  4.5 N (1.0 lb).
  - (3) Pedal force is increased in predetermined increments until either a simultaneous lockup occurs, or both wheels on one axle and one or no wheels on the second axle lock.
- (e) Wheel lockup: Only wheel lockups above a vehicle speed of 15 km/h (9.3 mph) are considered.
- (f) Test surface: This test is conducted first on a surface with a skid number of 20 (wet) and then on a surface with a skid number of 50 (wet).
- (g) Data to be recorded. The following six channels of analog information must be automatically recorded in phase continuously throughout each test run in such a way that values of the six variables can be cross referenced in real time:
  - (1) Vehicle speed.
  - (2) Brake pedal force.

- (3) Angular velocity at each wheel.
- (h) If a failure occurs, the operating conditions at failure are specified in terms of vehicle speed at rear lockup and the time intervals between wheels which lock.
- (i) The test is conducted according to the following steps:
  - (1) Initial pedal force for the first stop is:
    - (i) 45 N (10 lb) on the skid number 20 surface.
    - (ii) 90 N (20 lb) on the skid number 50 surface.
  - (2) Make one constant pedal force stop from 65 km/h (40.4 mph).
  - (3) Increase the pedal force by 45 N (10 lb) and repeat step 2.
  - (4) Repeat steps 2 and 3 as long as the result achieved for each stop is one or no wheels locking on each axle.
  - (5) As steps 2 and 3 are repeated, if both wheels on the front axle and one or no wheels on the rear axle lock, do not repeat steps 2 and 3 beyond this point (pedal force) of front axle lockup. Make two more stops at the same pedal force level. At this point the lockup sequence has been determined and the test is complete.
  - (6) As steps 2 and 3 are repeated, if both wheels on the rear axle and one or no wheels on the front axle lock, make two more stops at the same pedal force level and:
    - (i) If at least one of these two additional stops yields the same result as the first stop, then the

lockup sequence has been determined and the test is complete.

- (ii) If the results of both of these additional stops is different from that obtained for the first stop, increase the pedal force by 10 N (2.2 lb) and make three more stops. Continue this process until at least two of the three stops result in one of the following:
  - (A) Both wheels on the rear axle and one or no wheels on the front axle lock, or
  - (B) All four wheels lock.
- (iii) When either of the conditions described in Paragraphs (i)(6)(ii)(A) or (i)(6)(ii)(B) of this section occurs, the lockup sequence has been determined and the test is complete.
- (7) As steps 2 and 3 are repeated, if all four wheels lock, reduce the pedal force by 20 N (4.5 lb) and make one stop.
  - (i) If both wheels on the front axle and one or no wheels on the rear axle lock, or both wheels on the rear axle and one or no wheels on the front axle lock, make two additional stops. If at least one of the two additional stops does not result in the same lockup sequence as the first stop, increase the pedal force by 10 N (2.2 lb) and make three stops. At this point the lockup sequence has been determined and the test is complete.
  - (ii) If one or no wheels on each axle lock, increase the pedal force level in increments of  $10\ N$  (2.2

- lb) and make one stop at each new pedal force
  level until either of the following occurs:
- (A) Both wheels on the front axle and one or no wheels on the rear axle lock, or
- (B) Both wheels on the rear axle and one or no wheels on the front axle lock.
- (iii) When either of the conditions described in Paragraphs (i)(7)(ii)(A) or (i)(7)(ii)(B) of this section occurs, make two additional stops at that pedal force level. If at least one of the two additional stops results in the same lockup sequence as the first stop at that pedal force level, the lockup sequence has been determined and the test is complete.

#### S7.4. Cold Effectiveness.

#### S7.4.1. Vehicle Conditions.

- (a) Vehicle load: GVWR and LLVW.
- (b) Transmission position: In neutral.

## S7.4.2. Test Conditions and Procedures.

- (a) IBT:  $\geq 50^{\circ}\text{C} (122^{\circ}\text{F}) \leq 100^{\circ}\text{C} (212^{\circ}\text{F}) \leq .$
- (b) Test speed: 100 km/h (62.1 mph).
- (c) Pedal force:  $\geq$  65 N (14.6 lb)  $\leq$  500 N (112.4 lb).

- (d) Wheel lockup: No lockup of any wheel allowed at speeds greater than 15 km/h (9.3 mph).
- (e) Number of runs: 6 stops.
- (f) Test surface: Skid number 81 (dry).
- (g) For each stop, bring the vehicle to test speed and then stop the vehicle in the shortest possible distance under the specified conditions.

### S7.5. High Speed Effectiveness.

#### S7.5.1. Vehicle Conditions.

- (a) Vehicle load: GVWR and LLVW.
- (b) Transmission position: In gear.

### S7.5.2. Test Conditions and Procedures.

- (a) IBT:  $\geq 50$ °C (122°F)  $\leq 100$ °C (212°F)  $\leq$ .
- (b) Test speed: 80% of vehicle masimum speed.
- (c) Pedal force:  $\geq 65 \text{ N} (14.6 \text{ lb}) \leq 500 \text{ N} (112.4 \text{ lb})$ .
- (d) Wheel lockup: No lockup of any wheel allowed at speeds greater than 15 km/h (9.3 mph).
- (e) Number of runs: 6 stops.
- (f) Test surface: Skid number 81 (dry).

#### S7.6. Partial Failure - Stops With Engine Off.

#### S7.6.1. General Information.

This test is for vehicles equipped with one or more brake power units or brake power assist units.

#### S7.6.2. Vehicle Conditions.

- (a) Vehicle load: GVWR only.
- (b) Transmission position: In neutral.

#### S7.6.3. Test Conditions and Procedures.

- (a) IBT:  $\geq 50$ °C (122°F)  $\leq 100$ °C (212°F)  $\leq$  .
- (b) Test speed: 100 km/h (62.1 mph).
- (c) Pedal force:  $\geq$  65 N (14.6 lb)  $\leq$  500 N (112.4 lb).
- (d) Wheel lockup: No lockup of any wheel allowed at speeds greater than 15 km/h (9.3 mph).
- (e) Number of runs: 6 stops.
- (f) Test surface: Skid number 81 (dry).
- (g) All system reservoirs (brake power and/or power assist units are fully charged and the vehicle's engine off (not running) at the beginning of each stop.

#### S7.7. Antilock Failure.

#### S7.7.1. Vehicle Conditions.

- (a) Vehicle load: GVWR and LLVW.
- (b) Transmission position: In neutral.

#### S7.7.2. Test Conditions and Procedures.

- (a) IBT:  $\geq 50^{\circ}\text{C} (122^{\circ}\text{F}) \leq 100^{\circ}\text{C} (212^{\circ}\text{F}) \leq .$
- (b) Test speed: 100 km/h (62.1 mph).
- (c) Pedal force:  $\geq 65 \text{ N } (14.6 \text{ lb}) \leq 500 \text{ N } (112.4 \text{ lb})$ .
- (d) Wheel lockup: No lockup of any wheel allowed at speeds greater than 15 km/h (9.3 mph).
- (e) Number of runs: 6 stops.
- (f) Test surface: Skid number 81 (dry).
- (g) Functional failure:
  - (1) Disconnect the functional power source, or otherwise render the antilock system inoperative.
  - (2) Determine whether the brake system indicator is activated when any functional failure of the antilock system is created.
  - (3) Restore the system to normal at the completion of this test.

- (h) Structural failure: If an antilock system structural failure would result in the same type of structural failure as a hydraulic circuit failure (S7.9), then the test for antilock structural failure is not conducted here. Otherwise, the test for antilock structural failure is conducted.
- (i) If more than one antilock brake subsystem is provided, then repeat test for each subsystem.

#### S7.8. Variable Proportioning Valve Failure.

#### S7.8.1. Vehicle Conditions.

- (a) Vehicle load: LLVW and GVWR.
- (b) Transmission position: In neutral.

#### S7.8.2. Test Conditions and Procedures.

- (a) IBT:  $\geq 50^{\circ}\text{C} (122^{\circ}\text{F}) \leq 100^{\circ}\text{C} (212^{\circ}\text{F}) \leq .$
- (b) Test speed: 100 km/h (62.1 mph).
- (c) Pedal force:  $\geq 65 \text{ N} (14.6 \text{ lb}) \leq 500 \text{ N} (112.4 \text{ lb})$ .
- (d) Wheel lockup: No lockup of any wheel allowed at speeds greater than 15 km/h (9.3 mph).
- (e) Number of runs: 6 stops.
- (f) Test surface: Skid number 81 (dry).

#### (g) Functional failure:

- (1) Disconnect the functional power source or disconnect the variable proportioning brake system.
- (2) Determine whether the brake system indicator is activated when any functional failure of the variable proportioning system is created.
- (3) Restore the system to normal at the completion of this test.
- (h) Structural failure: If a variable prportioning valve system structural failure would result in the same type of structural failure as a hydraulic circuit failure (S7.9), then the test for a variable proportioning valve structure failure is not conducted here. Otherwise, the test for a variable proportioning valve structural failure is conducted.
- (i) If more than one variable proportioning brake subsystem is provided, then repeat the test for each subsystem.

#### S7.9. Partial Failure - Hydraulic Circuit Failure.

#### S7.9.1. General Information.

This test is for vehicles manufactured with and without a split service brake system.

#### S7.9.2. Vehicle Conditions.

(a) Vehicle load: LLVW and GVWR.

(b) Transmission position: In neutral.

#### S7.9.3. Test Conditions and Procedures.

- (a) IBT:  $\geq 50^{\circ}$ C (122°F)  $\leq 100^{\circ}$ C (212°F)  $\leq$ .
- (b) Test speed: 100 km/h (62.1 mph).
- (c) Pedal force:  $\geq 65 \text{ N } (14.6 \text{ lb}) \leq 500 \text{ N } (112.4 \text{ lb})$ .
- (d) Wheel lockup: No lockup of any wheel allowed at speeds greater than 15 km/h (9.3 mph).
- (e) Alter the service brake system to produce any one rupture or leakage type of failure, other than a structural failure of a housing that is common to two or more subsystems.
- (f) Determine the control force, pressure level, or fluid level (as appropriate for the indicator being tested) necessary to activate the brake warning indicator.
- (g) Number of runs: After the brake warning indicator has been activated, make the following stops depending on the type of brake system:
  - (1) 4 stops for a split service brake system.
  - (2) 10 consecutive stops for a non-split service brake system.
- (h) Each stop is made by a continuous application of the service brake control.
- (i) Restore the service brake system to normal at the completion of this test.

(j) Repeat the entire sequence for each of the other systems.

## S7.10. Partial Failure - Power Brake Unit or Brake Power Assist Unit Inoperative (System Depleted).

#### S7.10.1 General Information.

This test is for vehicles equipped with one or more brake power units or brake power assist units.

#### S7.10.2. Vehicle Conditions.

- (a) Vehicle load: GVWR only.
- (b) Transmission position: In neutral.

#### S7.10.3. Test Conditions and Procedures.

- (a) IBT:  $\geq 50^{\circ}\text{C} (122^{\circ}\text{F}) \leq 100^{\circ}\text{C} (212^{\circ}\text{F}) \leq .$
- (b) Test speed: 100 km/h (62.1 mph).
- (c) Pedal force:  $\geq 65 \text{ N } (14.6 \text{ lb}) \leq 500 \text{ N } (112.4 \text{ lb}).$
- (d) Wheel lockup: No lockup of any wheel allowed at speeds greater than 15 km/h (9.3 mph).
- (e) Number of runs: 6 stops.
- (f) Test surface: Skid number 81 (dry).

- (g) Disconnect the primary source of power for one brake power assist unit or brake power unit, or one of the brake power unit or brake power assist unit subsystems if two or more subsystems are provided.
- (h) If the brake power unit or power assist unit operates in conjunction with a backup system and the backup system is automatically activated in the event of a primary power service failure, the backup system is operative during this test.
- (i) Exhaust any residual brake power reserve capability of the disconnected system.
- (j) Make each of the 6 stops by a continuous application of the service brake control.
- (k) Restore the system to normal at completion of this test.
  - (1) For vehicles equipped with more than one brake power unit or brake power assist unit, conduct tests for each in turn.

#### S7.11. Parking Brake - Static Test.

#### S7.11.1. Vehicle Conditions.

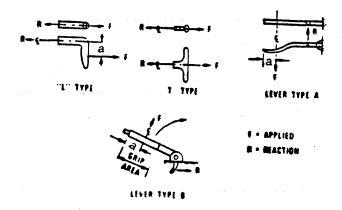
- (a) Vehicle load: GVWR only.
- (b) Transmission position: In neutral.
- (c) Parking brake burnish:

- (1) For vehicles with parking brake systems not utilizing the service friction elements, the friction elements of such a system are burnished prior to the parking brake test according to the published recommendations furnished to the purchaser by the manufacturer.
- (2) If no recommendations are furnished, the vehicle's parking brake system is tested in an unburnished condition.

#### S7.11.2. Test Conditions and Procedures.

- (a) IBT:  $\leq 100^{\circ}\text{C} (212^{\circ}\text{F})$ .
- (b) Parking brake control force: Hand control ≤ 400 N (89.9 lb); foot control ≤ 500 N (112.4 lb).
- (c) Hand force measurement locations: The force required for actuation of a hand-operated brake system is measured at the center of the actuation lever, as illustrated in Figure 2.
- (d) Parking brake applications: 1 apply and 2 reapply if necessary.
- (e) Test surface gradient: 20% grade.
- (f) Drive the vehicle onto the grade with the longitudinal axis of the vehicle in the direction of the slope of the grade.
- (g) Stop the vehicle and hold it stationary by applying the service brake control and place the transmission in neutral.
- (h) With the service brake applied sufficiently to just keep the vehicle from rolling, apply the parking brake as specified in S7.11.2(i) or S7.11.2(j).

# Location for Measuring Brake Application Force (Hand Brake)



Dimension a = 40 mm (1.57 in)

FIGURE 2

- (i) The parking brake system is actuated by a single application not exceeding the limits specified in S7.11.2(b).
- (j) In the case of a parking brake system that does not allow application of the specified force in a single application, a series of applications may be made to achieve the specified force.
- (k) Following the application of the parking brakes, release all force on the service brake control and, if the vehicle remains stationary, start the measurement of time.
- (1) If the vehicle does not remain stationary, reapplication of a force to the parking brake control at the level specified in S7.11.2(b) as appropriate for the vehicle being tested (without release of the ratcheting or other holding mechanism of the parking brake) is used up to two times to attain a stationary position.
- (m) Verify the operation of the parking brake application indicator.
- (n) Following observation of the vehicle in a stationary condition for the specified time in one direction, repeat the same test procedure with the vehicle orientation in the opposite direction on the same grade.

#### S7.12. Parking Brake - Dynamic Test.

#### S7.12.1. Vehicle Conditions.

- (a) Vehicle load: GVWR only.
- (b) Transmission position: In neutral.

(c) Parking brake burnish: No additional burnishing is allowed beyond that specified in S7.11.1(c).

#### S7.12.2. Test Conditions and Procedures.

- (a) IBT:  $\leq 100^{\circ}C$  (212°F).
- (b) Parking brake control force: Hand control  $\leq$  400 N (89.9 lb); foot control  $\leq$  500 N (112.4 lb).
- (c) Hand force measurement locations: The force required for actuation of a hand-operated brake system is measured at the center of the hand grip area or at a distance of 40 mm (1.57 in) from the end of the actuation lever, as illustrated in Figure 2.
- (d), Number of runs: 2 stops.
- (e) Test speed: 60 km/h (37.3 mph).
- (f) Wheel lockup: no lockup of any wheel allowed at speeds greater than 15 km/h (9.3 mph).
- (g) With the vehicle at a test speed of 60 km/h (37.3 mph), apply the parking brake as specified in S7.12.2(h) or S7.12.2(i).
- (h) The parking brake system is actuated by a single application not exceeding the limit specified in S7.12.2(b).
- (i) In the case of a parking brake system that does not allow application of the specified force in a single application, a series of applications may be made to achieve the specified force.

#### S7.13. Heating Snubs.

#### S7.13.1. General Information.

The purpose of the snubs is to heat up the brakes in preparation for the hot performance test which follows immediately.

#### S7.13.1. Vehicle Conditions.

- (a) Vehicle load: GVWR only.
- (b) Transmission position: In gear.

#### S7.13.2. Test Conditions and Procedures.

#### (a) IBT:

- (1) Establish an IBT before the first brake application (snub) of  $\geq$  55°C (131°F)  $\leq$  65°C (149°F).
- (2) IBT's before subsequent snubs are those occurring at the distance intervals.
- (b) Number of snubs: 15.
- (c) Test speeds: The initial speed for each snub is 120 km/h (74.6 mph) or 80% of Vmax, whichever is slower. Each snub is termianted at one-half the initial speed.
- (d) Deceleration rate:
  - (1) Maintain a constant deceleration rate of 3.0 m/s $^2$  (9.8 fps $^2$ ).

- (2) Attain the specified deceleration within one second and maintain it for the remainder of the snub.
- (e) Pedal force:  $\leq 500 \text{ N } (112.4 \text{ lb})$ .
- (f) Time interval: Maintain an interval of 40 seconds between the start of brake applications (snubs).
- (g) Accelerate as rapidly as possible to the initial test speed immediately after each snub.
- (h) Immediately after the 15th snub, accelerate to  $100 \, \text{km/h}$  (62.1 mph) and commence the hot performance test.

#### S7.14. Hot Performance.

#### S7.14.1. General Information.

The hot performance test is conducted immediately after completion of the 15th heating snub.

#### S7.14.2. Vehicle Conditions.

- (a) Vehicle load: GVWR only.
- (b) Transmission position: In neutral.

#### S7.14.3. Test Conditions and Procedures.

- (a) IBT: Temperature achieved at completion of heating snubs.
- (b) Test speed: 100 km/h (62.1 mph).

- (c) Pedal force: The pedal force is not greater than the average pedal force achieved during the shortest GVWR cold effectiveness stop.
- (d) Wheel lockup: no lockup of any wheel allowed at speeds greater than 15 km/h (9.3 mph).
- (e) Number of runs: 2 stops.
- (f) Immediately after the 15th heating snub, accelerate to 100 km/h (62.1 mph) and commence the 1st stop of the hot performance test.
- (g) If the vehicle is incapable of attaining 100 km/h, it is tested at the same speed used for the GVWR cold effectiveness test.
- (h) Immediately after completion of the first hot performance stop, accelerate as rapidly as possible to the specified test speed and conduct the second hot performance stop.
- (i) Immediately after completion of second hot performance stop, drive 1.5 km (0.98 mi) at 50 km/h (31.1 mph) before the first cooling stop.

#### S7.15. Braking Cooling Stops.

#### S7.15.1. General Information.

The cooling stops are conducted immediately after completion of the hot performance test.

#### S7.15.2. Vehicle Conditions.

- (a) Vehicle load: GVWR only.
- (b) Transmission position: In gear.

#### S7.15.3. Test Conditions and Procedures.

- (a) IBT: Temperature achieved at completion of hot performance.
- (b) Test speed: 50 km/h (31.1 mph).
- (c) Pedal force:  $\leq 500 \text{ N } (112.4 \text{ lb}).$
- (d) Deceleration rate: maintain constant deceleration rate of  $3.0 \text{ m/s}^2 \text{ (9.8 fps}^2\text{)}$ .
- (e) Wheel lockup: No lockup of any wheel allowed at speeds greater than 15 km/h (9.3 mph).
- (f) Number of runs: 4 stops.
- (g) Immediately after the hot performance stops, drive 1.5 km (0.93 mi) at 50 km/h (31.1 mph) before the first cooling stop.
- (h) For the first through the third cooling stops:
  - (1) After each stop, immediately accelerate at the maximum rate to 50 km/h (31.1 mph).
  - (2) Maintain that speed until beginning the next stop at a distance of 1.5 km (0.93 mi) from the beginning of the previous stop.
- (i) For the fourth cooling stop:

- (1) Immediately after the fourth stop, accelerate at the maximum rate to 100 km/h (62.1 mph).
- (2) Maintain that speed until beginning the recovery performance stops at a distance of 1.5 km (0.93 mi) after the beginning fo the fourth cooling stop.

#### S7.15. Recovery Performance.

#### S7.16.1. General Information.

The recovery performance test is conducted immediately after completion of the brake cooling stops.

#### S7.16.2. Vehicle Conditions.

- (a) Vehicle load: GVWR only.
- (b) Transmission position: In neutral.

#### S7.16.3. Test Conditions and Procedures.

- (a) IBT: Temperature achieved at completion of cooling stops.
- (b) Test speed: 100 km/h (62.1 mph).
- (c) Pedal force: Pedal force is not greater than the average pedal force of the shortest GVWR cold effectiveness.
- (d) Wheel lockup: No lockup of any wheel allowed at speeds greater than 15 km/h (9.3 mph).

- (e) Number of runs: 2 stops.
- (f) Immediately after the fourth cooling stop, accelerate at the maximum rate to 100 km/h (62.1 mph).
- (g) Maintain that speed until beginning the first recovery performance stop at a distance of 1.5 km (0.93 mi) after the beginning of the fourth cooling stop.
- (h) If the vehicle is incapable of attaining 100 km/h, it is tested at the same speed used for the GVWR cold effectiveness test.
- (i) Immediately after completion of the first recovery performance stop, accelerate as rapidly as possible to the specified test speed and conduct the second recovery performance stop.

#### S7.17. Final Inspection.

#### Inspect:

- (a) The service brake system for detachment or fracture of any components, such as brake springs and brake shoes or disc pad facings.
- (b) The friction surface of the brake, the master cylinder or brake power unit reservoir cover, and seal and filler openings, for leakage of brake fluid or lubricant.
- (c) The master cylinder or brake power unit reservoir for compliance with the volume and labeling requirements of S5.4.2 and S5.4.3. In determining the fully applied worn condition, assume that the lining is worn to (1) rivet or bolt heads on riveted or bolted linings or (2) within 0.8 mm

- (1.32 in) of shoe or pad mounting surface on bonded linings or (3) the limit recommended by the manufacturer, whichever is larger relative to the total possible shoe or pad movement. Drums or rotors are assumed to be at nominal design drum diameter or rotor thickness. Linings are assumed adjusted for normal operating clearance in the released position.
- (d) The brake system indicators, for compliance with operation in various key positions, lens color, labeling, and location, in accordance with S5.5.

#### APPENDIX B

## Vehicle Information and Summary Data Sheets

## Test Vehicle Information/Specifications

Vehicle Type: Van	Wheelbase: <u>2</u>	845	mm
Manufacturer: Dodge	Model: <u>Carav</u>	an	
VIN: 2B4FK41K5JR521196	Production Da	te: <u>9/87</u>	
GVWR: 2200 kg GAWR - Frt:	1100	kg Rear: <u>1</u> 1	.11kg
Engine-Type: Gas	No. Cy1:	4 Di	sp: 2.5 1
Transmission-Type: Automatic Fwd S	pds: <u>3</u>	_ Drive Axle	: Rear
Tires-Mfgr: Goodyear	Style: <u>Ra</u>	dial	
Size: <u>P195/75 R14</u> Test	t Press - Frt:	<u>2.4</u> bar Re	ear: 2.4 bar
Grade <u>LF</u>	<u>RF</u>	LR	RR
Treadwear: 280		280	
Traction: A	_A	Α	_ <u>A</u>
Temperature: B	B	В	<u>B</u>
Serial Number: NA	<u>NA</u>	NA	NA
Estimated Mileage: 1500	1500	1500	1500
Brake System - Booster-Type: Vacuum			
Parking Brake-Type: R	ear Shoes	Contro	ol: <u>Foot</u>
Prop. Valve-Type: <u>Heig</u>	<u>ht Sensing</u> Split	Point: <u>Varia</u>	able Ratio: .278
Plumbing Split Type:	Diagonal	<u> </u>	-
	Front		Rear
Brake Type:	Disc	Drum	:
Drum/Rotor Size:		mm	mm
Lining Size:		mm	mm
Lining Codes:	VX 5D EE	BX_P	M FE / BX RY FE
Lining Attachment:	Rivet	Rive	t
Wheel Cyl/Piston dia:_			
Weights - Curb Weight - Frt:	893 kg Rear:	647 kg T	otal: <u>1540</u> kg
Test Weight LLVW - Frt:	998kg Rear:	714 kg T	otal: <u>1712</u> kg
Test Weight GVW - Frt: 1	<u> 107       kg</u> Rear: <u> </u>	<u>1107                                   </u>	otal: <u>2214</u> kg
Center of Gravity -			
Height Above Ground - Curb:_	683 mm LLVW:	<u>692</u> mm	GVW: 667 mr
Aft of Front Axle - Curb:_	1195 mm LLVW:	<u>1186</u> mm	GVW: 1422 mr
Moments of Inertia (ft-lb/sec <sup>2</sup> ) <u>CUR</u>	B LLVW	<u>*</u>	GVW
Roll (About X Axis): 61			782.5
Pitch (About Y Axis): 230			2898.5
Yaw (About Z Axis):	•		2935.5
Vehicle Maximum Speed: 142			m/h
Comments:			

## Summary of Performance to Modified Harmonized Brake Test Procedure

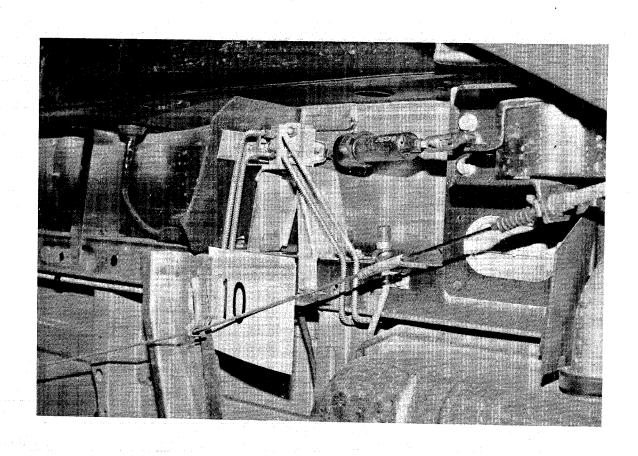
Vehicle <u>Dodge Caravan</u> Tested by <u>VRTC</u>

Date Test Completed <u>10/21/87</u> 80% V<sub>max</sub> = <u>113</u> km/h

Service Bi	ake and Par			ts_(Kesult	s for "b				
	<u>Laden</u> 100 km/h 80			V <sub>max</sub>	100		Unladen		
	in ne	•	in	gear	100 km/h in_neutral		80% V <sub>max</sub> in gear		
Full Service Braking	SD (m)	PF <sub>max</sub>	SD (m)	PF <sub>max</sub>	SD	PF max	SD	PF <sub>max</sub>	
Engine On:	61	427	78	<u>498</u>	<u>(m)</u> 51	<u>(N)</u> 445	<u>(m)</u> 67	(14)	
Engine Off:	58	485	NA					400	
Post Fade:	57	<del>489</del>		NA NA	NA NA	NA .	NA NA	<u>NA</u>	
Partial Failures (Engine On):		409	NA	<u>NA</u>	NA_	NA	<u>NA</u>	<u>NA</u>	
Circuit #1 Failed:	113	4.00	3T A	37.4	100		***		
Circuit #2 Failed:	<u> </u>	480	NA NA	NA_NA	108	454	NA_	NA NA	
Anti-lock Failed:		485	NA_	<u>NA</u>	122	325	<u>NA</u>	<u>NA</u>	
	NA	<u>NA</u>	<u>NA</u>	<u>NA</u>	NA_	<u>NA</u>	<u>NA</u>	<u>NA</u>	
Variable Prop. Valve Failed		<u>NA</u>	<u>NA</u>	<u>NA</u>	61	<u>NA</u>	NA_	NA_	
Power Unit/Assist Failed:	161	494	<u>NA</u>	NA	NA	NA	NA_	NA	
Adhesion Utilization	Parking	Brake Tes	ts		Fade an	d Recover	y Series		
Low Coefficient Effectiveness	20% Grade			Baseline:	Best S	top SD <u>6</u>	l_m Avg	PF <u>258</u>	
SD PF <sub>max</sub> (m) (N)	Control Fo	rce to Ho	1d:	<u>Heating</u> :	Stops 1	-15 PF <sub>max</sub> -	<u>138</u> N		
Laden <u>26</u> <u>196</u>	Uphill _3	<u>65</u> n			Stops 1	-15 Min De	ecel Sus	2.90 m/s	
Unladen25214	Downhill_3	<u>11</u> N		Stop 15 Initial Temp ( C)					
Axle Lock Sequence	Dynamic Te	st			LF <u>396</u>	RF <u>440</u>	LR 168	RR <u>_ 116</u>	
Balanced Front Rear 20 SN:	Results for	r Best St	op:	<pre>Hot Stop:</pre>	SD <u>80</u>	m PF <sub>max</sub> -	<u>249</u> N		
Unladen X 50 SN:	SD72	m		Recovery:	Stops	1-4 PF <sub>max</sub> -	<u>107</u> N		
Laden X	Final Dece	1_3.96	m/s <sup>2</sup>	Recovery S	Ston: Si	D 66 m I	or 2/40	) N	
UnladenX	PF <sub>max</sub> 391	N		TOO VELY	<u>леор</u> . в	<u> </u>	max 24	LV.	



1987 Dodge Caravan



Dodge Caravan Height Sensing Proportioning Valve

## Test Vehicle Information/Specifications

Vehicle Type: Minivan	Wheelbase:_	2243		_mm
Engine-Type: Gas	No. Cyl:	4	Disp: <u>2.2</u>	1
Tires-Mfgr: Yokohama	Style:	Radial		<del></del>
Size: <u>P195/75 R14</u> Test	Press - Frt:	2.4	bar Rear: <u>2.4</u>	bar
Grade <u>LF</u>	<u>RF</u>	LR	RR	
Treadwear: 220	220	220	220	
Traction: B	В	<u>B</u>	B	
Temperature: B	В	<u>B</u>	<u>B</u>	
Serial Number: <u>LV5217</u> _	LV5217	LV521	7 LV5217	
Estimated Mileage: 150	150	150		
Brake System - Booster-Type: Vacuum				<del> </del>
Parking Brake-Type: <u>Re</u>	ar Brake		Control: <u>Hand</u>	<del>,</del> ,
Prop. Valve-Type: <u>Heigh</u>	t <u>Sensing</u> Spl	lit Point	: <u>Variable</u> Ratio	
Plumbing Split Type: F	ront/Rear			
	Front		<u>Rear</u>	
Brake Type:	Disc		Drum	
Drum/Rotor Size:	255	mm _	254	mm
Lining Size:	114x48x10	mm _	244x50x5	mm
Lining Codes:	AK 3405 FF		B701A FE	· · · · · ·
Lining Attachment:	Bonded		Bonded	
Wheel Cyl/Piston dia:	60.33		20,64	
Weights - Curb Weight - Frt: 8	78kg Rear	: 633	_kg Total:1511	kg
Test Weight LLVW - Frt: 10	84 kg Rear	: 618	_kg Total: <u>1702</u>	kg
Test Weight GVW - Frt: $10$	82kg Rear	: 1074	_kg Total: <u>2156</u>	kg
Center of Gravity -	•			
Height Above Ground - Curb:	684 mm LL	VW: <u>685</u>	mm GVW:712	mm
Aft of Front Axle - Curb:	940 mm LL	VW: <u>814</u>	mm GVW:117	mm
Moments of Inertia (ft-lb/sec <sup>2</sup> ) <u>CURB</u>	<u>L</u>	LVW	GVW	
Roll (About X Axis): 499	,1	635.3	657.5	
Pitch (About Y Axis): 1716				
Yaw (About Z Axis): <u>1777</u>		•		
Vehicle Maximum Speed: 135			km/h	
Comments:				

### Summary of Performance to Modified Harmonized Brake Test Procedure

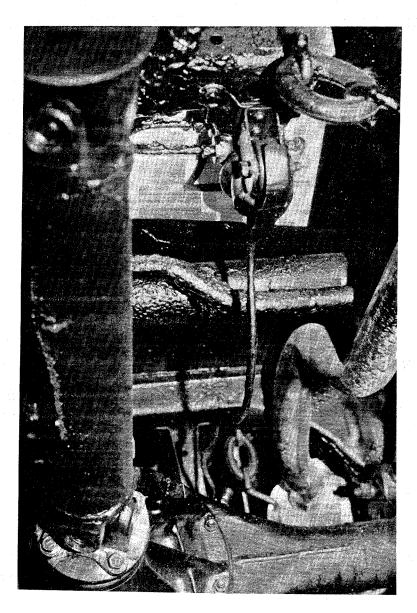
Vehicle Toyota Van Tested by VRTC

Date Test Completed 9-9-87 80% V<sub>max</sub> = 108 km/h

		Lad		<u>'ests (Results for "best" stops)</u> <u>Unladen</u>					
	100 km/h in neutral		80% V <sub>max</sub> in gear		100 km/h in neutral		80% V <sub>max</sub> in gear		
	SD	PFmax	SD	PFmax	SD	PFmax	SD	PFmax	
Full Service Braking	<u>(m)</u>	<u>(N)</u>	(m)	(N)	(m)	(N)	(m)	(N)	
Engine On:	64	<u>427</u> .	72	445	54	<u>276</u>	63	334	
Engine Off:	57	445	NA	<u>NA</u>	<u>NA</u>	<u>NA</u>	<u>N</u> A	NA	
Post Fade:	59	<u>467</u>	NA NA	<u>NA</u>	NA	NA	NA	NA	
<u>Partial Failures (Engine On):</u>									
Circuit #1 Failed:	146	498	<u>NA</u>	NA	156	<u> 187</u>	<u>N</u> A	NA	
Circuit #2 Failed:	70	480	<u>NA</u>	<u>NA</u>	59	316	NA	NA	
Anti-lock Failed:	NA	<u>NA</u>	NA	<u>NA</u>	NA	NA	NA	NA_	
Variable Prop. Valve Failed:	57_	<u>498</u>	<u>NA</u>	<u>NA</u>	58	280	NA	NA	
Power Unit/Assist Failed:	<u> 135</u>	498	NA	NA NA	NA	NA	NA	NA	
Low Coefficient           Effectiveness         SD         PFmax           (m)         (N)           Laden         28         151	20% Grade Control For Uphill 2		ld:	Baseline: Heating:	Stops 1	-15 PF <sub>max</sub> -	<u>120</u> N	PF_249_N 2.90_m/s	
Unladen 24 173	Downhill_2	22_N		Stop 15 Initial Temp ( C)					
Axle Lock Sequence Balanced Front Rear	Dynamic Te	<u>st</u>		LF 432 RF 432 LR 196 RR 190					
20 SN:  Laden X	Results for	r Best Ste	op:	<pre>Hot Stop:</pre>	SD_73	m PF <sub>max</sub> -	<u>245</u> N		
Unladen X 50 SN:	SD <u>58</u>	m		Recovery:	Stops	1-4 PF <sub>max</sub> -	<u>124</u> N		
Laden X	Final Dece	1 <u>2,74</u> r	m/s	Recovery :	Stop: S	D <u>66</u> m 1	PF <sub>may</sub> 23	<u>1</u> N	
UnladenX_	PF <sub>max</sub> 391	N					max		



1987 Toyota Van



Toyota Van Height Sensing Proportioning Valve

## Test Vehicle Information/Specifications

Wheelbase:	3340	mm
Model: <u>Astr</u>	0	
Production D	ate: <u>9/86</u>	
No. Cyl:_	6	Disp: <u>4.3</u> 1
pds:4	Drive Ax	le: <u>Rear</u>
Style: <u>R</u>	adial	
t Press - Frt:_	bar	Rear:bar
<u><b>RF</b></u>	<u>LR</u>	RR
280	280	
_ <u>A</u>	A	<u>A</u>
В	В	<u>B</u>
	The same of the same same same	
800	800	800
	. Come to a substitute and english and	200
Rear Shoes	Cont	rol: Foot
<u>ked</u> Split	Point: 2	95 Ratio: .285
Front/Rear		
Front		Rear
Disc	<u>Dru</u>	ım ·
	mm	mm
	mm	mm
117 FE	241	FG
Rivet		
997 kg Rear:	<u>780</u> kg	Total: <u>1777</u> kg
<u> 1148      kg</u> Rear:_	<u>837</u> kg	Total: 1985 kg
1150 kg Rear:	<u>1225</u> kg	Total: 2375 kg
749 mm LLV	7: <u>749</u> m	nm GVW: <u>805</u> mm
1466 mm LLV	J: <u>1408</u> n	nm GVW: <u>1723</u> mm
RB LL	VW	GVW
NA		NA
		NA .
		NA
		km/h
	Model:AstrProduction DNo. Cyl:Style:RStyle:RStyle:RR	

#### Summary of Performance to Modified Harmonized Brake Test Procedure

Vehicle Chevrolet Astro Tested by VRTC

Date Test Completed 10/14/87 80% V<sub>max</sub> = 130 km/h

		Lad	len					
	100	100 km/h 80% V <sub>max</sub>		t V <sub>max</sub>	100	km/h	80	% V <sub>max</sub>
	<u>in ne</u>	utral	ir	n gear	in ne	utral	in gear	
	SD	PFmax	SD	PFmax	SD	PFmax	SD	PFmax
Full Service Braking	<u>(m)</u>	(N)	(m)	(N)	(m)	(N)	(m)	(N)
Engine On:	54	462	92	492	51	498	82	<u>498</u>
Engine Off:	59	445	NA	NA_	NA NA	<u>NA</u>	NA_	NA_
Post Fade:	59	374	NA	<u>NA</u>	NA	NA	NA NA	<u>NA</u>
<u>Partial Failures (Engine On)</u> :								
Circuit #1 Failed:	72	445	<u>NA</u>	<u>NA</u>	_62	480	NA	<u>NA</u>
Circuit #2 Failed:	135	<u>498</u>	NA	NA	139	<u>485</u>	NA	<u>NA</u>
Anti-lock Failed:	NA	<u>NA</u>	NA	<u>NA</u>	NA	<u>NA</u>	<u>NA</u>	<u>NA</u>
Variable Prop. Valve Failed:	NA	NA_	NA	<u>NA</u>	NA	<u>NA</u>	NA	<u>NA</u>
Power Unit/Assist Failed:	144	498_	<u>NA</u>	NA_	<u>NA</u>	<u>NA</u>	NA NA	<u>NA</u>
Adhesion Utilization	Parking	<u>Brake Tes</u>	ts		Fade an	d Recover	<u>y Series</u>	
Low Coefficient Effectiveness	20% Grade			<u>Baseline</u> :	Best S	top SD <u>5</u>	<u>4</u> m Avg	PF <u>391</u> N
SD PF <sub>max</sub>	Control Fo	rce to Ho	ld:	<u>Heating:</u>	Stops 1	-15 PF <sub>max</sub> .	<u>116</u> N	
(m) (N)						max		
Laden 29 222	Uphill <u>4</u>	.62 N			Stone 1	-15 Min D	ecel Sus	3.05 m/s
Unladen 22 285	Downhill 4	· · · · · · · · · · · · · · · · · · ·		Stop 15 Initial Temp ( C)				
	-			LF_377 RF_377 LR_171 RR_1				
Axle Lock Sequence	Dynamic Te	SL			LF_3//	_ KF <u> 3//</u>	_ LK <u>I/L</u>	KK_199
Balanced Front Rear 20 SN:	Results fo	r Best St	op:	Hot Stop: SD 61 m PFmax 378 N				
LadenX						— max-		
Unladen X	SD50	m		Recovery:	Stops	1-4 PF	107 N	
50 SN:		<del></del>			<b>-</b>	max		* * * * * * * * * * * * * * * * * * *
Laden X	Final Dece	1_3.05	m/s					
			. , =	Recovery :	Stop: Si	D <u>56</u> m	$PF_{max} 391$	<u> </u>
Unladen X	PF <sub>max</sub> _498	N						

## Test Vehicle Information/Specifications

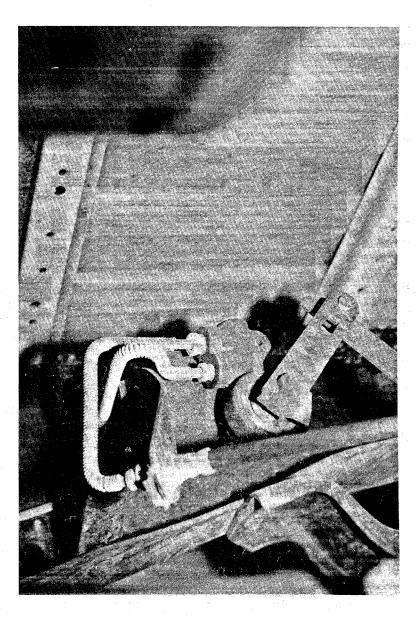
Vehicle Type: Van	_ Wheelbase:	3505	mm
Manufacturer: Ford	Model: E-250	)	· · · · · · · · · · · · · · · · · · ·
VIN: 1FTEE24H1HHA11007	_ Production Da	ate: <u>8/86</u>	
GVWR: 3265 kg GAWR - Frt:_	1406	_kg Rear: <u>192</u>	<u>29                                    </u>
Engine-Type: Gas	No. Cyl:	8 Dis	sp: 5.73 1
Transmission-Type: <u>Automatic</u> Fwd Sp	ds:	Drive Axle:	Rear
Tires-Mfgr: Michelin	Style: <u>R</u>	adial XC144	
Size: LT215/85R16 Test	Press - Frt:_	<u>4,5</u> bar Rea	ar: <u>4.5</u> bar
Grade <u>LF</u>	<u>RF</u>	LR	RR
Treadwear:			
Traction:			
Temperature:			
Serial Number: GD1189			GD1189
Estimated Mileage: 5500	5500	5500	5500
Brake System -			
Booster-Type: <u>Vacuum</u>			
Parking Brake-Type: <u>Rear Shoes</u>			
Prop. Valve-Type: <u>Height Sensing</u>	Split Point:	Rat	io:
Plumbing Split Type: <u>Front/Rear</u>			
	<u>ont</u>	<u>R</u> .	ear
Brake Type: <u>Disc</u>		Drum	
	mm		
Lining Size:			
Lining Codes: Ray 7033-4 FF		Pri BX-UB-FE	Sec BX-UC-DD
Lining Attachment:			
Wheel Cyl/Piston dia:			No. 1
Weights - Curb Weight - Frt: NA			
Test Weight LLVW - Frt: 12	34 kg Rear:_	kg To	tal: <u>2250</u> kg
Test Weight GVW - Frt: <u>13</u>	79kg Rear:_	<u>1882                                   </u>	tal: <u>3261</u> kg
Center of Gravity -			
Height Above Ground - Curb:			
Aft of Front Axle - Curb:	NAmm LLVW	: <u>1583</u> mm	GVW: 2023 mm
Moments of Inertia (ft-1b/sec <sup>2</sup> ) <u>CURE</u>	LLV	W	<u>GVW</u>
Roll (About X Axis): <u>NA</u>	NA		NA
Pitch (About Y Axis): NA	NA		NA
Yaw (About Z Axis): <u>NA</u>	NA_		NA
Vehicle Maximum Speed: 158		km	/h

#### Summary of Performance to Modified Harmonized Brake Test Procedure

		Lad	len			Un1	aden	
				v <sub>max</sub>	100 km/h		80% V <sub>max</sub>	
		utral	ir	max n gear		utral	in gear	
	SD	PFmax	SD	PFmax	SD	PFmax	SD	PFmax
Full Service Braking	<u>(m)</u>	(N)	(m)	(N)	(m)	(N)	(m)	(N)
Engine On:	<u>59</u>	445	93	445	<u>55</u>	436	91	427
Engine Off:	58	374	NA_	<u>NA</u>	NA	<u>NA</u>	NA	NA
Post Fade:	59	445	NA_	NA	NA	NA	NA	NA_
artial Failures (Engine On):								
Circuit #1 Failed:	129	480	NA_	NA	144	498	<u>NA</u>	NA
Circuit #2 Failed:	81	436	NA	NA	73	360	NA	NA
Anti-lock Failed:	NA	<u>NA</u>	NA	NA_	NA	<u>NA</u>	<u>NA</u>	NA_
Variable Prop. Valve Failed:	63	445	NA_	NA	55	480	NA	<u>NA</u>
Power Unit/Assist Failed:	144	498	NA	<u>NA</u>	NA	<u>NA</u>	NA	NA_
Adhesion Utilization	Parking	Brake Tes	ts		Fade an	d Recover	y Series	
Low Coefficient Effectiveness	20% Grade			Baseline:	Best S	top SD5	9_m Avg	PF <u>285</u>
/m\	Control Fo	rce to Ho	ld:	<u>Heating</u> :	Stops 1	-15 PF <sub>max</sub>	209_N	
(N)	Uphill <u>4</u>	62 N			Stops 1	-15 Min D	ecel Sus	3.05 m/
	Downhill_4			Stop 15 Initial Temp ( C)				
Axle Lock Sequence Balanced Front Rear	Dynamic Te	st		LF 466 RF 490 LR 124 RR 15				
	Results fo	r Best St	op:	<pre>Hot Stop:</pre>	SD <u>104</u>	m PF <sub>max</sub>	<u>271</u> N	
Unladen X	SD <u>43</u>	m		Recovery:	Stops	1-4 PF <sub>max</sub>	<u>142</u> N	
0 SN: aden X	Final Dece	1 3.96	m/s	_				
JnladenX	PF <sub>max</sub> 445	N		Recovery S	Stop: S	D <u>/I</u> m :	PF <sub>max</sub> 26	/N



1986 Ford E-250 Van



Ford E-250 Height Sensing Proportioning Valve

## Test Vehicle Information/Specifications

Vehicle Type: King Cab Pickup	Wheelbase:	2950		_mm
Manufacturer: Nissan	Model:			
VIN: JN6ND1652HW011015	_ Production D	ate: <u>2/</u>	87	
GVWR: 1996 kg GAWR - Frt:_	998	_kg Rear	: 1154	_kg
Engine-Type: <u>Gas</u>	No. Cy1:_	4	Disp:2.4	1
Transmission-Type: <u>Automatic</u> Fwd Sp	ds: <u>3</u>	Drive	Axle: <u>Rear</u>	
Tires-Mfgr: Toyo	Style:R	Radial		<del></del>
Size: <u>P195/75 R14</u> Test	Press - Frt:_	<u>2.4</u> b	ar Rear: 2.4	bar
Grade <u>LF</u>	<u>RF</u>	LR	RR	
Treadwear: 200	200	200		
Traction: B	В	<u>B</u>		
Temperature: B	В	<u>B</u>	<u>B</u>	
Serial Number: MPC047	MPC047	MPC047	MPC047	<del></del> ,
Estimated Mileage: 1000	1000	1000	1000	
Brake System - Booster-Type: Vacuum				·
Parking Brake-Type: Re	ar Brake	C	ontrol: <u>Hand</u>	
Prop. Valve-Type: <u>Vari</u>	<u>able</u> Split Po	oint:	Ratio:	
Plumbing Split Type: F	ront/Rear			
	Front		Rear	
Brake Type:	Disc		Drum	
Drum/Rotor Size:	258x26	mm	260	mm
Lining Size:	146.6x48.5x10	mm	249.6x50,0x5.5	mm
Lining Codes:	HITACHI HP14E	3	AKEBONO B701FE	
Lining Attachment:	Bonded		Bonded	
Wheel Cyl/Piston dia:	42.8		25.4	<del></del>
Weights - Curb Weight - Frt: 75	8 kg Rear:	630	kg Total: <u>1388</u>	kg
Test Weight LLVW - Frt: 87	<u>'l          kg</u> Rear:_	698	kg Total: <u>1569</u>	kg
Test Weight GVW - Frt: 91	6 kg Rear:	1080	kg Total: <u>1996</u>	kg
Center of Gravity -				
Height Above Ground - Curb:	608 mm LLVV	W: 606	mm GVW:635	mm
Aft of Front Axle - Curb:	1339 mm LLVV	W: <u>1312</u>	mm GVW:1596	mm
Moments of Inertia (ft-lb/sec <sup>2</sup> ) <u>CURI</u>	LL	<u>vw</u>	GVW	
Roll (About X Axis):370	),7 4!	54.1	556.6	
Pitch (About Y Axis): 1998	3,2 23	18,3	2795.3	
Yaw (About Z Axis): <u>227</u> 2	2.4 252	26.7	2955.4	
Vehicle Maximum Speed: 150			km/h	
Comments: <u>Deceleration sensing prop.</u>	valve			

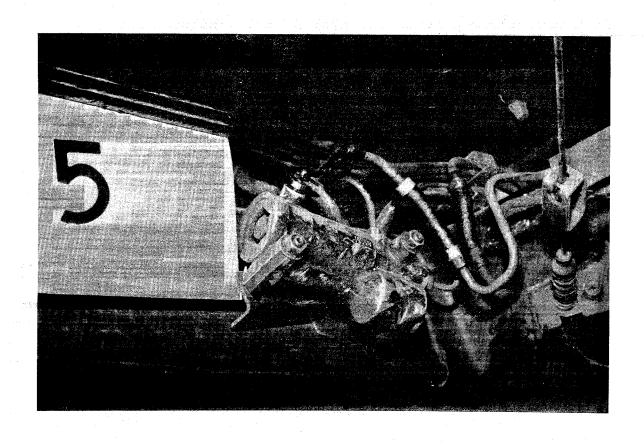
#### Summary of Performance to Modified Harmonized Brake Test Procedure

VehicleNissan TruckTested byVRTCDate Test Completed 7/24/8780% Vmax = 120 km/h

•		Lad				Un1	aden			
	100	100 km/h		100 km/h 80% V <sub>max</sub>		V <sub>max</sub>	100	km/h	80% V max in gear	
	<u>in ne</u>	utral	in	gear	<u>in ne</u>	utral				
	SD	$PF_{max}$	SD	PFmax	SD	PFmax	SD	PFmax		
Full Service Braking	<u>(m)</u>	<u>(N)</u>	<u>(m)</u>	<u>(N)</u>	<u>(m)</u>	<u>(N)</u>	(m)	<u>(N)</u>		
Engine On:	<u>65</u>	462	97	<u>356</u>	57	436	80	400		
Engine Off:	<u>69</u>	<u>445</u>	<u>NA</u>	<u>NA</u>	<u>NA</u>	NA	NA	<u>NA</u>		
Post Fade:	65	294	NA	<u>NA</u>	NA	NA	NA	<u>NA</u>		
<u>Partial Failures (Engine On)</u> :					·					
Circuit #1 Failed:	88	334	NA	NA	<u>76</u>	240	NA	<u>NA</u>		
Circuit #2 Failed:	118	480	NA	<u>NA</u>	127	249	NA_	<u>NA</u>		
Anti-lock Failed:	<u>NA</u>	NA_	NA	<u> </u>	NA	<u>NA</u>	NA_	<u>NA</u>		
Variable Prop. Valve Failed	52	436	<u>NA</u>	NA	67	142	NA_	NA		
Power Unit/Assist Failed:	131	494	<u>NA</u>	<u>NA</u>	NA	NA	NA	NA		
Adhesion Utilization	Parking	Brake Tes	ts		Fade an	d Recover	y Series			
Low Coefficient Effectiveness	20% Grade			Baseline:	Best S	top SD <u>6</u>	<u>5</u> m Avg	PF <u>258</u> N		
SD PF <sub>max</sub> (m) (N)	Control Fo	rce to Ho	1d:	<u>Heating</u> :	Stops 1	-15 PF <sub>max</sub>	N			
Laden	Uphill 2	<u>22</u> N			Stops 1	-15 Min D	ecel Sus	3.05 m/s		
Unladen 26 116	Downhill 2	<u>22</u> N		Stop 15 Initial Temp ( C)						
Axle Lock Sequence	Dynamic Te	<u>st</u>		LF 496 RF 516 LR 224 RR 243						
Balanced Front Rear 20 SN:	Results for Best Stop:		op:	Hot Stop: SD 72 m PF max 258 N						
Laden         X           Unladen         X	SD <u>54</u>	m		Recovery:	Stops	1-4 PF <sub>max</sub>	<u>124</u> N			
50 SN:  Laden X	Final Dece	13.05	m/s		<b>-</b> . a			· ·		
Unladen X	PF <sub>max</sub> 400	N	•	Recovery	Stop: S	D <u>68</u> m	Pr <sub>max</sub> 25	<u>8_N</u>		



1987 Nissan Truck



Nissan Truck Deceleration Sensing Proportioning Valve

Vehicle Type: 4WD Pickup	Wheelbase:	3124		mm
Manufacturer: Chevrolet	Model: <u>S-10</u>			
VIN: 1GCDT14R2H2213412	Production D	ate: <u>4/8</u>	7	
GVWR: 2314 kg GAWR - Frt:_	1225	_kg Rear:	1225	kg
Engine-Type: Gas	No. Cyl:_	6	Disp:2.8	1
Transmission-Type: <u>Automatic</u> Fwd Spc	ls: <u>4</u>	Drive	Axle:	<del></del>
Tires-Mfgr: General	Style: <u>R</u>	adial	·	
Size: <u>P205/75 R15</u> Test	Press - Frt:_	<u>2.4</u> ba	r Rear: 2.4	_bar
Grade <u>LF</u>	RF	<u>LR</u>	RR	
Treadwear: <u>NA</u>	NA	<u>NA</u>	NA	
Traction: NA	NA	<u>NA</u>	NA	
Temperature: NA	NA	<u>NA</u>	NA	· · · · ·
Serial Number: <u>NA</u>	NA	<u>NA</u>	NA	
Estimated Mileage: 650	650	650	650	
Brake System - Booster-Type: <u>Vacuum</u>				
Parking Brake-Type: <u>Rea</u>	ır Shoes	Co	ntrol: <u>Foot</u>	
Prop. Valve-Type: <u>Fixe</u>	lSpli	t Point:_		.48
Plumbing Split Type: Fr	ont/Rear			
	Front		<u>Rear</u>	
Brake Type:	lotor	<u>D</u>	rum	
Drum/Rotor Size:		mm		mm
Lining Size:		mm		mm
Lining Codes:1	17 FE		35 FE / 224 FF	
Lining Attachment:F	livet		ivet	
Wheel Cyl/Piston dia:				<del></del>
Weights - Curb Weight - Frt: 96	7_kg Rear:_	<u>639</u> k	g Total: <u>1606</u>	kg
Test Weight LLVW - Frt: <u>108</u>	kg Rear:_	<u>748</u> k	g Total: 1832	kg
Test Weight GVW - Frt: 114	8 kg Rear:	<u>1161                                  </u>	g Total: 2309	kg
Center of Gravity -				
Height Above Ground - Curb:	618 mm LLVW	: <u>639</u>	_mm GVW: 697	mm
Aft of Front Axle - Curb:1	.243 mm LLVW	: <u>1276</u>	_mm GVW:1571	mm
Moments of Inertia (ft-lb/sec <sup>2</sup> ) <u>CURB</u>	LLV	w	<u>gvw</u>	
Roll (About X Axis): 405.		<u>5.8</u>		
Pitch (About Y Axis): 2473.			3071.3	
Yaw (About Z Axis): <u>2686</u> .				
Vehicle Maximum Speed: 151				
Comments:			. •	

Vehicle Chevrolet S-10 Tested by VRTC

Date Test Completed 9-29-87 80%  $V_{max} = 121$  km/h

Service 1	Brake and Par	Lad		scs (Kesuic	3 LOL L		aden	
	100	km/h		v <sub>max</sub>				% V <sub>max</sub>
		utral		max n gear		utral		gear
	SD	PFmax	SD	PFmax	SD	PFmax	SD	PFmax
Full Service Braking	<u>(m)</u>	(N)	(m)	(N)	(m)	(N)	(m)	(N)
Engine On:	61	498	88	498	54	<u>436</u>	77	<u>374</u>
Engine Off:	62	498	NA	NA	NA	<u>NA</u>	NA_	NA
Post Fade:	60	498	<u>NA</u>	<u>NA</u>	<u>NA</u>	<u>NA</u>	NA	NA NA
<u> Partial Failures (Engine On)</u>								
Circuit #1 Failed:	80	445	<u>NA</u>	<u>NA</u>	67	400	<u>NA</u>	NA
Circuit #2 Failed:	182	<u>498</u>	NA	NA NA	161	480	<u>NA</u>	NA_
Anti-lock Failed:	NA	<u>NA</u>	<u>NA</u>	NA	NA_	<u>NA</u>	<u>NA</u>	NA
Variable Prop. Valve Faile		<u>NA</u>	<u>NA</u>	NA	<u>NA</u>	<u>NA</u>	NA NA	NA
Power Unit/Assist Failed:	180	498	NA_	NA	<u>NA</u>	NA	NA_	NA
Adhesion Utilization	Parking	Brake Tes	ts		Fade ar	d Recover	y Series	
<u>Low Coefficient</u> Effectiveness	20% Grade			Baseline:	Best S	top SD 6	1_m Avg	PF <u>471</u> N
SD PF <sub>max</sub>	Control Fo	rce to Ho	1d:	Heating:	Stops 1	-15 PF <sub>max</sub>	<u>107</u> N	
(m) (N)						max		
Laden 35 116	Uphill <u>.3</u>	91_N			Stops 1	-15 Min D	ecel Sus	2,90 m/s
Unladen <u>26</u> <u>124</u>	Downhill 3	11_N			Stop 15	Initial	Temp ( C	;)
Axle Lock Sequence	Dynamic Te	st			LF_510	RF <u>499</u>	LR <u>166</u>	RR_ 154
Balanced Front Rear 20 SN:	Results fo	r Best St	op:	Hot Stop:	SD <u>75</u>	m PF <sub>max</sub>	<u>454</u> N	
Laden X Unladen X X	SD <u>66</u>			Dogovory	Stone	1 / DE	116 N	
50 SN:	30 00	111	_	Recovery:	Scops	T T max	TTO IN	
Laden X	Final Dece	1_3.05	m/s	Recovery	Ston: S	D 65 m	<b>ወ</b> ፑ /‹ሬ	.2 N
Unladen X	PF <sub>max</sub> 498	N			<u> </u>	<u>,                                    </u>	max 40	11



1987 Chevrolet S-10

Vehicle Type: <u>Pickup</u>	_ Wheelbase:	2743	mm				
	Model: Ranger						
VIN: IFTBRIOA3FUB74109	Production Date: 1985						
GVWR: 1724 kg GAWR - Frt:_	832	_kg Rear: <u>9</u>	31kg				
Engine-Type: <u>Gas</u>	No. Cyl:_	D	isp: <u>2.3</u> 1				
Transmission-Type: Standard Fwd Sp	ds:	Drive Axl	e: <u>Rear</u>				
Tires-Mfgr: Goodyear	Style: <u>R</u>	adial					
Size: <u>P185/75 R14</u> Test	Press - Frt:_	<u> 2.4</u> bar R	ear: <u>2.4</u> bar				
Grade <u>LF</u>	RF	<u>LR</u>	<u>RR</u>				
Treadwear: NA	NA	NA	NA				
Traction: NA	NA	NA	NA				
Temperature: NA	NA	NA	NA				
Serial Number: NA	NA	NA	NA				
Estimated Mileage: 5000	5000	5000	5000				
Brake System - Booster-Type: <u>Vacuum</u>							
Parking Brake-Type: Re-	ar Shoes	Contr	ol: <u>Foot</u>				
Prop. Valve-Type: <u>None</u>	Spli	t Point:	Ratio: <u></u>				
Plumbing Split Type: F	ront/Rear						
	Front		Rear				
Brake Type:	Rotor	Drum					
Drum/Rotor Size:		mm	mm				
Lining Size:		mm	mm				
Lining Codes:	641 FF	6012	FF				
Lining Attachment:	Rivet	Rive	t				
Wheel Cyl/Piston dia:							
Weights - Curb Weight - Frt: 7	<u>)3                                    </u>	kg T	otal: <u>1238</u> kg				
Test Weight LLVW - Frt: 7	76kg Rear:_	626 kg T	otal: <u>1402</u> kg				
Test Weight GVW - Frt: 8	<u> 10       kg</u> Rear:_	<u>914                                    </u>	otal: <u>1724</u> kg				
Center of Gravity -							
Height Above Ground - Curb:	619 mm LLVW	: 658 mm	GVW: 659 mm				
Aft of Front Axle - Curb:	1185 mm LLVW	: <u>1225</u> mm	GVW: 1454 mm				
Moments of Inertia (ft-lb/sec <sup>2</sup> ) <u>CURB</u>	LLV	<u>w</u>	<u>gvw</u>				
Roll (About X Axis): 327	.538	4.4	437.8				
Pitch (About Y Axis): <u>1582</u>	.1172	2.5	2007.7				
Yaw (About Z Axis): 1699	.6 184	8.0	2326.6				
Vehicle Maximum Speed: 145		k	m/h				
Comments:							

Service	<u>Brake and Par</u>	<u>tial Fail</u>	<u>ure Tes</u>	ts (Result	s for "b	<u>est" stop</u>	s)	
		Lad				Unl	aden	
	100	km/h	80%	${\tt v}_{\tt max}$	100	km/h	80	% V <sub>max</sub>
	in_ne	utral	in	gear	in ne	utral	in	gear
	SD	PFmax	SD	PFmax	SD	PFmax	SD	PFmax
Full Service Braking	(m)	(N)	<u>(m)</u>	(N)	(m)	(N)	(m)	<u>(N)</u>
Engine On:	50	<u> 196</u>	68	<u> 249</u> .	60	124	<u>69</u>	124
Engine Off:	<u>46</u>	<u> 298</u>	NA	. <u>NA</u> .	NA	NA	<u>NA</u>	<u>NA</u>
Post Fade:	<u>47</u>	<u> 267</u>	NA_	<u> </u>	NA	NA_	<u>NA</u>	NA
Partial Failures (Engine On	):							
Circuit #1 Failed:	<u> 78</u>	267	NA_	<u> </u>	68	214	<u>NA</u>	NA
Circuit #2 Failed:	104	489	NA	<u> </u>	124	214	NA	<u>NA</u>
Anti-lock Failed:	NA_	NA	NA_	<u>NA</u>	NA	<u>NA</u>	NA	NA
Variable Prop. Valve Fail	ed: <u>NA</u>	NA	NA	<u>NA</u>	NA	<u>NA</u>	NA	NA
Power Unit/Assist Failed:	<u>62</u>	498	NA	NA	NA	NA_	NA_	<u>NA</u>
								•
Adhesion Utilization	Parking	Brake Tes	ts		Fade ar	nd Recover	y Series	
Low Coefficient Effectiveness	20% Grade			Baseline:	Best S	Stop SD <u>5</u>	0 m Avg	, PF <u>129</u> N
SD PF <sub>max</sub> (m) (N)	Control Fo	orce to Ho	old:	<u>Heating</u> :	Stops 1	l-15 PF <sub>max</sub>	<u>53</u> N	
Laden30111	Uphill _2	<u>285</u> N			Stops 1	L-15 Min D	ecel Sus	<u>2.90</u> m/s <sup>2</sup>
Unladen 24 102	Downhill_2	<u>218</u> N			Stop 15	Initial	Temp ( C	;)
Axle Lock Sequence	Dynamic Te	est			LF_288	RF <u>357</u>	_ LR <u>177</u>	RR_ 160
Balanced Front Rear 20 SN:	Results fo	or Best St	op:	<pre>Hot Stop:</pre>	SD <u>73</u>	m PF <sub>max</sub>	<u>129</u> N	
Unladen X	SD <u>49</u>	m		Recovery:	Stops	1-4 PF <sub>max</sub>	58_N	
50 SN: Laden X	Final Dece	el <u>3.96</u>	_m/s	Recovery	Stop: S	SD <u>61</u> m	PF 12	29 N
Unladen X	PF <sub>max</sub> 302	<u>2</u> N				· · · · · · · · · · · · · · · · · · ·	- max	-



1985 Ford Ranger

Vehicle Type: <u>Pickup</u>	Wheelbase	: 2967	: 	mm
Manufacturer: Ford	Model: F	-150	48.44.4	
VIN: 1FTCF15H4HLA48109	Production	n Date: <u>   3</u> ,	/87	
GVWR: 2177 kg GAWR - 1	Frt: <u>1202</u>	kg Rear	: <u>1309</u>	kg
Engine-Type: Gas	No. Cy	1:8	Disp: <u>5</u>	.8 1
Transmission-Type: Auto F	wd Spds:	Drive	Axle: <u>Rea</u>	<u>r</u>
Tires-Mfgr: Firestone	Style:	Supreme		
Size: <u>P215/75R15</u>	Test Press - Fr	t:l	oar Rear:	bar
Grade <u>LF</u>	<u>RF</u>	LR	<u>R</u>	<u>R</u>
Treadwear: 220	220	220		-
Traction: B	<u>B</u>	<u>B</u>	<u>B</u>	
Temperature: B	В	<u>B</u>	<u>B</u>	
Serial Number: 16394	16395	16395	1603	3
Estimated Mileage: 60	60	60	60	
Brake System -				
Booster-Type: Vacuum				
Parking Brake-Type: Shoes o	f rear brake	Contro	ol: Foot	
Prop. Valve-Type: <u>Fixed</u>	Split Poin	t:	Ratio:	
Plumbing Split Type: Front/	Rear			
	<u>Front</u>		Rear	e e e e e
Brake Type: Disc		Drum		
Drum/Rotor Size:		mm		mm
Lining Size:		_mm		mm
Lining Codes:				1. 
Lining Attachment:		· · · · · · · · · · · · · · · · · · ·		
Wheel Cyl/Piston dia:		····		<del></del>
Weights - Curb Weight - Frt	: <u>1056</u> kg Rea	r: <u>663</u>	_kg Total:	<u>1719                                   </u>
Test Weight LLVW - Frt	: <u>1152</u> kg Rea	r: <u>766</u>	_kg Total:	<u>1918                                   </u>
Test Weight GVW - Frt	: <u>1061</u> kg Rea	r: <u>1175</u>	_kg Total:	<u>2236</u> kg
Center of Gravity -				
Height Above Ground - Cu	rb: <u>704</u> mm L	LVW: 706	mm GVW:	734 mm
Aft of Front Axle - Cu	rb: <u>1144</u> mm L	LVW: 1185	mm GVW:	1559 mm
Moments of Inertia (ft-lb/sec <sup>2</sup> )	CURB	LLVW	<u>GVW</u>	
Roll (About X Axis): _	627.7	858	<u>951.</u>	2
Pitch (About Y Axis): _			4185.	3
Yaw (About Z Axis): _			4435.	5
Vehicle Maximum Speed: 169			km/h	
Comments: Rear axle antilock				

Vehicle Ford F-150 Tested by VRTC

Date Test Completed 5/26/87 80%  $V_{max} = 135$  km/h

		Lade				Un1	aden	
	100	km/h		t V <sub>max</sub> 100		100 km/h 8		t V <sub>max</sub>
	in r	eutral	in	gear	in ne	utral	in s	gear
	SD	PFmax	SD	PF <sub>max</sub>	SD	PFmax	SD	PF <sub>max</sub>
Full Service Braking	<u>(m)</u>	(N)	(m)	(N)	(m)	(N)	(m)	(N)
Engine On:	58	<u>258</u>	96	280	52	320	94	302
Engine Off:	58	236	NA_	NA	<u>NA</u>	<u>NA</u>	NA_	NA
Post Fade:	56	245	<u>NA</u>	NA_	<u>NA</u>	NA	<u>NA</u>	NA
<u> Partial Failures (Engine On)</u>	:							
Circuit #1 Failed:	198	489	NA	<u>NA</u>	201	480	NA_	NA
Circuit #2 Failed:	75	231	NA	<u>NA</u>	64	262	<u>NA</u>	<u>NA</u>
Anti-lock Failed:	57	316	NA_	NA_	53	262	NA	NA
Variable Prop. Valve Faile	d: <u>NA</u>	<u>NA</u>	NA	NA	NA	<u>NA</u>	NA	<u>NA</u>
Power Unit/Assist Failed:	73	<u>498</u>	NA	<u>NA</u>	NA_	NA	NA	NA
Adhesion Utilization	Parking	Brake Test	ts		Fade an	d Recover	y Series	
ow Coefficient Effectiveness	20% Grade	L		Baseline:	Best S	top SD5	<u>8</u> m Avg	PF <u>151</u> N
SD PF <sub>max</sub> (m) (N)	Control F	orce to Hol	ld:	<u>Heating</u> :	Stops 1	-15 PF <sub>max</sub> -	<u>76</u> n	
Laden <u>36</u> <u>93</u>	Uphill _	<u>498</u> N			Stops 1	-15 Min D	ecel Sus	2.90 m/s
Jnladen <u>32</u> 93	Downhill_	<u>485</u> N			Stop 15	Initial '	Temp (C)	)
Axle Lock Sequence Balanced Front Rear	Dynamic T	<u>est</u>			LF <u>377</u>	RF <u>377</u>	LR <u>196</u>	RR_216_
20 SN: Laden X	Results f	or Best Sto	op:	<pre>Hot Stop:</pre>	SD <u>81</u>	m PF <sub>max</sub> -	<u>147</u> N	
Unladen X 50 SN:	SD <u>76</u>	m		Recovery:	Stops	1-4 PF <sub>max</sub> -	<u>71</u> N	
Laden X	Final Dec	el <u>1,98</u> r	m/s <sup>2</sup>	Recovery S	Ston' S	D 66 m	PF 1/40	) N
UnladenX	PF <sub>max</sub> 49	8_N		ACCOVELY I	, <u>, , , , , , , , , , , , , , , , , , </u>	<u> </u>	'max-142	



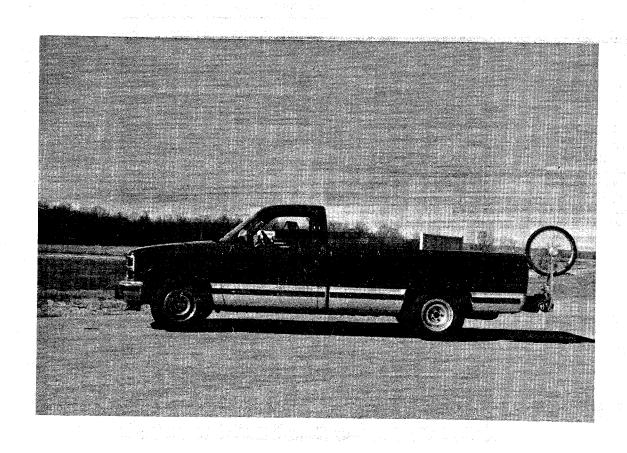
1987 Ford F-150

A CONTRACT OF THE PROPERTY OF

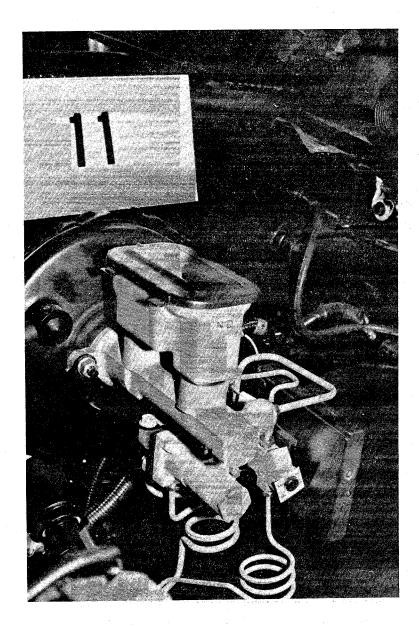
	No. Cyl:	te: <u>08/87</u> kg Rear: <u>15</u> 4	
GVWR: 2540 kg GAWR - Frt: 1 Engine-Type: Gas Transmission-Type: Auto Fwd Spds Tires-Mfgr: Uniroyal	No. Cyl:	kg Rear: <u>15</u> 4	
Engine-Type: <u>Gas</u> Transmission-Type: <u>Auto</u> Fwd Spds  Tires-Mfgr: <u>Uniroyal</u>	No. Cyl:		<u>4</u> kg
Transmission-Type: <u>Auto</u> Fwd Spds Tires-Mfgr: <u>Uniroyal</u>		8 Dis	-
Tires-Mfgr: Uniroyal	s: <u>4</u>		p: <u>5.0</u> 1
		Drive Axle:	Rear
Size: <u>P235/75 R15</u> Test B	Style: <u>R</u> a	dial	
	Press - Frt:	2.4 bar Rea	ır: <u>2.4</u> bar
Grade <u>LF</u>	<u>RF</u>	<u>LR</u>	<u>rr</u>
Treadwear: 280	280	280	280
Traction: B	В	В	<u>B</u>
Temperature: C	<u>C</u>		C
Serial Number:			
Estimated Mileage: 800	800	800	800
Brake System - Booster-Type: <u>Vacuum</u>			
Parking Brake-Type: <u>Rear</u>	Shoes	Control	: Foot
Prop. Valve-Type: <u>Fixed</u>	Split	Point: 460	Ratio: <u>.445</u>
Plumbing Split Type: Fro	ont/Rear		
	Front		Rear
Brake Type:Di	sc	Drum	
Drum/Rotor Size:	· · · · · · · · · · · · · · · · · · ·	mm	mm
Lining Size:		mm	mm
Lining Codes:D	1121 EE	241 FG	<u> </u>
Lining Attachment: Bo	onded	Rivete	d
Wheel Cyl/Piston dia:			
Weights - Curb Weight - Frt: 1082	<u> </u>	kg Tot	al: <u>1856</u> k
Test Weight LLVW - Frt: 1206	kg Rear:_	<u>803</u> kg Tot	al: 2009 k
Test Weight GVW - Frt: 1177	/kg Rear:	<u>1381                                   </u>	al: <u>2558</u> k
Center of Gravity -			
Height Above Ground - Curb:7	<u>734                                    </u>	763mm G	VW: 745 m
Aft of Front Axle - Curb: 13	398mm LLVW:	1340mm G	:VW: <u>1810</u> mr
Moments of Inertia (ft-1b/sec <sup>2</sup> ) <u>CURB</u>	LLVW		<u>GVW</u>
Roll (About X Axis):538.1	479	.4	NA
Pitch (About Y Axis): <u>3430.0</u>			NA
Yaw (About Z Axis): <u>3908,2</u>			NA
Vehicle Maximum Speed: 161		km/	'n
Comments: Rear Axle Antilock System			

Vehicle_	Chevrolet C-1500	·	Tested by_	VRTC				
		Date Test	Completed 1	1/4/87	80% V <sub>r</sub>	max = -	129	_km/h

		Lad				Unl	aden	
	100	km/h	80%	V <sub>max</sub>	100	km/h	80	% V <sub>max</sub>
	<u>in ne</u>	<u>utral</u>	in	gear	in ne	utral	in	gear
	SD	PFmax	SD	PFmax	SD	PFmax	SD	PFmax
Full Service Braking	(m)	(N)	(m)	(N)	(m)	(N)	(m)_	(N)
Engine On:	64	449	101	480	55	405	88	<u>480</u>
Engine Off:	54	471	NA_	N/ <u>.</u>	<u>NA</u>	<u>NA</u>	<u>NA</u>	<u>NA</u>
Post Fade:	62	462	NA	NA	<u>NA</u>	NA_	<u>NA</u>	NA
<u> Partial Failures (Engine On)</u> :								
Circuit #1 Failed:	84	462	NA	<u>NA</u>	72	414	<u>NA</u>	<u>NA</u>
Circuit #2 Failed:	142	498	NA_	NA	<u>135</u>	<u>409</u>	NA	<u>NA</u>
Anti-lock Failed:	60	498	NA	<u>NA</u>	55	445	<u>NA</u>	<u>NA</u>
Variable Prop. Valve Failed	NA	NA	NA	NA	<u>NA</u>	NA_	<u>NA</u>	<u>NA</u>
Power Unit/Assist Failed:	120	498	NA	<u>NA</u>	<u>NA</u>	<u>NA</u>	NA_	<u>NA</u>
Adhesion Utilization	Parking	Brake Tes	ts		Fade an	d Recover	y Series	
Low Coefficient Effectiveness	20% Grade			Baseline:	Best S	top SD <u>6</u>	4_m Avg	PF <u>311</u>
SD PF <sub>max</sub>	Control Fo	rce to Ho	old:	<u>Heating</u> :	Stops 1	-15 PF <sub>max</sub>	<u>160</u> N	
(m) (N) Laden <u>27 276</u>	Uphill <u>4</u>	45_N			Stops 1	-15 Min D	ecel Sus	2.90 m/
Jnladen <u>23</u> <u>298</u>	Downhill_4	67_N			Stop 15	Initial	Temp ( C	)
Axle Lock Sequence Balanced Front Rear	Dynamic Te	<u>est</u>			LF <u>432</u>	RF 466	LR_210	RR_ <u>199</u>
20 SN:  Laden X	Results fo	or Best St	cop:	Hot Stop:	SD <u>91</u>	m PF <sub>max</sub>	311 N	
UnladenX	SD <u>59</u>	m		Recovery:	Stops	1-4 PF <sub>max</sub>	<u>147</u> N	
50 SN: Laden <u>X</u>	Final Dece	1_2.74_	_m/s	Recovery	Ston: S	n 77 m	pr 31	1 ท
UnladenX	PF <sub>max</sub> 409	<u> </u>		Recovery	<u>5005</u> . 5		'max <del>'</del>	<u>.                                    </u>



1988 Chevrolet C-1500



Chevrolet C-1500 Master Cylinder and Antilock Valve

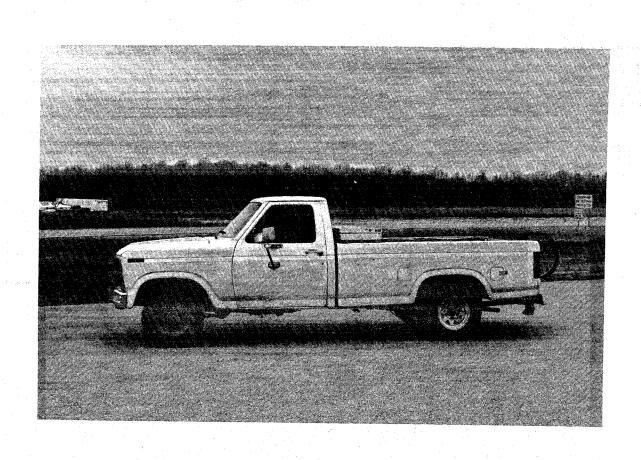
Manufacturer: Ford		<u>, ,                                   </u>	mm
Manufacturer. Foru	Model: F-150 4	x4	
VIN: F14FLHD6690	Production Date	: 1/80	
GVWR: 2631 kg GAWR - Frt:_	1281 kg	Rear: 1460	kg
Engine-Type: Gas	No. Cyl:	Disp	:1
Transmission-Type: Standard Fwd Spd	ls: <u>4</u>	Drive Axle:_	Rear
Tires-Mfgr: Atlas	Style: <u>Radi</u>	.a1	<u> </u>
Size: 235/75 R15 Test	Press - Frt: 2.	4 bar Rear	: <u>2.4</u> bar
Grade <u>LF</u>	<u>RF</u>	LR	RR
Treadwear: NA	NA N	IA	NA
Traction: NA	NA N	IA	NA
Temperature: NA	NA N	IA	NA
Serial Number: NA	NA N	IA	NA
Estimated Mileage: 1000	1000 1	.000	1000
Brake System - Booster-Type: Vacuum			
Parking Brake-Type: Rea	r Shoes	Control:	Foot
Prop. Valve-Type: Fixed	Split F	oint: 283	_ Ratio: 0.46
Plumbing Split Type: Fr	ont/Rear		
	Front		Rear
Brake Type:	isc	Drum	
Drum/Rotor Size:		mm	mm
Lining Size:	···	mm	mm
Lining Codes:			ويريمهم بنياني المعايشي البيناس
Lining Attachment:		er en	<u> 1918 - Arthur Golden, der State and State an</u>
Wheel Cyl/Piston dia:			
wheel cyl/fiscon dia			<u>and the second </u>
Weights - Curb Weight - Frt: 100		000 kg Tota	1: <u>2004</u> kg
	4kg Rear: <u>10</u>	_	
Weights - Curb Weight - Frt: 100	4 kg Rear: 10 4 kg Rear: 9	48 kg Tota	1: <u>2132</u> kg
Weights - Curb Weight - Frt: 100  Test Weight LLVW - Frt: 118	4 kg Rear: 10 4 kg Rear: 9	48 kg Tota	1: <u>2132</u> kg
Weights - Curb Weight - Frt: 100  Test Weight LLVW - Frt: 118  Test Weight GVW - Frt: 122	4 kg Rear: 10 4 kg Rear: 9 7 kg Rear: 14	48 kg Tota 11 kg Tota	1: <u>2132</u> kg 1: <u>2638</u> kg
Weights - Curb Weight - Frt: 100  Test Weight LLVW - Frt: 118  Test Weight GVW - Frt: 122  Center of Gravity -	4 kg Rear: 10 4 kg Rear: 9 7 kg Rear: 14 706 mm LLVW:	<u>48</u> kg Tota <u>11</u> kg Tota mm GV	1: <u>2132</u> kg 1: <u>2638</u> kg W: <u>794</u> mm
Weights - Curb Weight - Frt: 100  Test Weight LLVW - Frt: 118  Test Weight GVW - Frt: 122  Center of Gravity -  Height Above Ground - Curb:  Aft of Front Axle - Curb:	4 kg Rear: 10 4 kg Rear: 9 7 kg Rear: 14  706 mm LLVW: 692 mm LLVW:	48 kg Tota 11 kg Tota 737 mm GV	1: 2132 kg 1: 2638 kg W: 794 mm W: 1814 mm
Weights - Curb Weight - Frt: 100  Test Weight LLVW - Frt: 118  Test Weight GVW - Frt: 122  Center of Gravity -  Height Above Ground - Curb:	4 kg Rear: 10 4 kg Rear: 9 7 kg Rear: 14  706 mm LLVW: 692 mm LLVW: LLVW		1: <u>2132</u> kg 1: <u>2638</u> kg W: <u>794</u> mm
Weights - Curb Weight - Frt: 100  Test Weight LLVW - Frt: 118  Test Weight GVW - Frt: 122  Center of Gravity -  Height Above Ground - Curb: Aft of Front Axle - Curb: 1  Moments of Inertia (ft-1b/sec <sup>2</sup> ) CURB	4 kg Rear: 10 4 kg Rear: 9 7 kg Rear: 14  706 mm LLVW: 692 mm LLVW: LLVW NA	248 kg Tota -11 kg Tota -737 mm GV -1508 mm GV	1: 2132 kg 1: 2638 kg W: 794 mm W: 1814 mm
Weights - Curb Weight - Frt: 100  Test Weight LLVW - Frt: 118  Test Weight GVW - Frt: 122  Center of Gravity -  Height Above Ground - Curb: Aft of Front Axle - Curb: 1  Moments of Inertia (ft-lb/sec <sup>2</sup> ) CURB  Roll (About X Axis): NA	4 kg Rear: 10 4 kg Rear: 9 7 kg Rear: 14  706 mm LLVW: 692 mm LLVW: LLVW NA NA	248 kg Tota 11 kg Tota 737 mm GV 1508 mm GV	1: 2132 kg 1: 2638 kg W: 794 mm W: 1814 mm
Weights - Curb Weight - Frt: 100  Test Weight LLVW - Frt: 118  Test Weight GVW - Frt: 122  Center of Gravity -  Height Above Ground - Curb: Aft of Front Axle - Curb: 1  Moments of Inertia (ft-lb/sec <sup>2</sup> ) CURB  Roll (About X Axis): NA  Pitch (About Y Axis): NA	4 kg Rear: 10 4 kg Rear: 9 7 kg Rear: 14  706 mm LLVW: 692 mm LLVW: LLVW NA NA NA	48 kg Tota   11 kg Tota   737 mm GV   1508 mm GV   G   N	1: 2132 kg 1: 2638 kg W: 794 mm W: 1814 mm

Vehicle Ford F-150 4x4

Ford F-150 4x4 Tested by VRTC

Date Test Completed 11/18/87 80%  $V_{max} = 116$  km/h

Service Br.	ake and Par			ts (Result	s for "b			
	100		den	77	100		aden	9. 37
		km/h	808	V <sub>max</sub>		km/h		% V max gear
	in_ne	utral	SD	gear .	SD	utral	SD	
Full Service Braking	(m)	PF <sub>max</sub>	(m)	PF <sub>max</sub> (N)	(m)	PF <sub>max</sub> (N)	(m)	PF <sub>max</sub> (N)
Engine On:	58	356	77	409	56	329	70	365
Engine Off:	56	391	NA		NA	NA NA	NA.	NA
Post Fade:	66_	347	NA	-	NA	NA NA	NA	NA
Partial Failures (Engine On):		<u></u>			****			
Circuit #1 Failed:	83	391	NA	NA	74	409_	NA_	NA
Circuit #2 Failed:	123	498	NA	NA	125	249	NA	NA
Anti-lock Failed:	NA_	NA	NA	NA	NA	NA	NA	NA
Variable Prop. Valve Failed		NA	NA	NA	NA	NA	NA	<u>N</u> A
Power Unit/Assist Failed:	129	498	NA	NA_	NA_	NA_	NA	NA
Low Coefficient           Effectiveness         SD         PFmax           (m)         (N)           Laden         27         160           Unladen         24         160           Axle Lock Sequence         Balanced Front Rear           20 SN:         Laden         X           Unladen         X           50 SN:         X           Laden         X	20% Grade Control Fo Uphill 6 Downhill 6 Dynamic Te Results fo SD119 Final Dece	667_N 632_N est or Best S	top:	Heating:	Stops 1 Stops 1 Stop 15 LF_340 SD_70	1-15 PF <sub>max</sub> 1-15 Min D 5 Initial		g PF <u>231</u> N  s <u>2.90</u> m/s  S RR 160
Unladen X ev. 2/6/87)	PF <sub>max</sub> 498			Recovery	Stop: S	SD <u>74</u> m	PF <sub>max</sub> 22	27_N

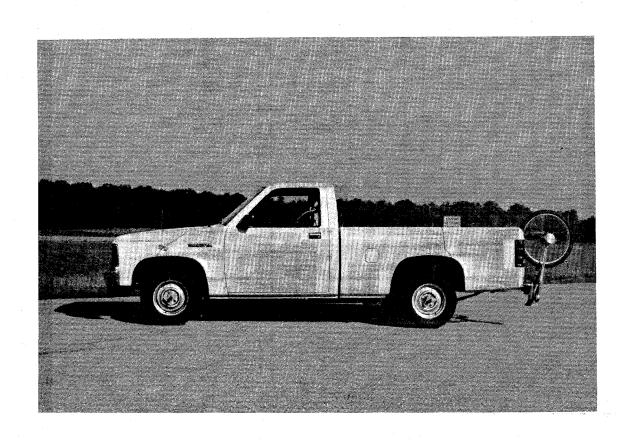


1980 Ford F-150 4x4

Vehicle Type: Pickup	Wheelbase:2	845		_mm		
Manufacturer: Dodge	Model: <u>Dakota</u>					
VIN: 1B7FN14C8HS327073	_ Production Da	ite: <u>9/86</u>				
GVWR: 1865 kg GAWR - Frt:_	1089	kg Rear: 1	044	_kg		
Engine-Type: Gas	No. Cy1:	4D	isp: <u>2.2</u>	1		
Transmission-Type: Standard Fwd Spo	ls: <u>5</u>	_ Drive Axl	e: <u>Rear</u>			
Tires-Mfgr: Goodyear	Style:Ve	ector Radial				
Size: <u>P195/75R14</u> Test	Press - Frt:_	bar R	ear:	bar		
Grade <u>LF</u>	<u>RF</u>	<u>LR</u>	RR			
Treadwear: 280	280	280	280			
Traction: A	Α	Α	A			
Temperature: B	В	В	<u>B</u>			
261257 -	261258-	261262-	261259-			
Serial Number: GCW-34C	GCW-34C	GCW-34C	GCW-34C			
Estimated Mileage: 600	600	600	600			
Brake System -						
Booster-Type: Vacuum		•				
Parking Brake-Type: Shoes of rea	r brake	Control:	Foot			
Prop. Valve-Type: <u>Height Sensing</u>	Split Point:_	Ra	it1o: 0,252			
Plumbing Split Type: Front/Rear						
Fr	ont		Rear			
Brake Type: <u>Disc</u>		Drum	AND			
Drum/Rotor Size:	mm			mm		
Lining Size:	mm			_mm		
Lining Codes: BX JD EE	<del></del>	BX-RY-FE	/ BX-PM-FE			
Lining Attachment:				<del>_</del>		
Wheel Cyl/Piston dia:						
Weights - Curb Weight - Frt: 71	<u> 2kg Rear:_</u>	<u>562</u> kg	Fotal: 1274	k		
Test Weight LLVW - Frt: 81	<u>2kg</u> Rear:_	<u>712        kg</u>	Fotal: 1524	k		
Test Weight GVW - Frt: 92	5kg Rear:_	939kg	Гоtal: <u>1964</u>	k		
Center of Gravity -						
Height Above Ground - Curb:	600 mm LLVW	: <u>617</u> mı	n GVW: 625	mr		
Aft of Front Axle - Curb:	1255 mm LLVW	: <u>1329</u> m	m GVW: <u>1360</u>	m		
Moments of Inertia (ft-lb/sec <sup>2</sup> ) <u>CURB</u>	LLV	<u>w</u>	GVW			
Roll (About X Axis):376		0,5	590.5			
Pitch (About Y Axis): 1831			2298,3			
Yaw (About Z Axis): <u>1986</u>			2596,5			
Comments:						

Vehicle <u>Dodge Dakota</u>		Tested by	VRTC		
	Date Test	Completed	7/8/87	80% V <sub>max</sub> =	112km/h

Service b	rake and Pa			ts (Result	S LOL L			<u></u>
	100	Lad		T7	100		nladen	
		km/h	8U*	V <sub>max</sub>	100 km/h in neutral		80% V <sub>max</sub> in gear	
		eutral		gear				
Full Service Braking	SD	PF <sub>max</sub>	SD (m)	PF <sub>max</sub>	SD (m)	PF <sub>max</sub>	SD	PFmax
Engine On:	<u>(m)</u> 53	<u>(N)</u> 436	(m) 64	( <u>N)</u> 445	<u>(m)</u> 57	(N) 418	<u>(m)</u>	<u>(N)</u> 445
Engine Off:	<u> </u>		NA		NA	NA NA	66 NA	NA
Post Fade:	60	311	NA NA	NA NA	NA NA	NA NA	NA NA	
Partial Failures (Engine On)		211	NA	<u>IVA</u>	<u>NA</u>	NA	NA_	NA
Circuit #1 Failed:	.• 74	409	NA	NA	69	374	NA	ÑΑ
Circuit #2 Failed:	122	285	NA NA	NA NA	130	178	NA NA	NA NA
Anti-lock Failed:	NA NA	NA	NA NA	NA NA	NA	NA NA	NA NA	NA NA
Variable Prop. Valve Faile		342	NA NA	NA NA	58	391	NA NA	NA NA
Power Unit/Assist Failed:	132	498	NA NA	NA NA	NA	NA NA	NA NA	NA NA
· · · · · · · · · · · · · · · · · · ·								
Adhesion Utilization	Parking	Brake Tes	ts		Fade an	d Recover	y Series	
Low Coefficient Effectiveness	20% Grade			Baseline:	Best S	top SD_5	<u>3</u> m Avg	PF <u>231</u> N
SD PF <sub>max</sub> (m) (N)	Control F	orce to Ho	old:	<u>Heating</u> :	Stops 1	-15 PF <sub>max</sub>	<u>116</u> N	
Laden 24 160	Uphill _	<u>262</u> n		Stops 1-15 Min Decel Sus $3.05$ m/s <sup>2</sup>				
Unladen 25 129	Downhill_	<u>231</u> N			Stop 15	Initial	Temp ( C	)
Axle Lock Sequence	Dynamic To	<u>est</u>			LF_349	RF <u>_ 379</u>	LR 149	RR <u>129</u>
Balanced Front Rear 20 SN: Laden X	Results f	or Best St	op:	<pre>Hot Stop:</pre>	SD <u>71</u>	m PF <sub>max</sub>	<u>227</u> N	
Unladen X 50 SN:	SD <u>44</u>	m		Recovery:	Stops	1-4 PF <sub>max</sub>	<u>89</u> N	
Laden X	Final Dec	el <u>3.81</u>	m/s	Recovery	Ston: S	D 64 m	DF 22	1 N
Unladen X	PF <sub>max</sub> 28	5 N		Recovery Stop: SD 64 m PF <sub>max</sub> 231			<u> </u>	



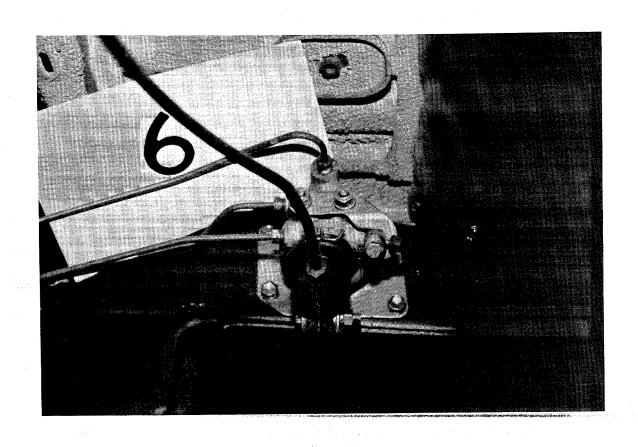
1987 Dodge Dakota

Vehicle Type: <u>Multipurpose</u>	Wheelbase			mm
Manufacturer: Toyota	Model: <u>4</u>	-Runner	superior and the state of the s	
VIN: <u>JT4RN62S5H0140017</u>	Production	n Date:2	2/87	
GVWR: 2304 kg GAWR - Frt		· · · · · · · · · ·		
Engine-Type: <u>Gas</u>	No. Cy	1:4	Disp: <u>2.4</u>	1
Transmission-Type: Manual Fwd	-			
Tires-Mfgr: Bridgestone				
Size: <u>P225/75 R15</u> Te	est Press - Fr	t:	bar Rear:	bar
Grade <u>LF</u>	<u>RF</u>	<u>LR</u>	<u>RR</u>	
Treadwear: 180				•
Traction: B				
Temperature: B				
Serial Number: T8401				-
Estimated Mileage: 4000		4000	4000	<del></del>
Brake System - Booster-Type: Vacuum				<del></del>
Parking Brake-Type:				
Prop. Valve-Type: Heig			<u>Variable</u> Rati	o: <u>0.25</u>
Plumbing Split Type:				
D. 1 . m	Front		Rear	
Brake Type:			Drum	
Drum/Rotor Size:		mm _	295	mm
Lining Size:			296x50x6	mm
Lining Codes:	The state of the s		M2207FG	
Lining Attachment:			Bonded	
Wheel Cyl/Piston dia:				00 1-
Weights - Curb Weight - Frt:				
Test Weight LLVW - Frt: Test Weight GVW - Frt:			-	_
Center of Gravity -	1030 kg kea	1. <u>12/J</u>	_kg Total25	<u> </u>
Height Above Ground - Curb:	. 737 mm I	13 <i>0.</i> 1 - 764	S mm CVIII - 8	05 mm
Aft of Front Axle - Curb:				
		LVW	<u> </u>	<u> </u>
		LLVW	GVW	
Roll (About X Axis):2	•			
Pitch (About Y Axis):17				
Yaw (About Z Axis):26				<del></del>
Vehicle Maximum Speed: 148			km/h	
Comments:				<del></del> '

VehicleToyota 4-RunnerTested byVRTCDate Test Completed9-2-8780% Vmax= 118 km/h

DOLVICO DIA	<u> </u>	Lad				est" stop: Unla	aden	
		km/h	808	v <sub>max</sub>		km/h	80% V <sub>max</sub>	
		utral		gear		eutral .	<u>in gear</u>	
	SD	PFmax	SD	PFmax	SD	PF <sub>max</sub>	SD (m)	PF <sub>max</sub>
Full Service Braking	<u>(m)</u>	(N)	(m) 83	(N) 489	<u>(m)</u> 52	400	73	418
Engine On:	<u>60</u>	480		NA .	NA NA	NA	NA NA	NA NA
Engine Off:	63	409	NA NA	NA NA	NA NA	NA NA	NA NA	NA NA
Post Fade:	61	<u>485</u>	NA	NA	INA	NA	III.	
Partial Failures (Engine On):	1.67		NT A	ATA	146	498	NA	NA _
Circuit #1 Failed:	<u> 164</u>	498	NA NA	<u>NA</u> NA	69	320	NA NA	NA NA
Circuit #2 Failed:	75 <u>^</u>	<u>480</u>	NA NA				NA NA	NA_
Anti-lock Failed:	NA	NA	NA NA	NA NA	<u>NA</u> 55	240	NA NA	NA
Variable Prop. Valve Failed:		436	NA NA	NA NA		NA	NA NA	NA NA
Power Unit/Assist Failed:	100	498	NA	<u>NA</u>	<u>NA</u>	NA	IVA	
	Doreleima	Brake Tes	T	<u> </u>	Fado a	nd Recover	v Series	
Adhesion Utilization		Dlake les	SCS				-	
Low Coefficient Effectiveness	20% Grade			<u>Baseline</u> :	Best	Stop SD <u>6</u>	O m Av	g PF <u>391</u> N
	Control Fo	orce to Ho	old:	<u>Heating</u> : Stops 1-15 PF <sub>max</sub> 187 N				
max	001101201	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,				max		
(11)	TT_L	000 N			Stone	1_15 Min D	ecel Sus	s <u>3.05</u> m/s
	Uphill _2							
Unladen 22 196	Downhill_2	289_N		Stop 15 Initial Temp ( C)				
Axle Lock Sequence	Dynamic To	est			LF <u>349</u>	RF <u>338</u>	LR_199	9 RR 232
Balanced Front Rear	D 6.	a Dante Ci		Hat Stan	en 60	m PF	382 N	
20 SN:	Results fo	or best so	cop.	Hot Stop:	3 <u>0_0</u> 3	m PF <sub>max</sub>	<u> </u>	
Laden X	an 110			December	Ctona	1.4 DE	12/ N	
UnladenX	SD 113	III		Recovery.	scops	1-4 PF <sub>max</sub>	124 1	
50 SN:	Rémai Dan	.1 1 02	2					
Laden X	Final Dece	r <u> 1.03</u>	_111/5	Recovery Stop: SD 68 m PFmax 320 N				
Unladen X	PF <sub>max</sub> 39	1N						
	max	<del></del>	1					

1987 Toyota 4-Runner



Toyota 4-Runner Height Sensing Proportioning Valve

Vehicle Type: MPV	Wheelbase:2	576	mm
Manufacturer: AMC	_ Model: <u>Chero</u>	kee	
VIN: 1JCMR7824HT091269	_ Production Da	te: <u>1/87</u>	
GVWR: 1960 kg GAWR - Frt:_	1134	kg Rear:_	<u>1225</u> kg
Engine-Type: Gas	No. Cyl:	6	Disp: 4.0 1
Transmission-Type: <u>Automatic</u> Fwd Sp	ds: <u>4</u>	_ Drive A	xle: <u>Rear</u>
Tires-Mfgr: Goodyear	Style: <u>Ra</u>	dial	
Size: <u>P205/75 R15</u> Test	Press - Frt:	<u>2.4</u> bar	Rear: 2.4 bar
Grade <u>LF</u>	RF	LR	RR
Treadwear: 280	280	280	280
Traction: A	_A	_A	A
Temperature: B		В	<u>B</u>
Serial Number: <u>M6ULBA1376</u>	M6ULBA1146	M6ULBA138	6 <u>M6ULBA1146</u>
Estimated Mileage: 4000	4000	4000	4000
Brake System - Booster-Type: <u>Vacuum</u>			·
Parking Brake-Type: <u>Re</u>	ar Brake	Con	trol: <u>Hand</u>
Prop. Valve-Type: <u>Fixed</u>	<u>l Prop</u> Split Poi	nt: <u>229</u>	Ratio:0.260
Plumbing Split Type: F	ront/Rear		
	Front		Rear
Brake Type:	Disc	<u>Dr</u>	um
Drum/Rotor Size:	280x22	mm <u>25</u>	<u>4</u> mm
Lining Size:		mm	mm
Lining Codes:	BX-X0-EE	BX	-RM-EE / BX-RW-EE
Lining Attachment:	Rivet	Ri	vet
Wheel Cyl/Piston dia:			
Weights - Curb Weight - Frt: 88	0kg Rear:	<u>644</u> kg	Total: <u>1524</u> kg
Test Weight LLVW - Frt: 97	<u>'3</u> kg Rear:	<u>735                                    </u>	Total: <u>1708</u> kg
Test Weight GVW - Frt: 99	<u> 6kg Rear:</u>	<u>1064                                    </u>	Total: 2059 kg
Center of Gravity -			
Height Above Ground - Curb:	693 mm LLVW:	710	mm GVW: 700 mm
Aft of Front Axle - Curb:	1088 mm LLVW:	1108	mm GVW: <u>1331</u> mm
Moments of Inertia (ft-1b/sec <sup>2</sup> ) CURE	LLVW	· ···	<u>gvw</u>
Roll (About X Axis):460	0.1259	.6	518.7
Pitch (About Y Axis): 1920	.81891	. 3	2247.6
Yaw (About Z Axis):2045	5.2 2170	.0	2714.4
Vehicle Maximum Speed: 168	· · · · · · · · · · · · · · · · · · ·		km/h
Comments: 4-Wheel Drive			

	Laden						sts (Results for "best" stops) Unladen				
	100	km/h		V <sub>max</sub>				% V <sub>max</sub>			
	in n	<u>eutral</u>		gear in neutral			<u>in gear</u>				
	SD	PFmax	SD	PFmax	SD	PFmax	SD	PFmax			
<u>Full Service Braking</u>	<u>(m)</u>	(N)	(m)	<u>(N)</u>	<u>(m)</u>	<u>(N)</u>	(m)	<u>(N)</u>			
Engine On:	66	480	108	480	58	400	95	445			
Engine Off:	66	<u> 427</u>	NA	<u>NA</u>	<u>NA</u>	<u>NA</u>	<u>NA</u>	NA			
Post Fade:	65	338	NA	<u>NA</u>	<u>NA</u>	<u> </u>	<u>NA</u>	NA			
<u> Partial Failures (Engine On)</u>											
Circuit #1 Failed:	79	<u>356</u>	<u>NA</u>	NA_	<u>71</u>	<u>258</u>	<u>NA</u>	NA			
Circuit #2 Failed:	126	<u>480</u>	<u>NA</u>	<u>NA</u>	<u> 153</u>	<u>245</u>	<u>NA</u>	<u> </u>			
Anti-lock Failed:	<u>NA</u>	<u>NA</u>	<u>NA</u>	NA	<u>NA</u>	NA	<u>NA</u>	<u>NA</u>			
Variable Prop. Valve Faile	d: <u>NA</u>	NA	NA	NA	<u>NA</u>	<u>NA</u>	NA	NA			
Power Unit/Assist Failed:	116	<u>498</u>	NA_	NA	NA_	NA	<u>NA</u>	NA			
in the state of th											
Adhesion Utilization	Parking	Brake Tes	sts		Fade at	nd Recover	y Series				
Low Coefficient Effectiveness	20% Grade	•		<u>Baseline</u> :	Best S	Stop SD <u>6</u>	6_m Ave	g PF <u>356</u> N			
SD PF <sub>max</sub> (m) (N)	Control F	orce to Ho	old:	Heating: Stops 1-15 PF <sub>max</sub> 133 N							
Laden <u>27</u> <u>222</u>	Uphill _	311_N			Stops	1-15 Min D	ecel Sus	3.05_m/s			
Jnladen <u>24</u> <u>196</u>	Downhill_	<u>222</u> N			Stop 1	5 Initial	Temp (	5)			
Axle Lock Sequence	<u>Dynamic T</u>	<u>'est</u>			LF <u>429</u>	RF <u>427</u>	_ LR_149	RR 118			
Balanced Front Rear 20 SN:	Results f	or Best St	top:	<pre>Hot Stop:</pre>	SD <u>85</u>	m PFmax	<u>347</u> N				
Laden         X           Unladen         X	SD <u>63</u>	m		Recovery:	Stops	1-4 PF <sub>max</sub>	107_N				
50 SN: Laden X	Final Decel 3.35 m/s			_		an 60	DD 20	EC N			
Unladen X	PF <sub>max</sub> 25	8 N		Recovery Stop: SD 69 m PF <sub>max</sub> 356 N				N0			



1987 AMC Cherokee

#### APPENDIX C

### Tabular Results -- FMVSS 135 Notice 4 Tests

### Low Coefficient Test Results

	Laden					Unladen				
	50	km/h	Axle	Ax1e	50	km/h	Axle	Axle		
	SD	PFmax	Lock	Lock	SD	<b>PFmax</b>	Lock	Lock		
<u>Vehicle</u>	<u>(m)</u>	(N)	20 SN	50 SN	(m)	(N)	20 SN	50 SN		
Dodge Caravan	26	196	Front	Front	25	214	Front	Front		
Toyota Van	28	151	Front	Front	24	173	Front	Front		
Chevrolet Astro	29	222	Front	Front	22	285	Front	Front		
Ford E-250	29	214	Front	Rear	27	138	Front	Front		
Nissan Truck	25	156	Front	Front	26	116	Front	Front		
Chevrolet S-10	35	116	Front	Front	26	124	Front	Front		
Ford Ranger	30	111	Front	Rear	24	102	Front	Rear		
Ford F-150	36	93	Front	Front	32	93	Front	Front		
Chevrolet C-1500	27	276	Front	Front	23	298	Front	Front		
Ford F-150 4X4	27	160	Front	Front	24	160	Front	Front		
Dodge Dakota	24	160	Front	Front	25	129	Front	Front		
Toyota 4-Runner	25	187	Front	Front	22	196	Front	Front		
Jeep Cherokee	27	222	Front	Front	24	196	Front	Front		
Average	28.3	3			24.9	•				

Laden Full System Results

		Engine On			Engin	e Off	Post	Fade	
	80 %	100	km/h	80₽	$V_{max}$	100	km/h	100	km/h
	Vmax	SD P	Fmax	SD P	Fmax	SD P	Fmax	SD P	Fmax
<u>Vehicle</u>	(km/h)	(m)	(N)	(m)	(N)	<u>(m)</u>	(N)	(m)	<u>(N)</u>
Dodge Caravan	113	61	427	78	498	58	485	57	489
Toyota Van	108	64	427	72	445	57	445	59	467
Chevrolet Astro	130	54	462	92	492	59	445	59	374
Ford E-250	126	59	445	93	445	58	374	59	445
Nissan Truck	120	65	462	97	356	69	445	65	294
Chevrolet S-10	121	61	498	88	498	62	498	60	498
Ford Ranger	116	50	196	68	249	46	298	47	267
Ford F-150	135	58	258	96	280	58	236	56	245
Chevrolet C-1500	129	64	449	101	480	54	471	62	462
Ford F-150 4X4	116	58	356	77	409	56	391	66	347
Dodge Dakota	112	53	436	64	445	52	400	60	311
Toyota 4-Runner	118	60	480	83	489	63	409	61	485
Jeep Cherokee	134	66	480	108	480	66	427	65	338
Average		59.5				58.3		59.7	

Unladen Full System Results

	80 %	100	km/h	80%	Vmax
	Vmax	SD	PFmax	SD	PFmax
<u>Vehicle</u>	(km/h)	<u>(m)</u>	(N)	<u>(m)</u>	(N)
Dodge Caravan	113	51	445	67	400
Toyota Van	108	54	276	63	334
Chevrolet Astro	130	51	498	82	498
Ford E-250	126	55	436	91	427
Nissan Truck	120	57	436	80	400
Chevrolet S-10	121	54	436	77	374
Ford Ranger	116	60	124	69	124
Ford F-150	135	52	320	94	302
Chevrolet C-1500	129	55	405	88	480
Ford F-150 4X4	116	56	329	70	365
Dodge Dakota	112	57	418	66	445
Toyota 4-Runner	118	52	400	73	418
Jeep Cherokee	134	58	400	95	445

Average

Laden Failed System Results

	Circu	uit #1	Circu	it #2	A.L.	/V.P.	Power	Assist
	SD	PFmax	SD	PFmax	SD	PFmax	SD	PFmax
<u>Vehicle</u>	<u>(m)</u>	(N)	<u>(m)</u>	(N)	(m)	<u>(N)</u>	<u>(m)</u>	(N)
Dodge Caravan	113	480	114	485	63	NA	161	494
Toyota Van	146	498	70	480	57	498	135	498
Chevrolet Astro	72	445	135	498			144	498
Ford E-250	129	480	81	436	63	445	144	498
Nissan Truck	88	334	118	480	52	436	131	494
Chevrolet S-10	80	445	182	498			180	498
Ford Ranger	78	267	104	489			62	498
Ford F-150	198	489	75	231	57	316	73	498
Chevrolet C-1500	84	462	142	498	60	498	120	498
Ford F-150 4X4	.83	391	123	498			129	498
Dodge Dakota	74	409	122	285	63	342	132	498
Toyota 4-Runner	164	498	. 75	480	63.	436	100	498
Jeep Cherokee	79	356	126	480			116	498
Average	106.7	,	112.8				125.1	St. San Life
Overall Average		109.8					* *	

# Unladen Failed System Results

	Circuit #1		Circu	iit #2	A.L./V.P.		
	SD	PFmax	SD	PFmax	SD	PFmax	
<u>Vehicle</u>	(m)	(N)	<u>(m)</u>	(N)	<u>(m)</u>	(N)	
Dodge Caravan	108	454	122	325	61	NA	
Toyota Van	156	187	59	316	58	280	
Chevrolet Astro	62	480	139	485			
Ford E-250	144	498	73	360	55	480	
Nissan Truck	76	240	127	249	67	142	
Chevrolet S-10	67	400	161	480			
Ford Ranger	68	214	124	214	. m + 2		
Ford F-150	201	480	64	262	53	262	
Chevrolet C-1500	72	414	135	409	55	445	
Ford F-150 4X4	74	409	. 125	249			
Dodge Dakota	69	374	130	178	58	391	
Toyota 4-Runner	146	498	69	320	55	240	
Jeep Cherokee	71	258	153	245			
Average	101.0	)	113.9	)			
Overall Average		107.5					

Fade and Recovery Results

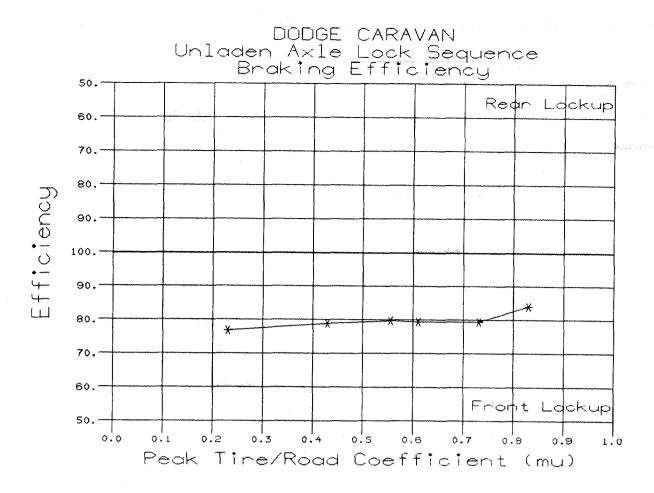
	Snub	15 IBT	Hot	Stop	Recove	r Stop
	Front	Rear	SD	<b>PFmax</b>	SD	PFmax
<u>Vehicle</u>	<u>(C)</u>	<u>(C)</u>	<u>(m)</u>	(N)	<u>(m)</u>	(N)
Dodge Caravan	418	142	80	249	66	249
Toyota Van	432	193	73	245	66	231
Chevrolet Astro	377	185	61	378	56	391
Ford E-250	478	140	104	271	71	267
Nissan Truck	506	234	72	258	68	258
Chevrolet S-10	505	160	75	454	65	462
Ford Ranger	322	168	73	129	61	129
Ford F-150	377	206	81	147	66	142
Chevrolet C-1500	449	205	91	311	77	311
Ford F-150 4X4	361	163	70	222	74	227
Dodge Dakota	364	139	71	227	64	231
Toyota 4-Runner	344	215	59	382	68	320
Jeep Cherokee	428	134	85	347	69	356
Average			77.3	3	67.0	

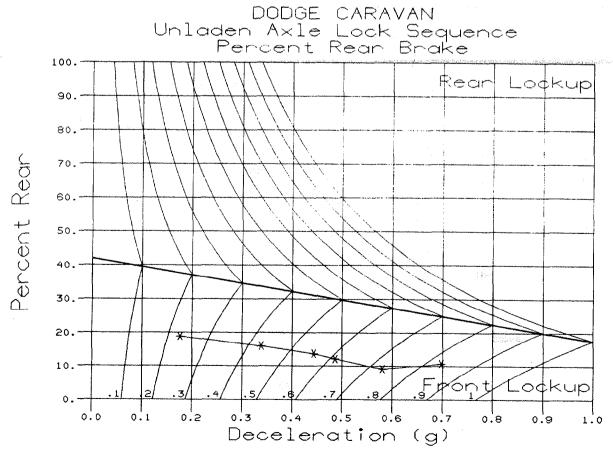
# Parking Brake Results

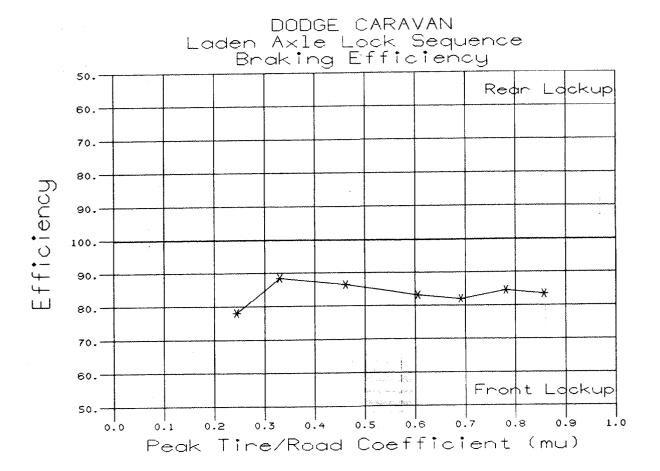
	Static 20	% Grade	60	60 km/h Stops		
	Minimum	Force		Final		
,	Up	Down	SD	Decel	PFmax	
<u>Vehicle</u>	(N)	<u>(N)</u>	<u>(m)</u>	(m/s/s)	(N)	
Dodge Caravan	365	311	72	3.96	391	
Toyota Van	254	222	58	2.74	391	
Chevrolet Astro	462	445	50	3.05	498	
Ford E-250	462	427	43	3.96	445	
Nissan Truck	222	222	54	3.05	400	
Chevrolet S-10	391	311	66	3.05	498	
Ford Ranger	285	218	49	3.96	302	
Ford F-150	498	485	76	1.98	498	
Chevrolet C-1500	445	467	59	2.74	409	
Ford F-150 4X4	667	632	119	1.52	498	
Dodge Dakota	262	231	44	3.81	285	
Toyota 4-Runner	298	289	113	1.83	391	
Jeep Cherokee	311	222	63	3.35	258	
Average	379	345	66.6	3.00		

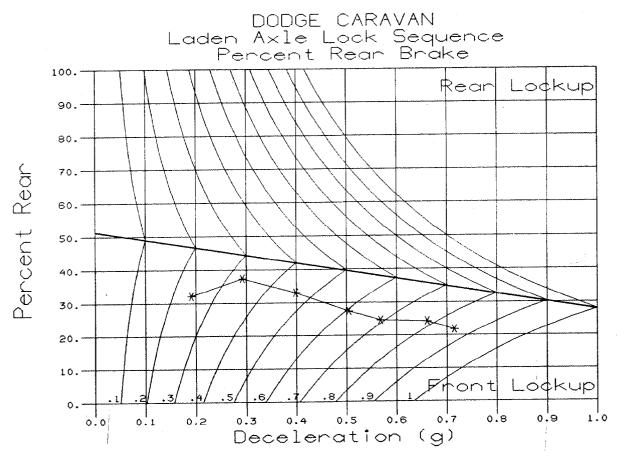
# APPENDIX D

# RTP Axle Lock Sequence Tests

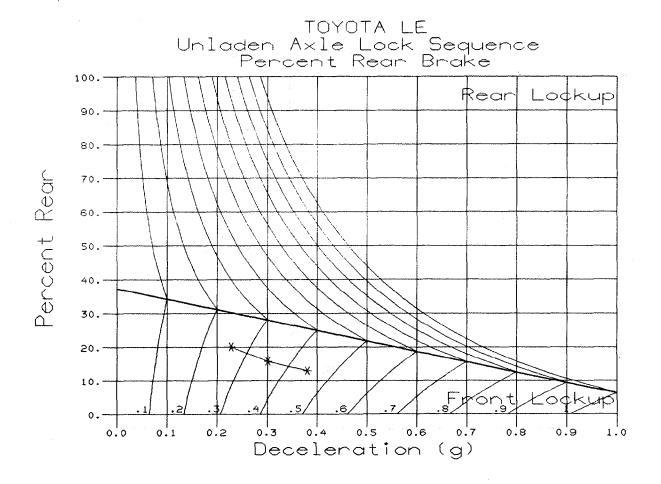


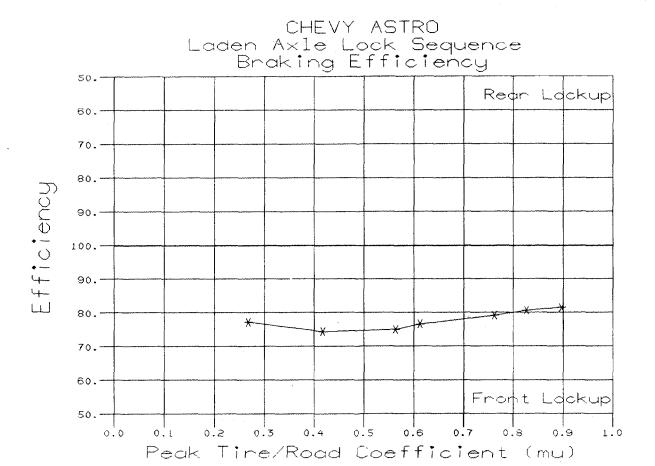


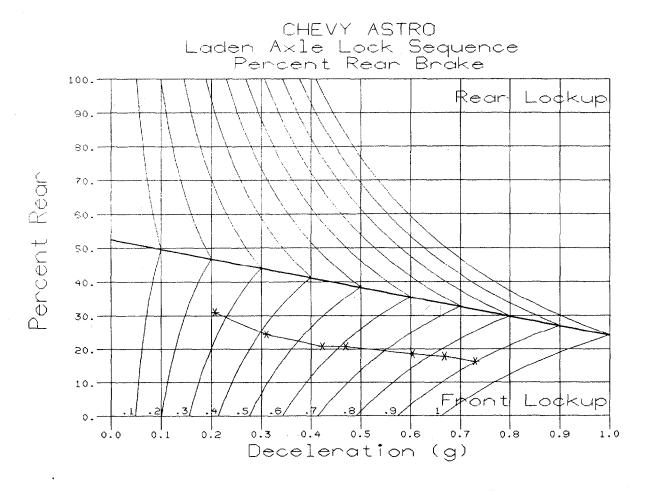


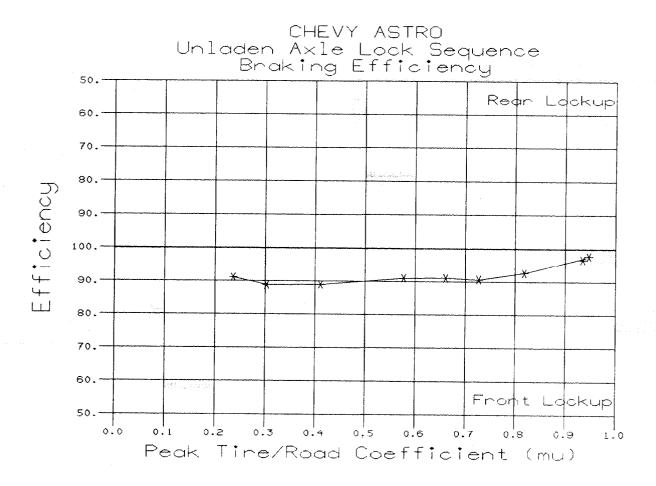


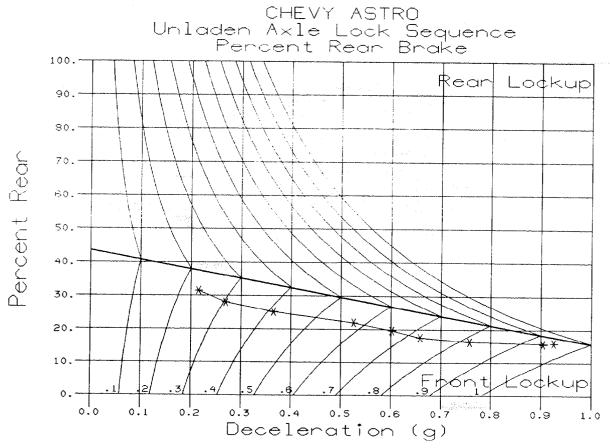
TOYOTA LE Unladen Axle Lock Sequence Braking Efficiency 50.-Redn Ldckup 60.-70.-80.-Efficiency 90.-100.-90.-80.-70.-60.-Front Lackup 50.-0.8 0.2 0.3 0.4 0.5 0.6 0.7 0.0 0.1 Peak Tire/Road Coefficient (mu)

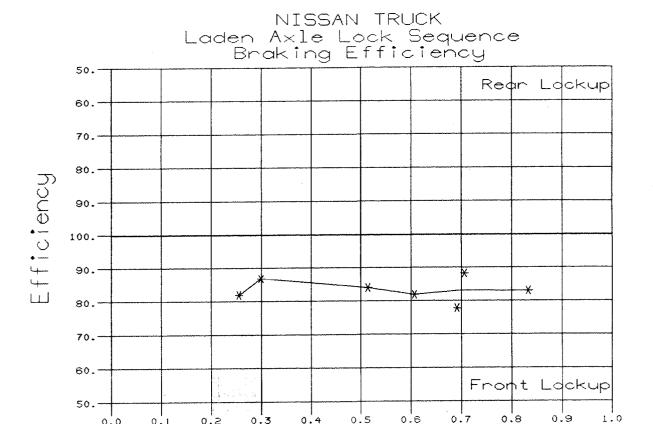




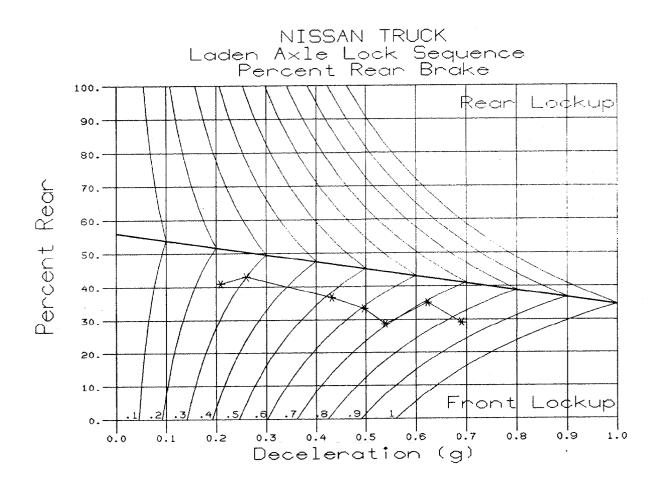


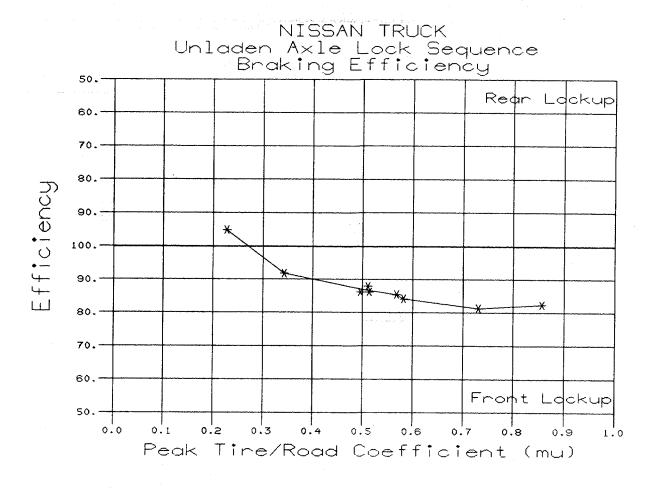


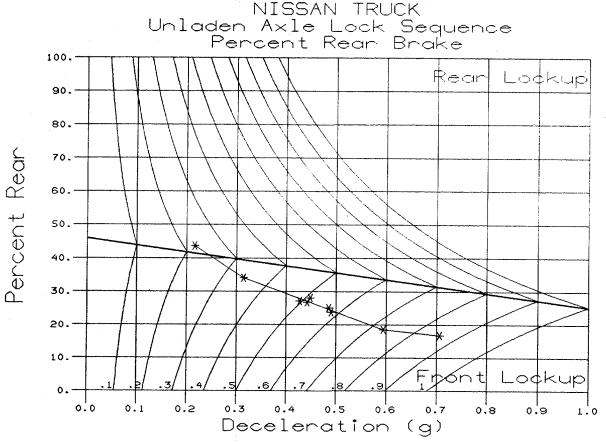


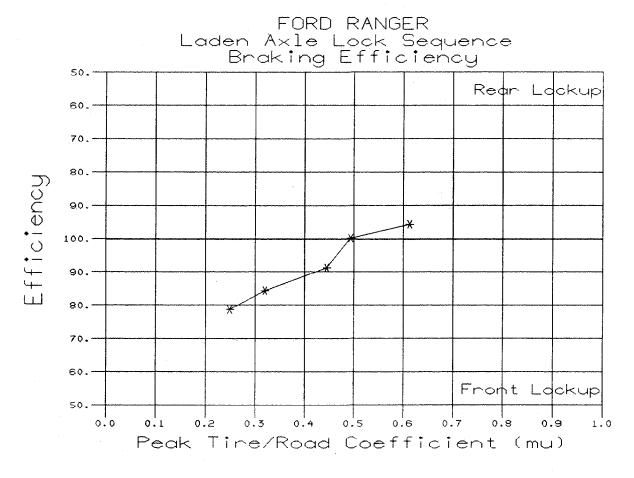


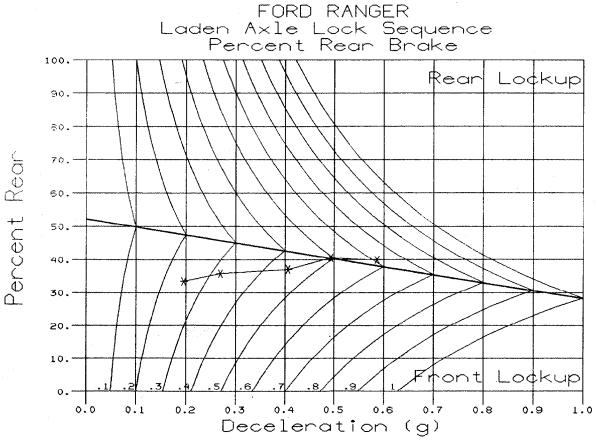
Peak Tire/Road Coefficient (mu)

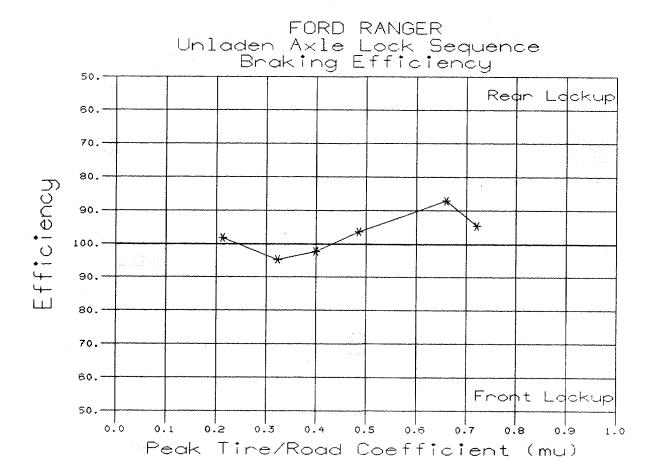


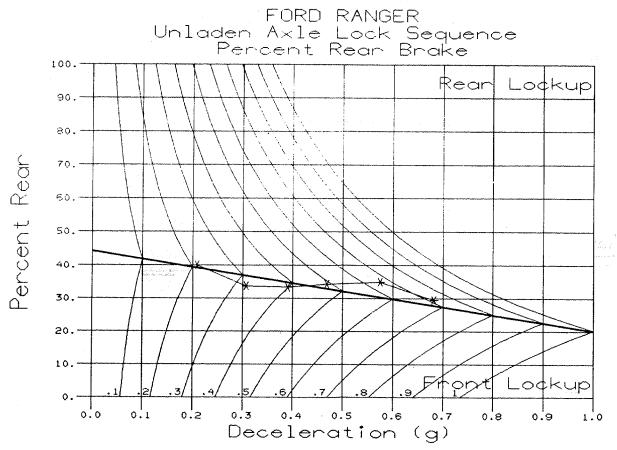




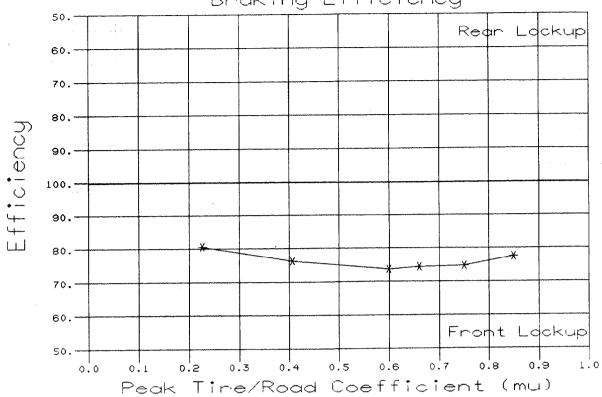


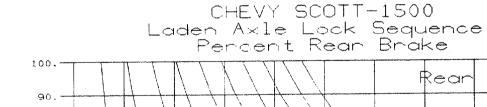


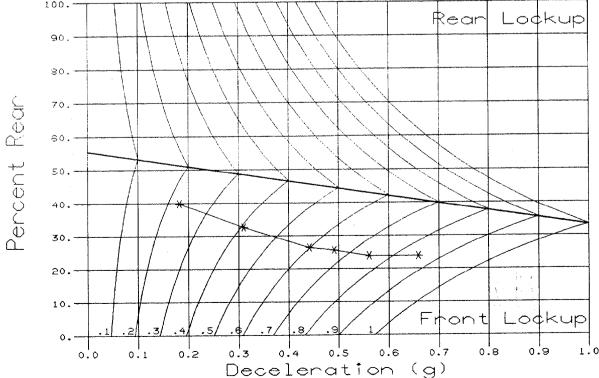


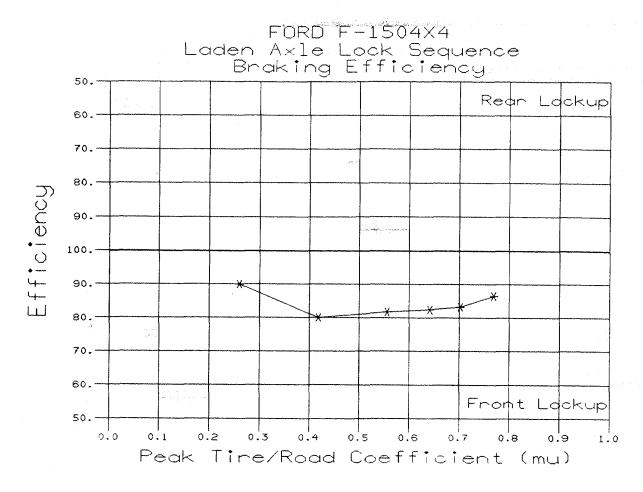


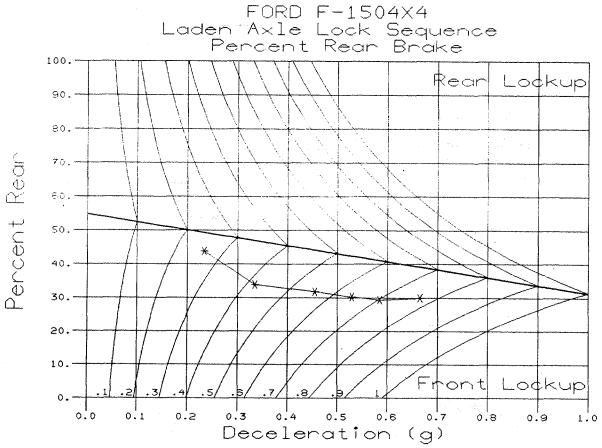


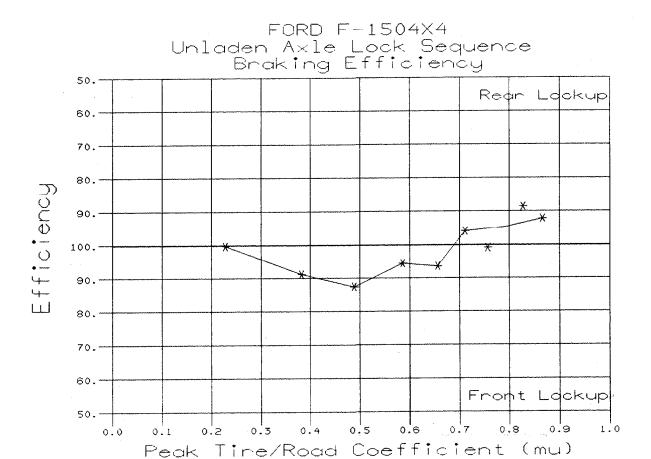


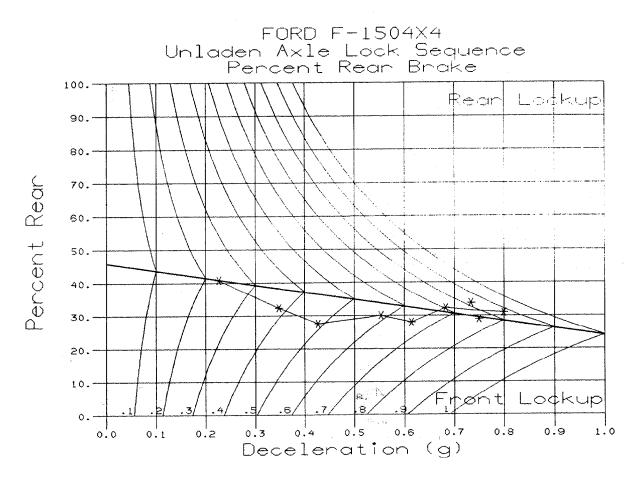


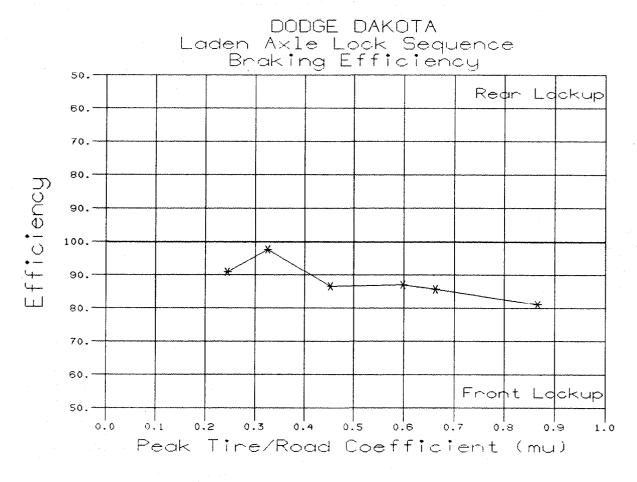


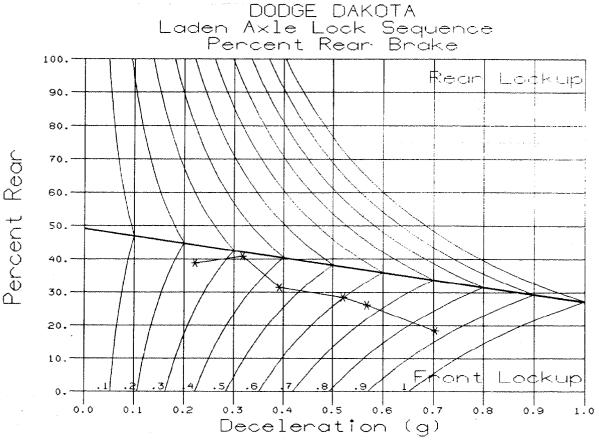


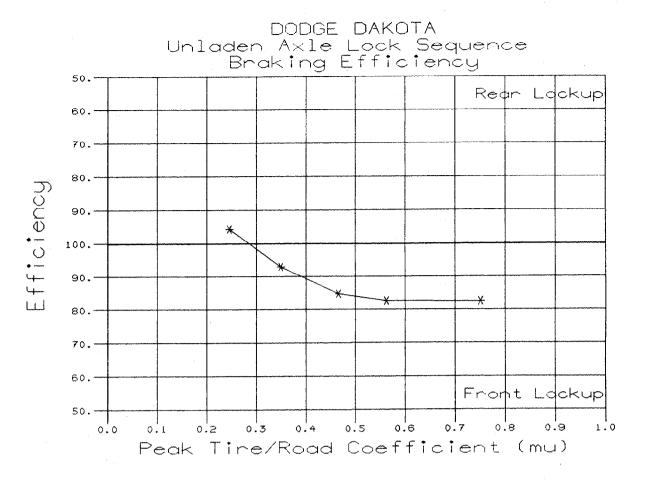


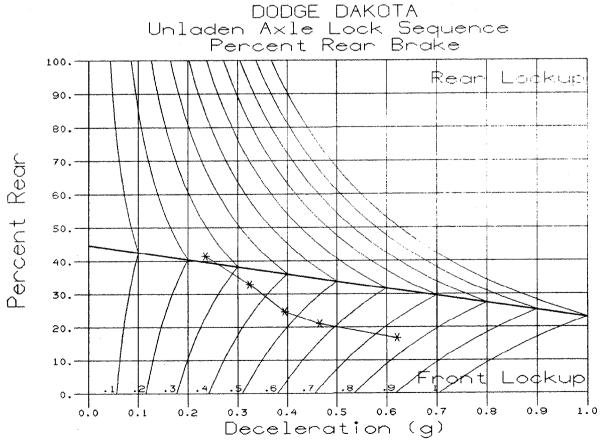


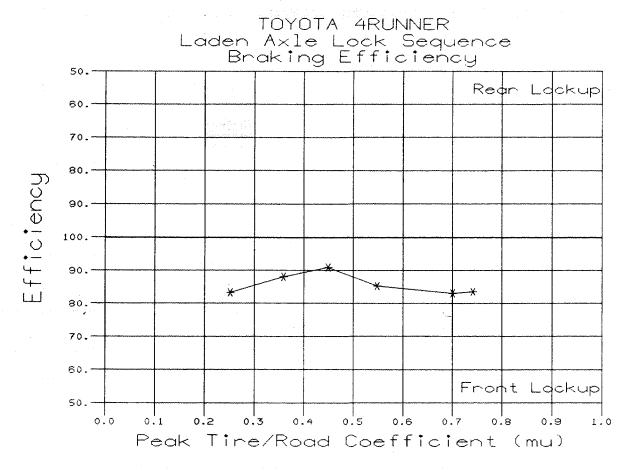


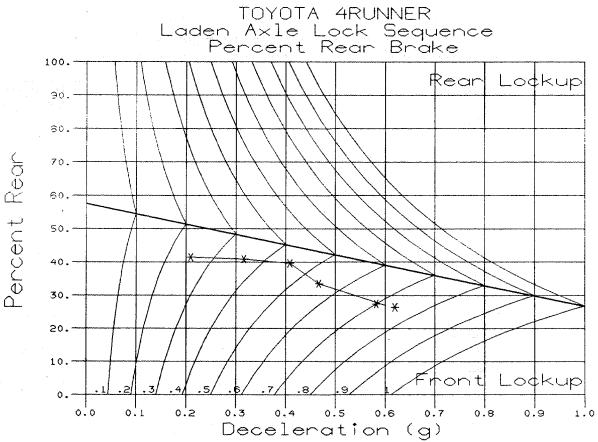




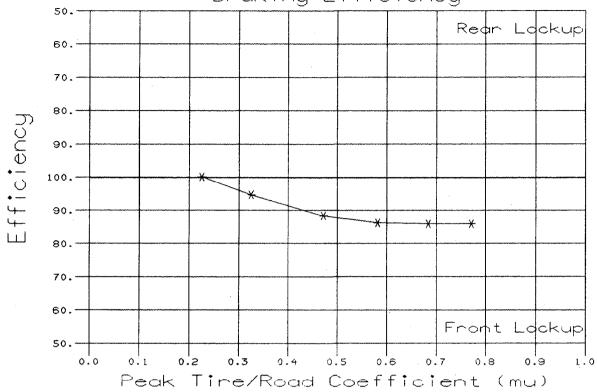




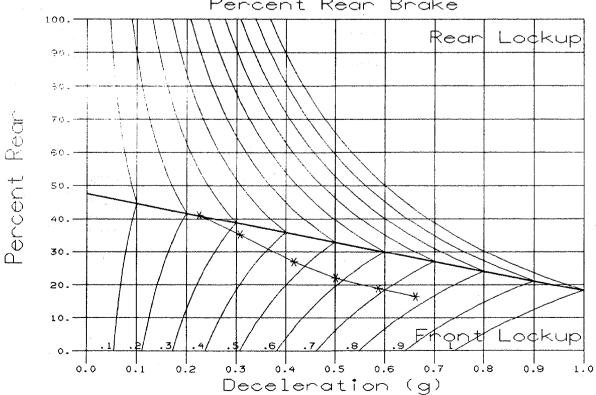




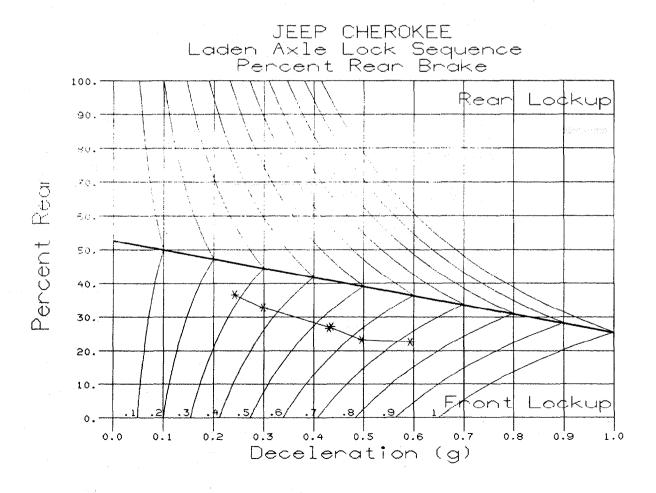


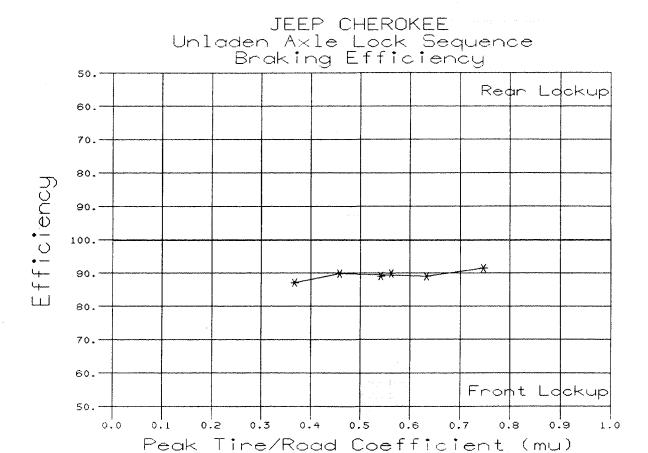


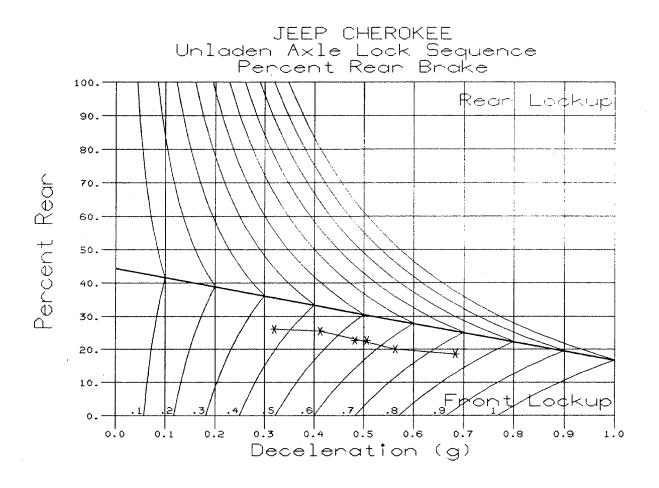




JEEP CHEROKEE Laden Axle Lock Sequence Braking Efficiency 50. Redn Ldckup 60.-70.-80.-Efficiency 90. 100,-90.-80.-70.-60.-Front Ldckup 0.2 0.4 0.5 0.6 0.7 0.8 0.0 Peak Tire/Road Coefficient (mu)



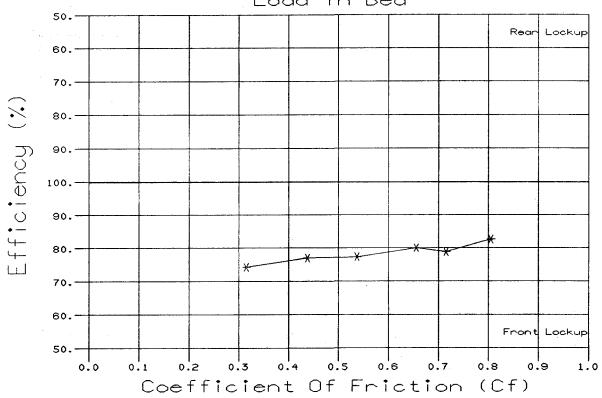


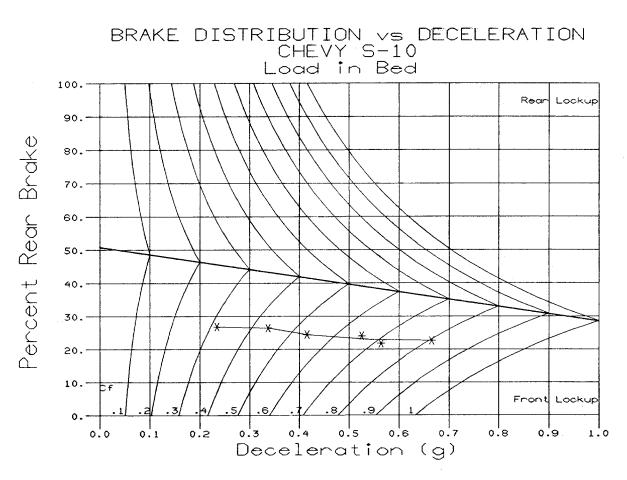


## APPENDIX E

## RTP Load Height Tests

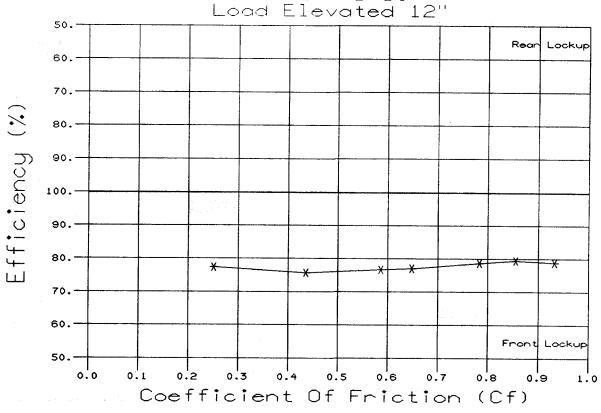
BRAKING EFFICIENCY VS. SURFACE FRICTION CHEVY S-10
Load in Bed

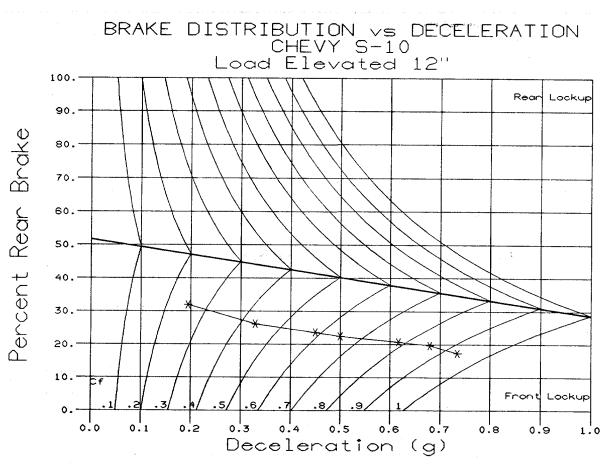




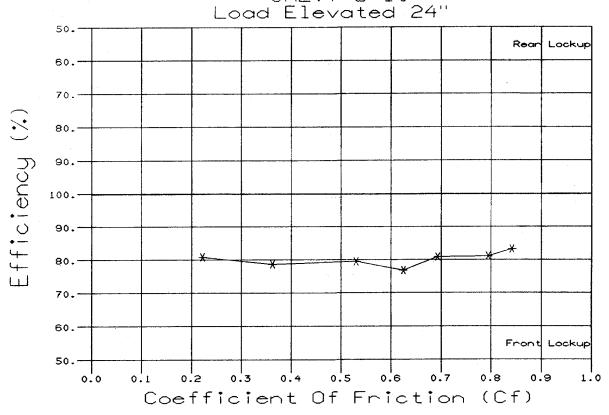
BRAKING EFFICIENCY VS SURFACE FRICTION CHEVY S-10

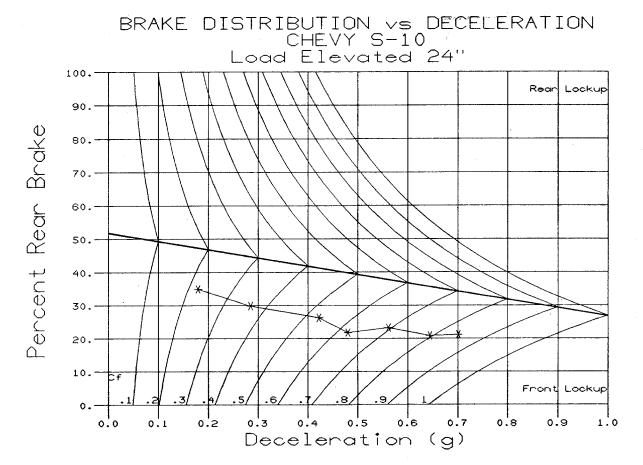
1 Property by the same many transfers of the same and the



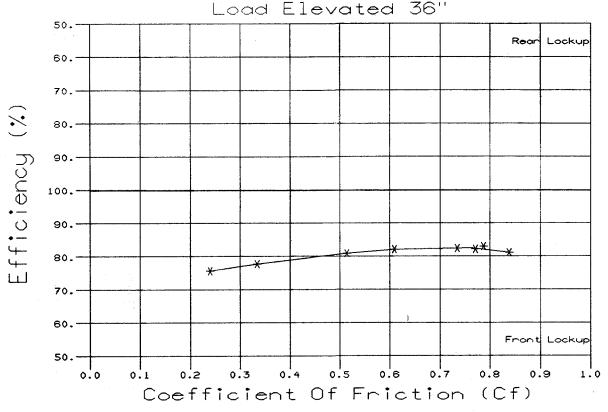


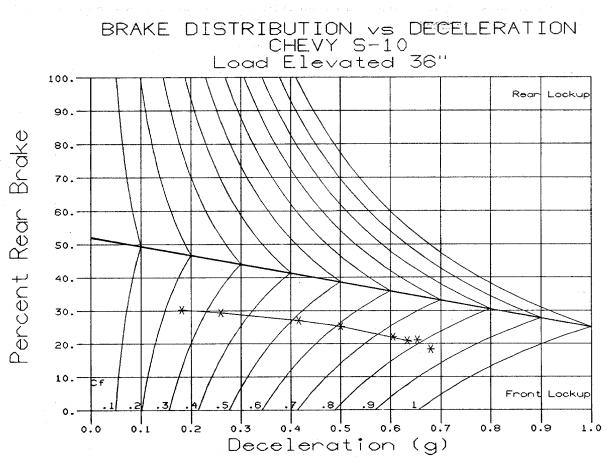
BRAKING EFFICIENCY VS SURFACE FRICTION CHEVY S-10



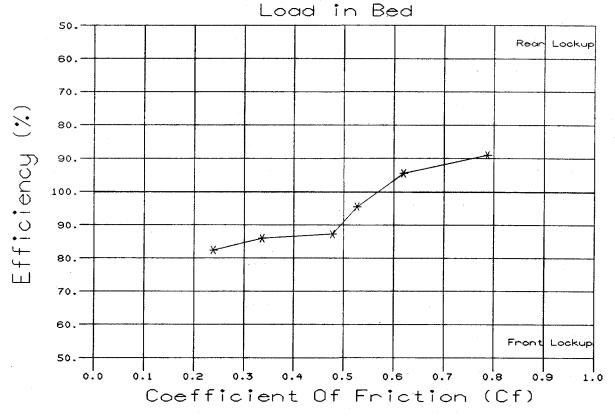


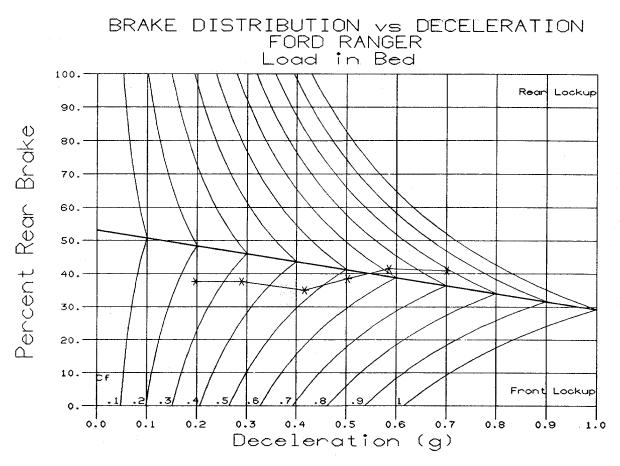
BRAKING EFFICIENCY VS SURFACE FRICTION CHEVY S-10



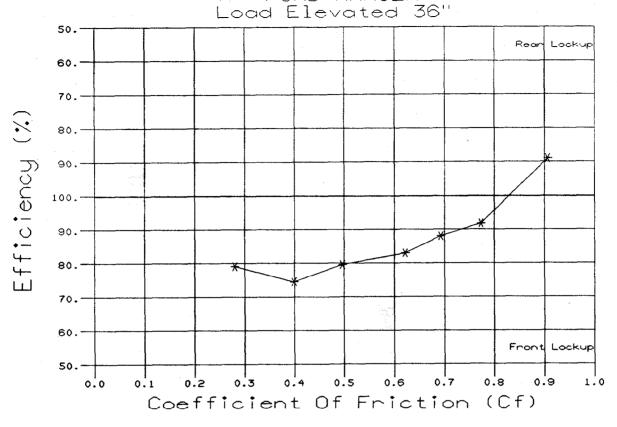


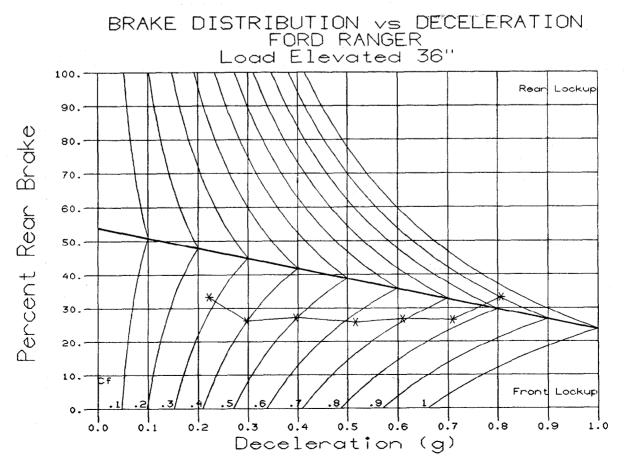
BRAKING EFFICIENCY VS SURFACE FRICTION FORD RANGER





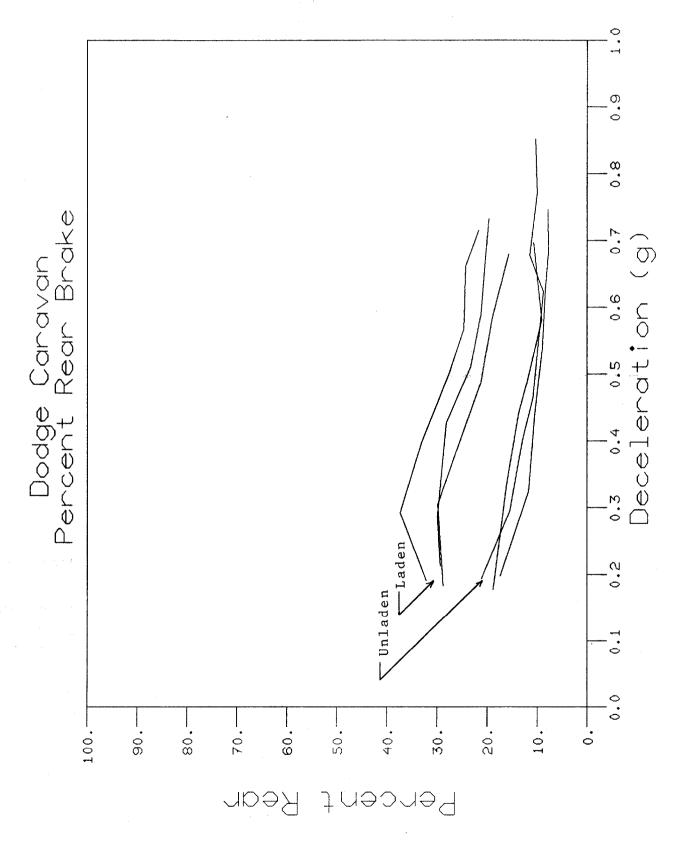
BRAKING EFFICIENCY VS SURFACE FRICTION FORD RANGER

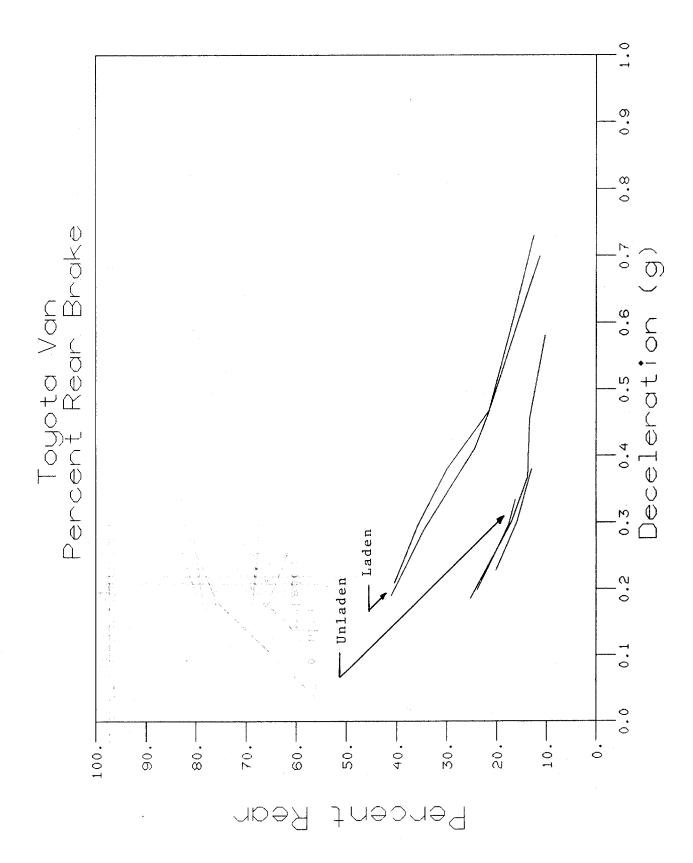


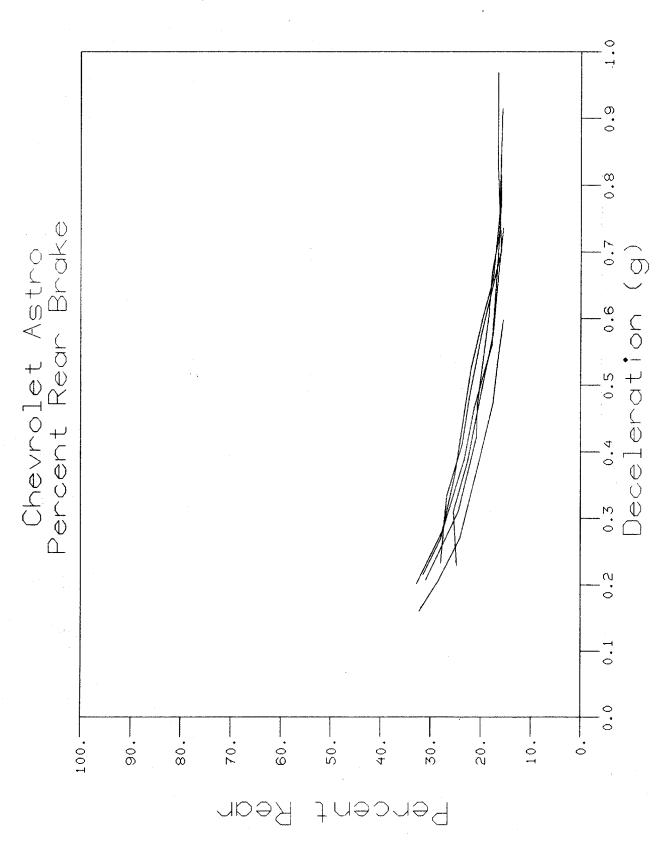


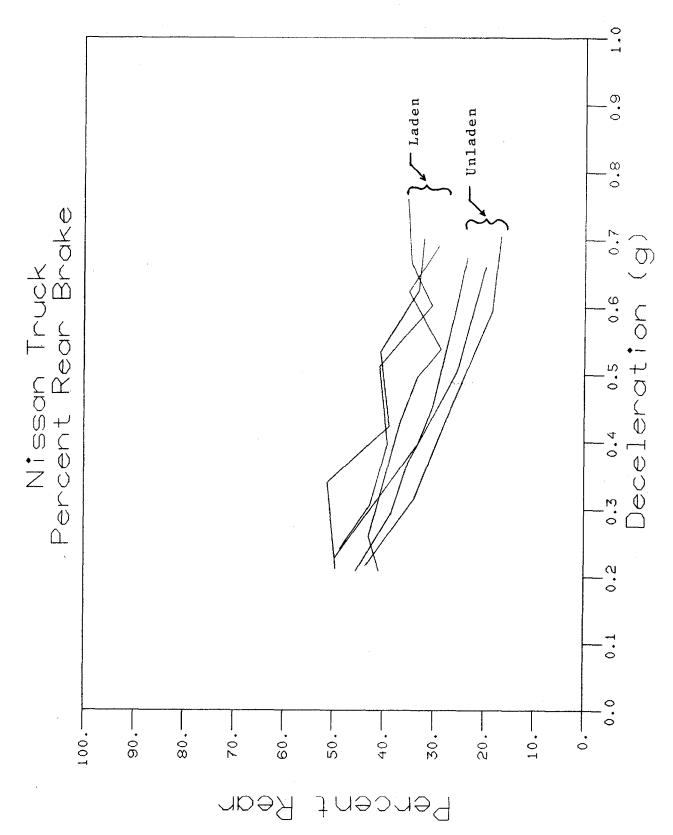
## APPENDIX F

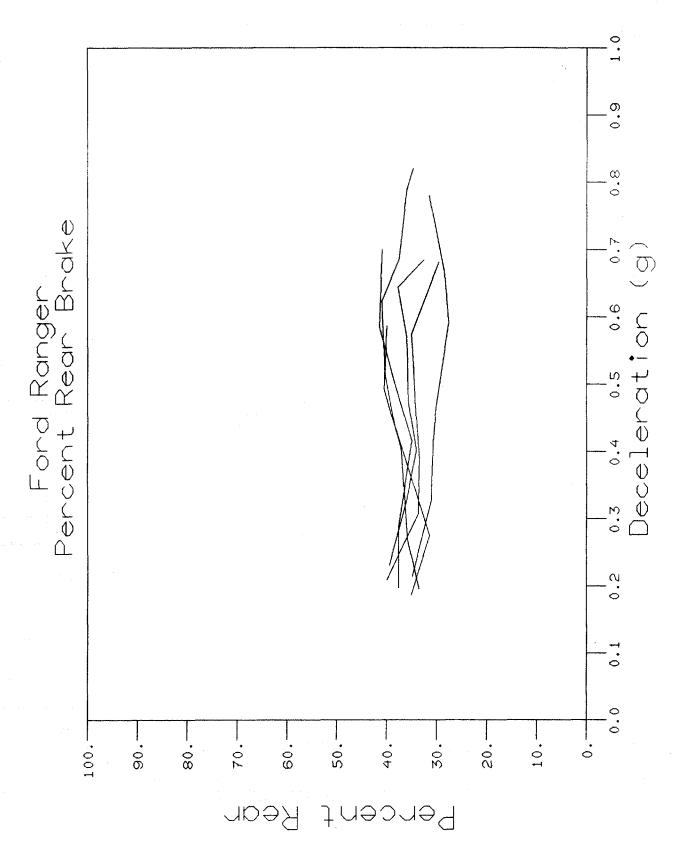
## RTP Tests Composites

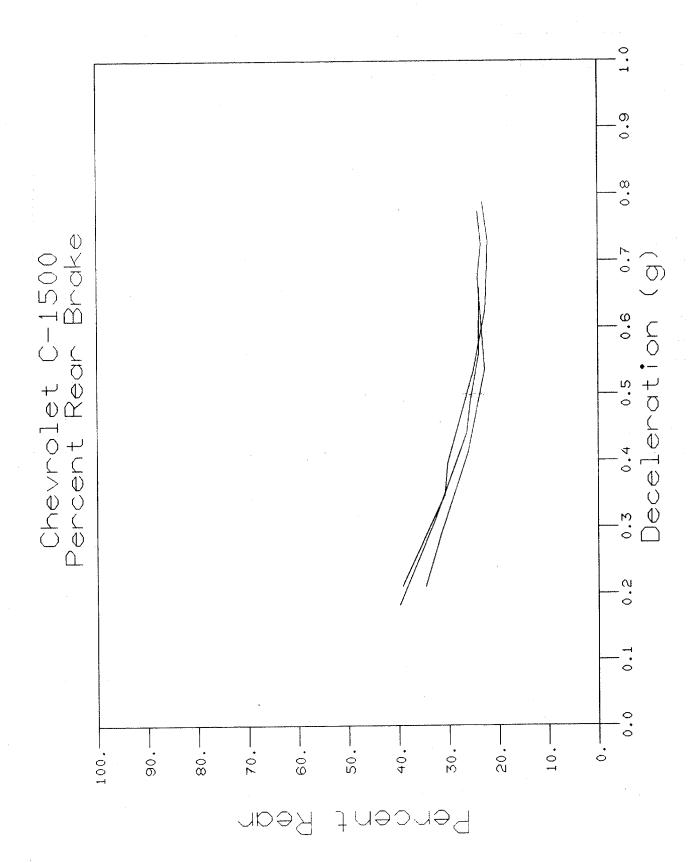


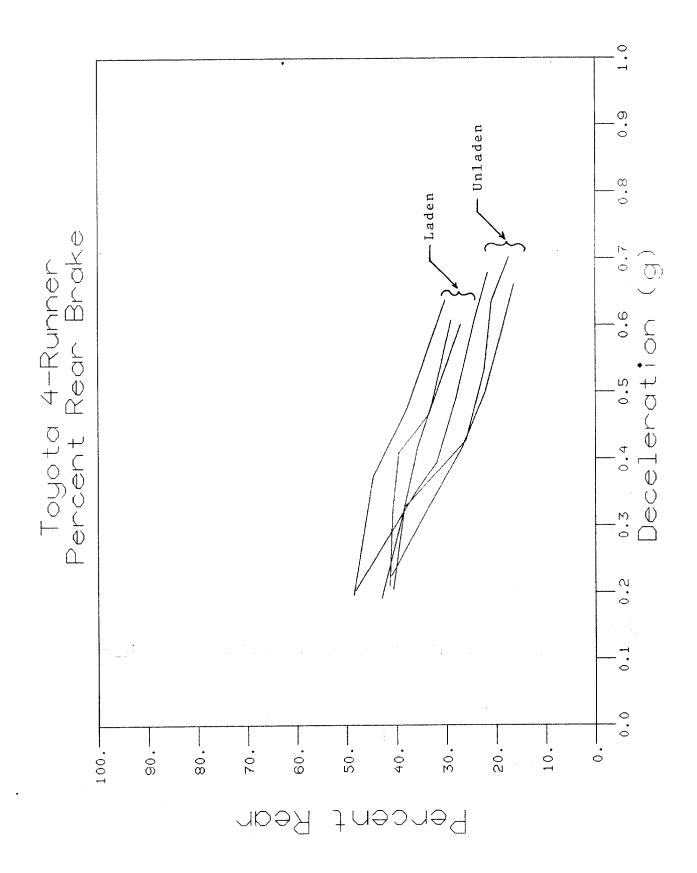


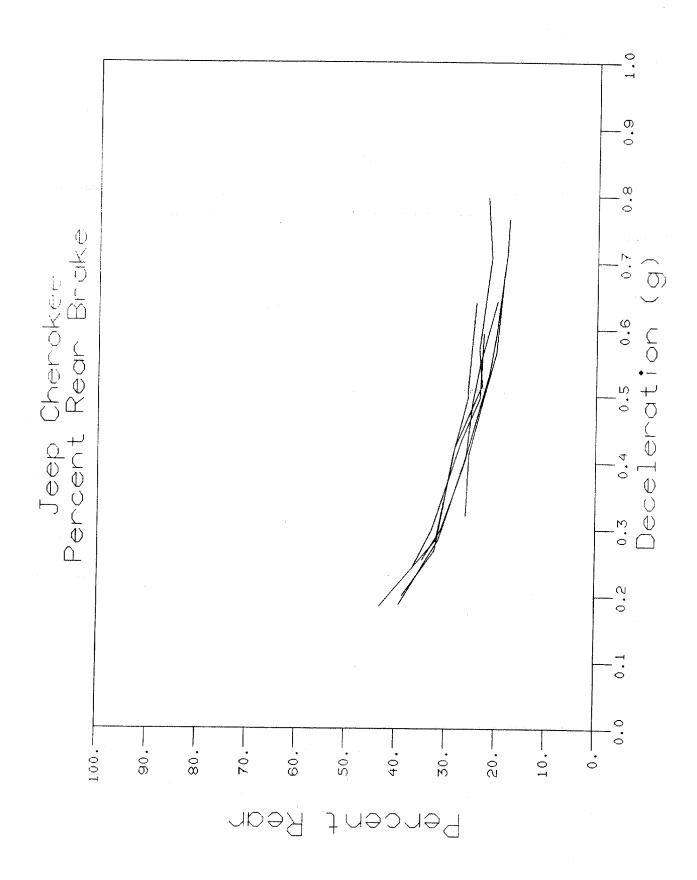












en e		way a	in the service	artika esti ar			4. Although Silver	•
;								
					, 4 3 5			
•						•		
*							•	
			•		•			
•								
1.0				*				
•								
				•				
					•			
a*			× .					
							•	(3.
								and.
		•	٠.					
		e de la companya de La companya de la co	~					A 18
- <b>1</b>								
		•			$\varphi = d = \chi_{-1} =$			
			,				*	
						*.		
				••				
			16	n de la companya de l				
					1.4			
				y =1.				
					7 :			
					**			
								Č.
		~						* * * * * * * * * * * * * * * * * * *
								*
. *				,				 <b>3</b> 5
		•						
		•		e e de la companya de	· · · · · · · · · · · · · · · · · · ·	No.		
				44.				4 <b>4.</b> J.C
			200			•		
*						•		
			100					
			<b>3</b>	and the second				
				and the second				
			•				•	
	`		*					
			. ,					
					÷			
	-	•		* 1	•			
						•		
						•		
				. *	***			
							the state of the same	
					ta Nacional			
	-*							